

## **INFORMATION TO USERS**

**This manuscript has been reproduced from the microfilm master. UMI films the text directly from the original or copy submitted. Thus, some thesis and dissertation copies are in typewriter face, while others may be from any type of computer printer.**

**The quality of this reproduction is dependent upon the quality of the copy submitted. Broken or indistinct print, colored or poor quality illustrations and photographs, print bleedthrough, substandard margins, and improper alignment can adversely affect reproduction.**

**In the unlikely event that the author did not send UMI a complete manuscript and there are missing pages, these will be noted. Also, if unauthorized copyright material had to be removed, a note will indicate the deletion.**

**Oversize materials (e.g., maps, drawings, charts) are reproduced by sectioning the original, beginning at the upper left-hand corner and continuing from left to right in equal sections with small overlaps.**

**Photographs included in the original manuscript have been reproduced xerographically in this copy. Higher quality 6" x 9" black and white photographic prints are available for any photographs or illustrations appearing in this copy for an additional charge. Contact UMI directly to order.**

**ProQuest Information and Learning  
300 North Zeeb Road, Ann Arbor, MI 48106-1346 USA  
800-521-0600**

**UMI<sup>®</sup>**



**Evaluation of Roaming and Download Times in  
Universal Cellular /Wireless LAN Systems**

YingRao Wei

A Thesis  
in  
The Department  
of  
**Electrical and Computer Engineering**

Presented in Partial Fulfillment of the Requirements  
for the Degree of Master of Applied Science at  
**Concordia University**  
Montreal, Quebec, Canada

July 2001  
© YingRao Wei, 2001



**National Library  
of Canada**

**Acquisitions and  
Bibliographic Services**

**395 Wellington Street  
Ottawa ON K1A 0N4  
Canada**

**Bibliothèque nationale  
du Canada**

**Acquisitions et  
services bibliographiques**

**395, rue Wellington  
Ottawa ON K1A 0N4  
Canada**

*Your file Votre référence*

*Our file Notre référence*

**The author has granted a non-exclusive licence allowing the National Library of Canada to reproduce, loan, distribute or sell copies of this thesis in microform, paper or electronic formats.**

**The author retains ownership of the copyright in this thesis. Neither the thesis nor substantial extracts from it may be printed or otherwise reproduced without the author's permission.**

**L'auteur a accordé une licence non exclusive permettant à la Bibliothèque nationale du Canada de reproduire, prêter, distribuer ou vendre des copies de cette thèse sous la forme de microfiche/film, de reproduction sur papier ou sur format électronique.**

**L'auteur conserve la propriété du droit d'auteur qui protège cette thèse. Ni la thèse ni des extraits substantiels de celle-ci ne doivent être imprimés ou autrement reproduits sans son autorisation.**

0-612-64065-5

**Canada**

# **ABSTRACT**

## **Evaluation of Roaming and Download Times in Universal Cellular /Wireless LAN Systems**

**YingRao Wei**

The growing demand for wireless access has led to the emergence of all kinds of standards for wireless communication, each of which has its own special requirements. The future transceiver equipment of mobile station (MS) should support the operation of these systems from the viewpoint of system compatibility. In this case, multi-mode, multi-band operation is required for user's convenience. Moreover, realization of small size and low power consumption handy terminals is necessary. These are the trends that have led to continued discussion about software radios (also called software defined radio, SDR). SDR is emerging as a potential programmatic solution: a software implementation of the user terminal which able to reconfigure such terminal to suit the changing radio environment as for example in the case of global roaming. There are a great number of international organizations and forums for software defined radios around the world.

In this thesis, a generalized state diagram of a SDR reconfigurable, multi-mode mobile station that could roam/handoff between different wireless systems is developed. A detailed description of the power-up, roaming and download operation for this reconfigurable MS is presented. Furthermore, its roaming connection establishment acquisition time in different scenarios is evaluated. Specifically, the relationships between the roaming acquisition time and *system resource blocking probability*, *mobile station resource blocking probability*, *packet successful transmission probability over*

*wireless channel and signaling bit rate over the universal base station channel* in different cases and design scenarios are analyzed. Such evaluations are important for prior design of SDR mobile terminal and universal base station in global roaming situations.

**Dedicated to My Parents, My Brother and My Husband  
for Their Love and Encouragement**

## **Acknowledgements**

At the outset I would like to express my most sincere gratitude to my thesis supervisor, Dr. A. K. Elhakeem, for his guidance, support, patience and encouragement during the entire course of this thesis. This work was born from his idea and his intellectual properties, also he provided constructive suggestions to enable me to demonstrate this new technique by mathematical analysis. I am deeply touched by his scientific attitude toward knowledge and rich experiences in the area of telecommunication. Moreover, Dr. Elhakeem does not only enlighten me on the love of research work, but also kindly conduct me in society. Here I would like to express my greatest admiration to my supervisor again!

Also, I would like to thank the great group of friends who gave me help and inspired me during the course of this work. Finally, I would like to express my thanks to my husband, my parents, and my brother. They are always standing besides me and helping with love and encouragement during the entire period of the study of my Masters.



# Table of Contents

List of Figures .....	ix
List of Tables .....	xii
<b>1. Introduction</b>	<b>1</b>
1.1 Objective of the Thesis .....	1
1.2 Organization of the Thesis .....	2
<b>2. Overview of cellular system</b>	<b>4</b>
2.1 Introduction to Software Radio.....	5
2.1.1 Definition of Software Radio .....	5
2.1.2 Architecture and Benefits of Software Radio .....	6
2.2 Introduction to Mobile Communication System.....	8
2.2.1 Different Types of Mobile Communication System .....	8
2.2.2 Cellular Mobile Communication System Architecture.....	10
2.2.3 Power-up Registration, Connection Establishment, and Handoff Process.....	11
<b>3. Reconfigurable Multi-mode Mobile Station for Wireless Communication Systems</b>	<b>33</b>
3.1 Profile of the Re-configurable Multi-mode Mobile Station.....	33
3.1.1 Over-the-Air Re-configuration.....	34
3.1.1.1 Configuration of the Universal Base Station.....	34
3.1.1.2 Configuration of the Mobile Station.....	35
3.1.2 Description of the Power-up Registration, Roaming Process.....	45
3.2 Connection Establishment of the Roaming Mobile Station .....	51
3.2.1 Description.....	51
3.2.2 Calculation of the Transition Probability for the State Diagram.....	61

<b>4. Estimation of the Roaming Acquisition Time</b>	<b>65</b>
4.1 Transition Function and Roaming Connection Establishment Acquisition Time.....	65
4.1.1 Roaming Connection Establishment Acquisition Time.....	65
4.1.2 Transition Function.....	65
4.2 Five Scenarios.....	73
4.2.1 Scenario Number 1.....	74
4.2.2 Scenario Number 6.....	77
4.2.3 Scenario Number 19.....	81
4.2.4 Scenario Number 20.....	85
4.2.5 Scenario Number 26.....	89
<b>5. Test Results</b>	<b>95</b>
5.1 Possible Cases .....	95
5.2 Roaming Acquisition Time Versus Packet Successful Transition Probability.....	104
5.3 Roaming Acquisition Time Versus System Resource Blocking Probability.....	111
5.4 Roaming Acquisition Time Versus Mobile Station Resource Blocking Probability....	114
5.5 Roaming Acquisition Time Versus Universal Channel Bit Rate.....	117
5.6 Other Tests on Roaming Acquisition Time for Scenario Number 1.....	120
<b>6. Conclusion and Contribution</b>	<b>125</b>
<b>7. Suggestion for Future Research</b>	<b>128</b>
<b>Appendix I: Bibliography</b>	<b>129</b>
<b>Appendix II: Acronyms</b>	<b>131</b>

## List of Figures

2.1 The Software Radio Architecture .....	7
2.2 Cellular Mobile Communication System .....	10
2.3 A Common Diagram of Call Flow .....	14
2.4 Mobile Station Termination Call Establishment .....	15-16
2.5 Mobile Station Origination Call Establishment .....	17-19
2.6 Five Possible Handoff Scenarios in GSM .....	20
2.7 The Synchronized intra-BTS Handoff .....	21
2.8 The Non-synchronized intra-BSC Handoff .....	22
2.9 The intra-MSR Handoff .....	24
2.10 The inter-MSR Handoff .....	25
2.11 Scenario for Subsequent Handoff back to the Original MSR .....	26
2.12 Scenario for Subsequent Handoff to a Third MSR .....	27
2.13 The Call Flow of a Soft Handoff .....	30
3.1 Over-the-Air Reconfiguration .....	35
3.2 Construction Code Tree of the Function Indication Bits of the Mobile Station .....	37-38
3.3 The Generalized State Diagram of the Mobile Station .....	41
3.4 Flowchart of the MS Power-up or Roaming Procedure .....	46
3.5 Cellular System Software Download Path of the Mobile Station Connection Establishment ...	53
3.6 Same System Path of the Mobile Station Connection Establishment .....	57
3.7 Calculation of the Total Time in Each State .....	63

4.1(a) A Signal Flow Graph I .....	66
4.1(b) A Simplified Flow Graph II .....	68
4.2 State Diagram for Connection Control of a Re-configurable Mobile Station (Scenario 1).....	75
4.3 State Diagram for Connection Control of a Re-configurable Mobile Station (Scenario 6).....	77
4.4 State Diagram for Connection Control of a Re-configurable Mobile Station (Scenario 19) .....	81
4.5 State Diagram for Connection Control of a Re-configurable Mobile Station (Scenario 20).....	85
4.6 State Diagram for Connection Control of a Re-configurable Mobile Station (Scenario 26).....	90
5.1(a), (b), (c) Acquisition time versus Packet Successful Transmission Probability (Scenario 1).....	104
5.2(a), (b), (c) Acquisition time versus Packet Successful Transmission Probability (Scenario 6).....	105
5.3(a), (b), (c) Acquisition time versus Packet Successful Transmission Probability (Scenario 19)....	106
5.4(a), (b), (c) Acquisition time versus Packet Successful Transmission Probability (Scenario 20). ..	107
5.5(a), (b), (c) Acquisition time versus Packet Successful Transmission Probability (Scenario 26)....	108
5.6 Acquisition time versus Packet Successful Transmission Probability (Comparison) .....	109
5.7(a), (b), (c) Acquisition time versus System Resource Blocking Probability (Scenario 1).....	111
5.8 Acquisition time versus System Resource Blocking Probability (Scenario 6).....	112
5.9 Acquisition time versus System Resource Blocking Probability (Scenario 19).....	112
5.10 Acquisition time versus System Resource Blocking Probability (Scenario 20).....	112
5.11 Acquisition time versus System Resource Blocking Probability (Scenario 26).....	113
5.12 Acquisition time versus System Resource Blocking Probability (Comparison of 5 scenarios)....	113
5.13 Acquisition time versus MS Resource Blocking Probability (Scenario 1).....	114
5.14 Acquisition time versus MS Resource Blocking Probability (Scenario 6).....	115
5.15 Acquisition time versus MS Resource Blocking Probability (Scenario 19).....	115
5.16 Acquisition time versus MS Resource Blocking Probability (Scenario 20).....	115
5.17 Acquisition time versus MS Resource Blocking Probability (Scenario 26).....	116
5.18 Acquisition time versus MS Resource Blocking Probability (Comparison of 5 scenarios)....	116

5.19 Acquisition time versus Universal Channel Bit Rate (Scenario 1).....	117
5.20 Acquisition time versus Universal Channel Bit Rate (Scenario 6).....	118
5.21 Acquisition time versus Universal Channel Bit Rate (Scenario 19).....	118
5.22 Acquisition time versus Universal Channel Bit Rate (Scenario 20).....	118
5.23 Acquisition time versus Universal Channel Bit Rate (Scenario 26).....	119
5.24 Acquisition time versus Universal Channel Bit Rate (Comparison of 5 scenarios).....	119
5.25 Acquisition time versus Packet Successful Transmission Probability (Case 2, Scenario 1)....	120
5.26 Acquisition time versus Packet Successful Transmission Probability (Case 3, Scenario 1)....	121
5.27 Acquisition time versus Packet Successful Transmission Probability (Case 4, Scenario 1)....	121
5.28 Acquisition time versus Packet Successful Transmission Probability (Case 5, Scenario 1)....	122
5.29 Acquisition time versus Packet Successful Transmission Probability (Case 6, Scenario 1)....	122
5.30 (a) Roaming Acquisition time from other systems to CDMA (Scenario 1).....	123
5.30 (b) Roaming Acquisition time from other systems to GSM (Scenario 1).....	123
5.30 (c) Roaming Acquisition time from other systems to wireless LAN (Scenario 1).....	124

## List of Tables

3.1 Seven Function Indication Bits for the Mobile Station .....	36
3.2 The Possible States of the Mobile Station .....	41
3.3 Mobile Station Transition Operation Table .....	52
4.1 36 Possible Designed Scenarios .....	73
4.2 The transitions in the state diagram (Scenario 1) .....	75
4.3 The transitions in the state diagram (Scenario 6) .....	78
4.4 The transitions in the state diagram (Scenario 19) .....	82
4.5 The transitions in the state diagram (Scenario 20) .....	86
4.6 The transitions in the state diagram (Scenario 26) .....	90
5.1(a) The required number of kilo-bits and packets in each state for the transition from GSM to other wireless systems .....	96
5.1(b) The minimum time spent in each state for the transition from GSM to other wireless systems ( $R_b=100\text{Kb/s}$ ) .....	97
5.1(c) The minimum time spent in each state for the transition from GSM to other wireless systems ( $R_b=50\text{Kb/s}$ ) .....	97
5.1(d) The minimum time spent in each state for the transition from GSM to other wireless systems ( $R_b=200\text{Kb/s}$ ) .....	97
5.2(a) The required number of kilo-bits and packets in each state for the transition from TDMA IS-54 to other wireless systems .....	98
5.2(b) The minimum time spent in each state for the transition from TDMA IS-54 to other wireless systems ( $R_b=100\text{Kb/s}$ ) .....	98

5.3(a) The required number of kilo-bits and packets in each state for the transition from CDMA system to other wireless systems .....	99
5.3(b) The minimum time spent in each state for the transition from CDMA system to other wireless systems ( $R_b=100\text{Kb/s}$ ) .....	99
5.4(a) The required number of kilo-bits and packets in each state for the transition from DECT to other wireless systems .....	100
5.4(b) The minimum time spent in each state for the transition from DECT to other wireless systems ( $R_b=100\text{Kb/s}$ ) .....	100
5.5(a) The required number of kilo-bits and packets in each state for the transition from AMPS/CDPD to other wireless systems .....	101
5.5(b) The minimum time spent in each state for the transition from AMPS/CDPD to other wireless systems ( $R_b=100\text{Kb/s}$ ) .....	101
5.6(a) The required number of kilo-bits and packets in each state for the transition from WLAN to other wireless systems .....	102
5.6(b) The minimum time spent in each state for the transition from WLAN to other wireless systems ( $R_b=100\text{Kb/s}$ ) .....	102

# Chapter 1 Introduction

## 1.1 Objective of The Thesis

The request for software radio is provoked by an expectant demand for multi-mode mobile terminals. Software radio technology will give the mobile station the ability of handling a wide range of wireless communication protocols by downloading software, switching from GSM to UMTS for example. A method of downloading software to a mobile terminal over the wireless link is adopted here. There are two main objectives for this thesis.

- To define for the re-configurable multi-mode mobile station, possible transitions from one kind of cellular standard to another, i.e. flexible roaming so as to accommodate several requirements of charging, quality of service (QoS), battery power level, network congestion etc. The mobile station should operate to handoff, not only from cell to cell, but also from one network standard to another, depending on the user satisfaction as above.
- To evaluate the average roaming, software download, handoff times in areas defined as having a mixture of universal cellular base stations, universal wireless LAN base stations, and classical base stations having only one cellular standard. The evaluation of the above roaming times also include times for sensing the universal pilot channel, classic base station pilot channel, association, and connection establishment signalling.

*Universal base station* means a base station that has the necessary software code for all standard systems such as GSM, CDMA IS-95, DECT, UMTS, etc. It will download such software code to a roaming mobile station upon request. The downloaded software will configure the modulation, access, and network functionalities of the reconfigurable and transparent mobile



station. *Classical base station* means a standard base station that provides fixed single mode system access to roaming users.

## **1.2 Organization of The Thesis**

The remainder of the thesis is organized as follows:

**Chapter 2** provides an introduction to software radio and mobile communication system. For software radio, we mainly present its definition, architecture and benefits. For the understanding of wireless communication system, we firstly show several types of mobile radio systems and the architecture of a cellular mobile communication system. Next, we present a detailed description of the mobile station operation in a mobile communication system. GSM is taken as an example for discussing power-up registration, mobile station connection establishment, and handoff operation. CDMA system IS-95 is also taken as an example when discussing soft handoff, semi-soft handoff operation.

Chapter 3 and Chapter 4 are the main part of the thesis. In **Chapter 3**, we present a reconfigurable, multi-mode mobile station for wireless communication systems. At first, we propose the configuration for the universal base station and reconfigurable mobile station. Then, based on these proposals, we present a generalized state diagram of this mobile station and a brief description of its power-up registration and roaming connection establishment process. Furthermore, the transition probabilities and the total time spent in each state shown in the state diagram are calculated.

In **Chapter 4**, we focus on analyzing the transition function of the generalized state diagram in order to find the roaming connection establishment acquisition time. Because of the complexity of finding a general form of the transition function for the generalized state diagram,

we choose five of the possible design scenarios for analysis. The transition function and roaming connection establishment acquisition time of these five scenarios are presented in Section 4.2.

In **Chapter 5**, we list six possible test cases and construct their input tables for the calculation of roaming connection establishment acquisition time in different design scenarios. But since the evaluation methods in these test cases are similar, we only choose case 1 for detailed test processing in five designed scenarios and choose scenario No.1 for detailed test processing in the six possible cases. The tests we performed are mainly in the analysis the relationship between the roaming acquisition time and *packet successful transmission probability over wireless channel  $P_i$*  (Section 5.2), *system resource blocking probability  $P_s$*  (Section 5.3), and *mobile station resource blocking probability  $P_m$*  (Section 5.4), *signalling bit rate over the universal base station channel  $R_b$*  (Section 5.5).

**Chapter 6** summarizes the result and contribution of this thesis.

**Chapter 7** provides some suggestions for future research.

**Appendix I** presents the bibliographies that we have referred to.

**Appendix II** presents some frequently used acronyms in thesis.

## **Chapter 2 Overview of Cellular Systems**

**During the past two decades, traditional cordless system, cellular mobile systems, mobile data and mobile satellite systems have grown at a tremendous speed. Also, some new wireless communication concepts, such as wireless local area networks (WLAN) have appeared along the way. More and more people use mobile phones, wireless data services are available in many areas, and wireless local area networks (WLAN) are used in many places since 1997.**

**For a better understanding of the motivation of this thesis, a short history of cellular mobile communication is presented here. First generation wireless cellular systems began to appear in the 1980's. These systems, like Advanced Mobile Phone Service (AMPS) and Total Access Communication System (TACS), were all analog and were based on frequency division multiple access (FDMA). They were only meant for voice communications. However, the demand for capacity increased very quickly. Digital cellular systems (2G systems), such as GSM and PCS came into the picture, which used time division multiple access (TDMA). Soon also the code division multiple access (CDMA) based system IS-95 evolved since it was recognized as a potential to increase the capacity further. All these second generation systems were still mainly for voice communication but they already provided some data services but at rate far less than 64 Kb/s.**

**A great number of these kinds of wireless networks have come into existence over the years and these systems have utilized many kinds of software and hardware technologies. Today again capacity has become an issue. When the 3G systems such as universal mobile telecommunication system (UMTS) are taken into use, there are still a great many 2G systems working. These 2G and 3G systems differ from each other in terms of modulation, channel coding, multiple access,**

etc. which will eventually lead to need for different kind of multi-band, multi-mode terminals. This will in return result in many different product platforms that could be programmed to different standards.

In addition, the industrial competition between Asia, Europe, and America promises a very difficult path toward the definition of a unique standard for future mobile systems, although market analysis underline the trading benefits of a common worldwide standard. It is therefore in this field that the *software radio* concept is emerging as a potential programmatic solution: a software implementation of the mobile terminal which able to dynamically reconfigure such terminal to suit the changing radio environment as for example in the case of global roaming.

## **2.1 Introduction to Software Radio**

As a starting point, mobile terminals were designed to support single mode operation. For the user side, it is inefficient to carry more than one communication terminals. Therefore, it is distinctly predictable that multi-mode mobile terminals will play an important role within the next generation of mobile communications. The new concept of software radio has been proposed to accommodate multi-modes on a single mobile terminal.

### **2.1.1 Definition of Software Radio**

*Software radio (also called software defined radio, SDR)* is thought to build flexible radio systems, multi-service, multi-standard, multi-band, reconfigurable and re-programmable by software. Some definitions often found in the literatures are [12]:

- Flexible TX/RX (transceiver unit) architecture, controlled and programmable by software.
- Signal processing able to replace, as much as possible, radio functionalities.
- “Air interface download ability”: radio equipment dynamically reconfigured by downloadable software at every level of the protocol stack.

- Software realization of terminals “multiple mode/standard”.
- Transceiver where the following can be defined by software: a) Frequency band and radio channel bandwidth. b) Modulation and coding scheme. c) Radio resource and mobility management protocol. d) User applications.

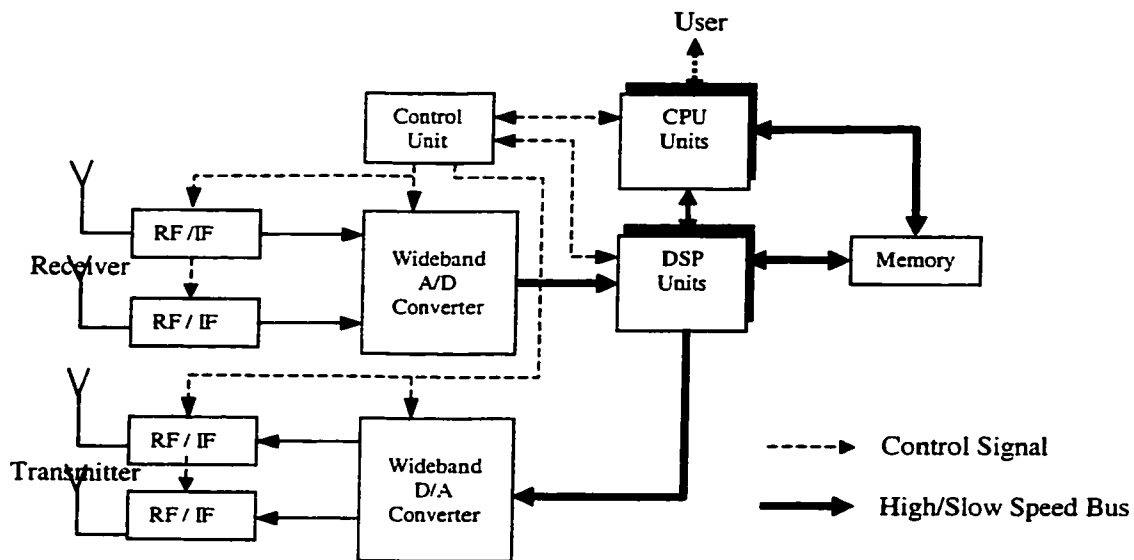
### ***2.1.2 Architecture and Benefits of Software Radio***

With software radio (SDR), one would implement a common hardware platform and accommodate the different wireless communication system standards and technologies via software modules and firmware. If the hardware must be adapted to a new standard, then a slight reprogramming of the processor should be all that is needed. The reconfigurability of a SDR mobile station means digital signal processing (DSP) engine reprogrammability, which in real time, implement radio interface and upper layer protocols. It is important to note that by digital signal processing (DSP) is really intended the concept of digital signal processing, and therefore not only DSP chipsets in strict sense, but also Field Programmable Gate Arrays (FPGA) and general-purpose processors [12].

Ideally the software radio (SDR) would consist of a DSP unit, which is connected directly to antenna. The trend in SDR design is to place the Analogue-to-Digital (A/D) converter as close as possible to the antenna. This will permit a wider implementation of software, bringing the benefit of reconfiguration capability. However, today’s technology has not yet reached the point at which this would be realizable, and therefore it does not utilize such architecture. Digitization at the IF is more likely to happen in the near future rather than the RF digitization. Software radio is now defined to be a piece of future radio equipment, which can be configured by software, to many different wireless systems. It provides real time operation and also, if needed, it can be used simultaneously in those systems. So a realizable software radio would consist of [15]:

- High quality analog wide band RF/IF stage.
- High performance wide band A/D and D/A converters.
- Digital signal processing unit consisting of general-purpose DSP processors, CPUs, configurable hardware and memory modules.

In the future an intelligent multi-band adaptive antenna system will also be included. The structure for the software radio is represented in Figure 2.1. [15]



**Figure 2.1** The Software Radio Architecture

We note that the interface between analog and digital part is shifted towards the antenna. This together with flexible software architectures makes it possible to achieve flexibility and plug-and-play type of use. All aspects relating to the air interface are implemented in programmable software or hardware and the mobile station can be reconfigured in real time over-the-air. The basic concept is based on the use of a simple hardware platform built using software radio to enable customers to modify the mobile terminal to work in different systems at different time and different area. The main difference compared to traditional mobile station is thus the total programmability.

Software radio can bring benefits not only to users but also to manufactures. For users, modifying the performance or functionality of the mobile terminal is achieved by downloading software. Downloading software modules, from user application layer to communication physical layer processing algorithms, will provide more flexibility to the terminal in terms of reconfiguration. For example, the software (SW) modules could be: speech codecs, modulation schemes, filters, interleaving method, or simply a set of parameters. Consequently, the mobile users will be able to adapt its personal communication device depending on his environment and preferences, so that the users take the advantage of worldwide mobility and coverage, reconfigurability and flexibility. Moreover, SDR technology increases hardware lifetime of both network and mobile station. To migrate to a new standard, reprogramming the hardware platform would be all that is needed.

For manufactures, the advantages would be the possibility to improve, correct the software during the operation, the possibility to concentrate R&D efforts on a reduced hardware platform set, applicable to many different standard, finally lead to lower costs.

This thesis mainly addresses the software download issues when the mobile station roams in different mobile communication systems, while SDR transceiver architecture, possible SW implementation, and network evolution issues are not considered in detail, these fundamental topics can be found in recent literature.

## **2.2 Introduction to Mobile Communication System**

### ***2.2.1 Different Types of Mobile Communication Systems***

During the last few decades, mobile communication has constantly grown in importance. In order to let the reader quickly know the current existing mobile communication systems, a brief description of the different types of mobile communication systems is presented here.

- **Public cellular mobile communication systems:** extend the telephone service of wire-line networks area-wide to mobile users. Example standards are Advanced Mobile Phone Service (AMPS), Total Access Communication System (TACS), Global System for Mobile Communication (GSM), Digital Cellular System at 1800 MHz (DCS-1800), Interim Standard 54 (TDMA IS-54), CDMA IS-95, Universal Mobile Telecommunication System (UMTS).
- **Wireless local area networks:** take into account the growing demand to avoid cabling of workstation computers. Example standards are HIPERLAN, IEEE 802.11 wireless LAN.
- **Cordless communication system:** in which the cable between the telephone terminal and the handset is replaced by a radio path that allows a radio connection of up to 300m/50m (outdoors/indoors). Example standards are CT2, Digital European Cordless Telephone (DECT).
- **Mobile satellite radio systems:** provide global communication and accessibility.
- **Trunked mobile radio systems:** are optimized for commercial application and provide services like closed user group.
- **Paging systems:** allow the direct paging of subscribers with mobile, pocket-sized receivers through the transmission of a signal or short message.

The need for ubiquitous personal communications impels the development of new networking techniques that accommodate mobile voice and data users who move throughout cities, or countries. The cellular mobile telephone system is responsible for providing coverage throughout a particular territory and capable of providing voice and data service to mobile users. Therefore, we describe the cellular mobile communication system for detail in the following, similar principle can be applied to other types of mobile communication systems.



### 2.2.2 Cellular Mobile Communication System Architecture

Figure 2.2 illustrates a typical cellular mobile communication system of the early 1990s. Each mobile station uses a separate, temporary radio channel to talk to the base station. The base station talks to many mobile stations at once, using one channel per mobile station. Channels may use a pair of frequencies for communication (Frequency Division Duplex FDD mode)—one frequency for transmitting from the base station (the forward link) and one frequency for the base station to receive calls from the users (the reverse link), or channels may use single frequency band (Time Division Duplex TDD mode) to transmit signals alternately in forward and reverse directions.

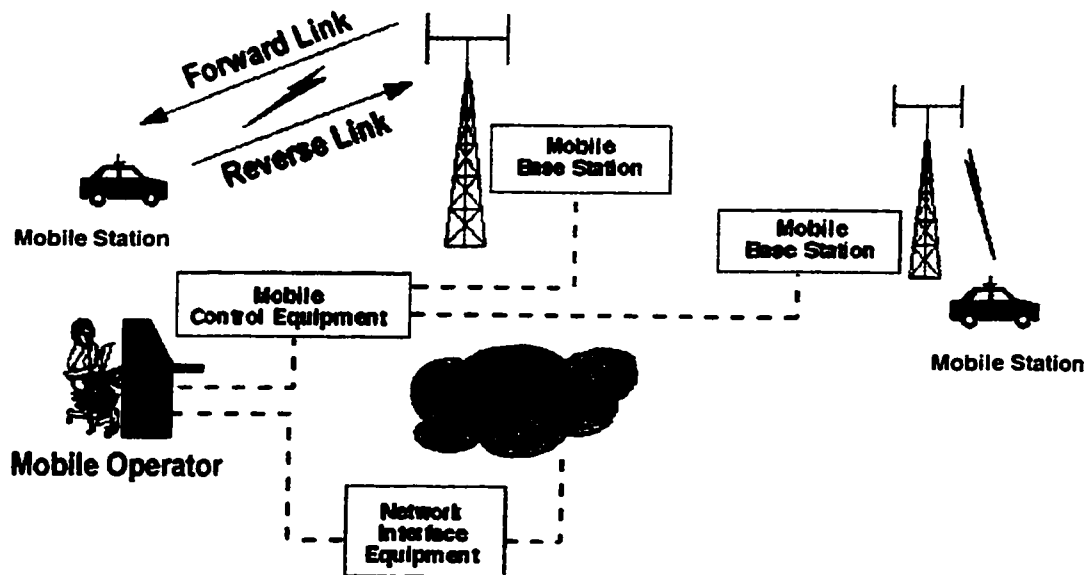


Figure 2.2 Cellular Mobile Communication System

The basic structure of mobile communication system includes radio services and telephone systems. Mobile radio service operates in a closed network and has no access to the public switched telephone system (PSTN), while mobile telephone service allows interconnection to the PSTN. The mobile communication system consists of the following four major components that work together to provide mobile service to subscribers.

- **Public switched telephone network (PSTN):** is made up of local networks, the exchange area networks, and the long-haul network that interconnect telephones and other communication devices on a worldwide basis.
- **Mobile telephone switching office (MTSO):** is the central office for mobile switching. It houses the mobile switching centre (MSC), field monitoring, and relay stations for switching calls from base stations to wire-line central offices (PSTN). In analog cellular networks, the MSC controls the system operation. The MSC controls calls, tracks billing information, and locates cellular subscribers.
- **Base station with antenna system (BS):** is used to refer to the physical location of radio equipment that provides coverage within a cell. A list of hardware located at a cell site includes power sources, interface equipment, radio frequency transmitters and receivers, and antenna systems.
- **Mobile station (MS):** consists of a control unit and a transceiver that transmits and receives radio transmissions to and from a base station.

### ***2.2.3 Power-up Registration, Connection Establishment, and Handoff/Roaming Process***

In order to understand the signalling operation of a mobile station in a mobile communication system, we will briefly describe the registration, connection establishment, and handoff/roaming process signalling. As there are many worldwide standards for mobile communication systems, it is unpredictable and unnecessary to present all of them here. In this section, we take GSM as the main example for description of the power-up registration, connection establishment and handoff process, not only because of market success, but also due to the system architecture that served many other systems as an early example. Specifically, some new handoff concepts such as soft

handoff, semi-handoff are introduced by taking CDMA system IS-95 as an example when discussing handoff process.

### **2.2.3.1 Power-up Registration**

The following power-up register process could be applied in the synchronization systems such as the first-generation and second-generation cellular mobile communication systems, e.g. AMPS, D-AMPS, GSM, CDMA IS-95, CDPD, etc.

Prior to establishing any communication links to other parties, the mobile station (MS) must first acquire synchronization with the mobile communication system. This begins after the MS is turned on in a Public Land Mobile Network (PLMN). The first step of the MS process is known as frequency synchronization. The frequency correction burst is unique and easily recognizable. For example, in GSM the frequency correction control channel (FCCH) burst is long sine wave that is offset by 67.7 KHz from the carrier frequency. The base station transmits all zeros for the frequency correction burst. The MS has to take out this offset before an estimate of the carrier frequency can be made.

After the frequency correction burst is detected, the MS will try to synchronize with the time synchronization burst (SCH). This time synchronization is generally carried out in two steps: coarse and fine. If synchronization does not occur, the process of frequency synchronization with the next highest power channel in the list may start.

Assuming that the mobile station is synchronized, it decodes the information on a broadcast/pilot channel. When these information are correctly decoded, the MS will follow one of the two paths:

- 1) If the broadcast control channel (BCCH) information includes the present BCCH channel number, then the MS will simply stay on the channel.

- 2) If the current channel is not included in the BCCH information list or the received signal strength level (BCCH level) is below the desired level, then the MS will continue searching for the next BCCH channel.

After the MS has successfully synchronized to the system timing, it must maintain the link and monitor the paging channel (PCH). The mobile station is also required to maintain information on the neighbouring BCCHs. The information, including sync information and the average measured RF levels of at least six adjacent cell channels, which is important for handoff process.

### **2.2.3.2 Connection Establishment**

**B**asic steps in the formation of a connection include connection request, paging procedure, identification process, authentication, ciphering, and call clearing international mobile subscriber identity (IMSI) attach and detach. There are two possible situations: Mobile station origination call establishment (MOC) and Mobile station termination call establishment (MTC). A common block diagram for MOC and MTC is shown in Figure 2.3. [1]

Next, we present the detailed signalling for a mobile station connection establishment in a GSM system. In MTC, the MS is called by a calling station which can be outside the GSM network or another mobile station. Figure 2.4 shows the detailed steps and required signalling in MTC. In MOC, the MS transmits a request for a new connection. Figure 2.5 shows the detailed steps and required signalling in MOC. Note that we focus on the signalling between the mobile station and the mobile network, while the signalling between the networks is not discussed here. Some acronyms used below were presented in appendix II.

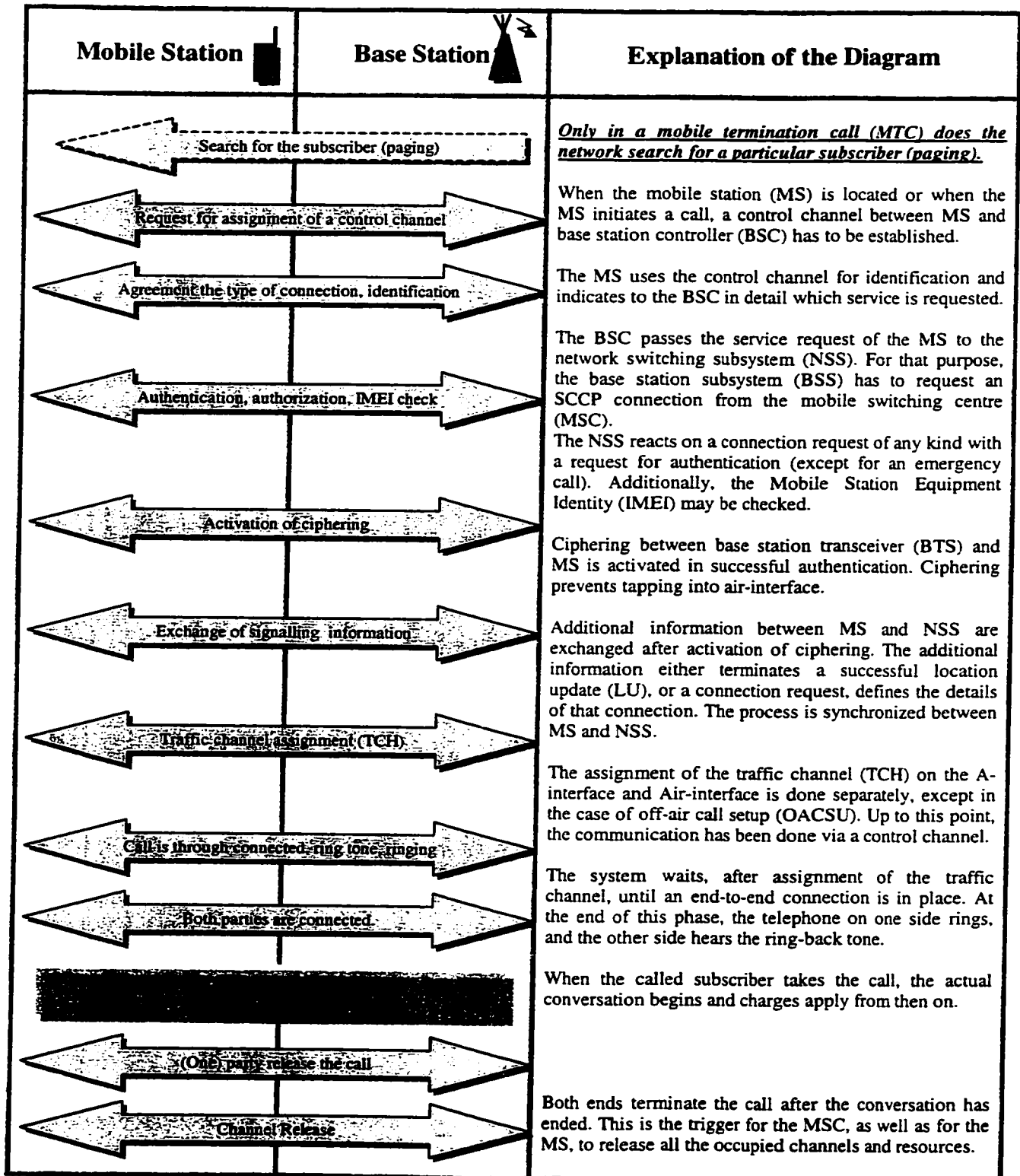


Figure 2.3 A Common Diagram of Call Flow

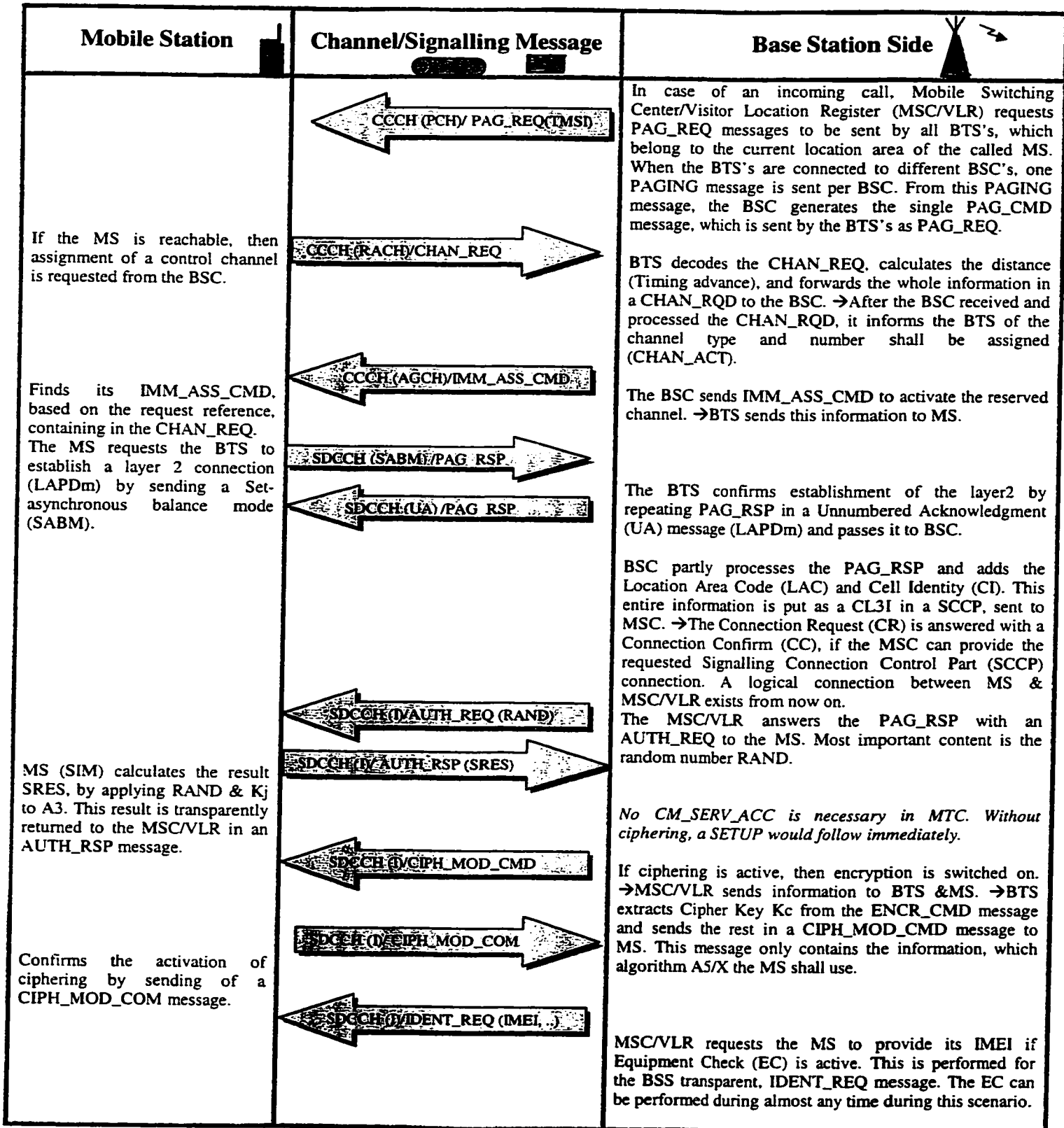


Figure 2.4 Mobile Station Termination Call Establishment (I)

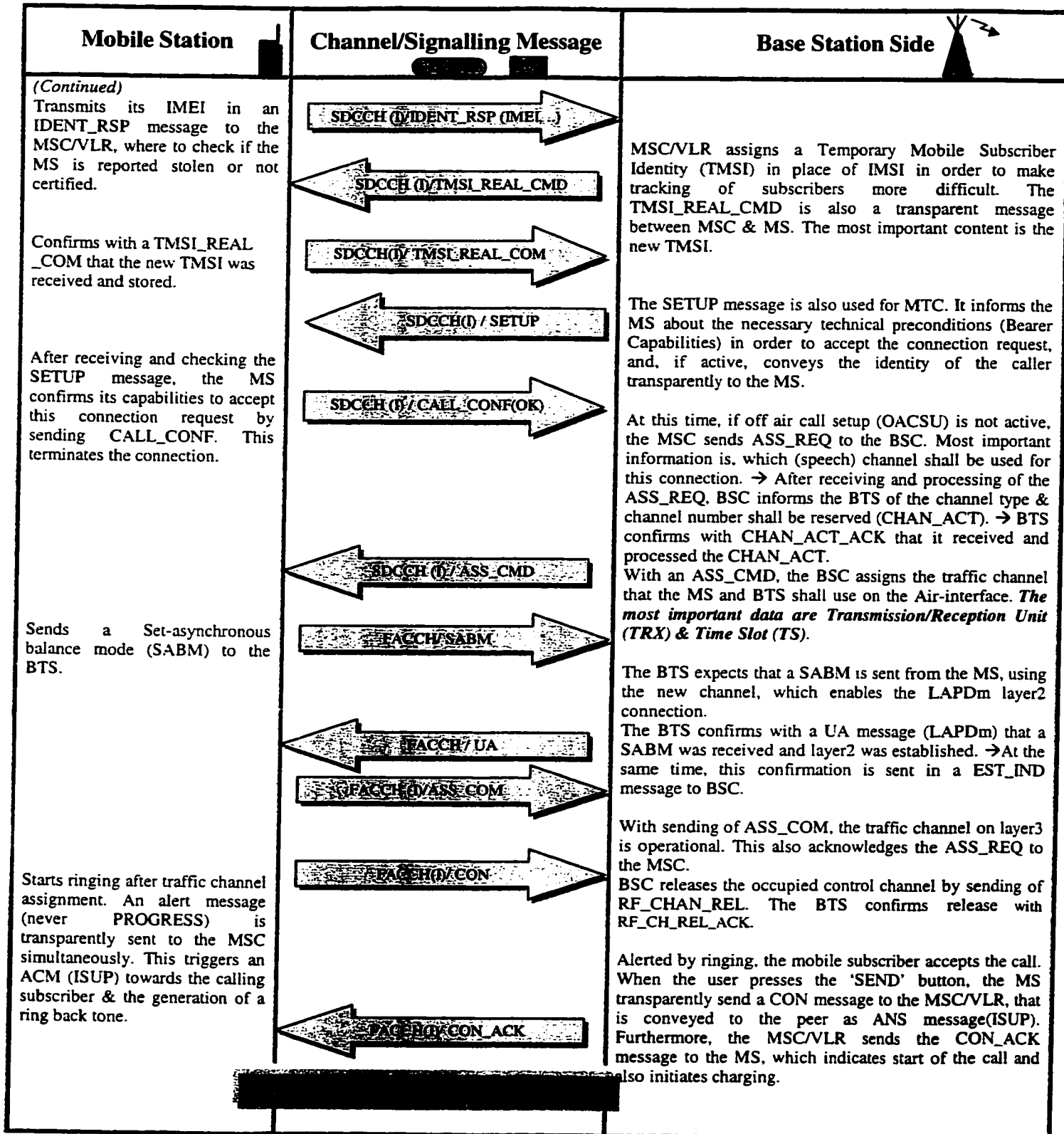


Figure 2.4 Mobile Station Termination Call Establishment (II)

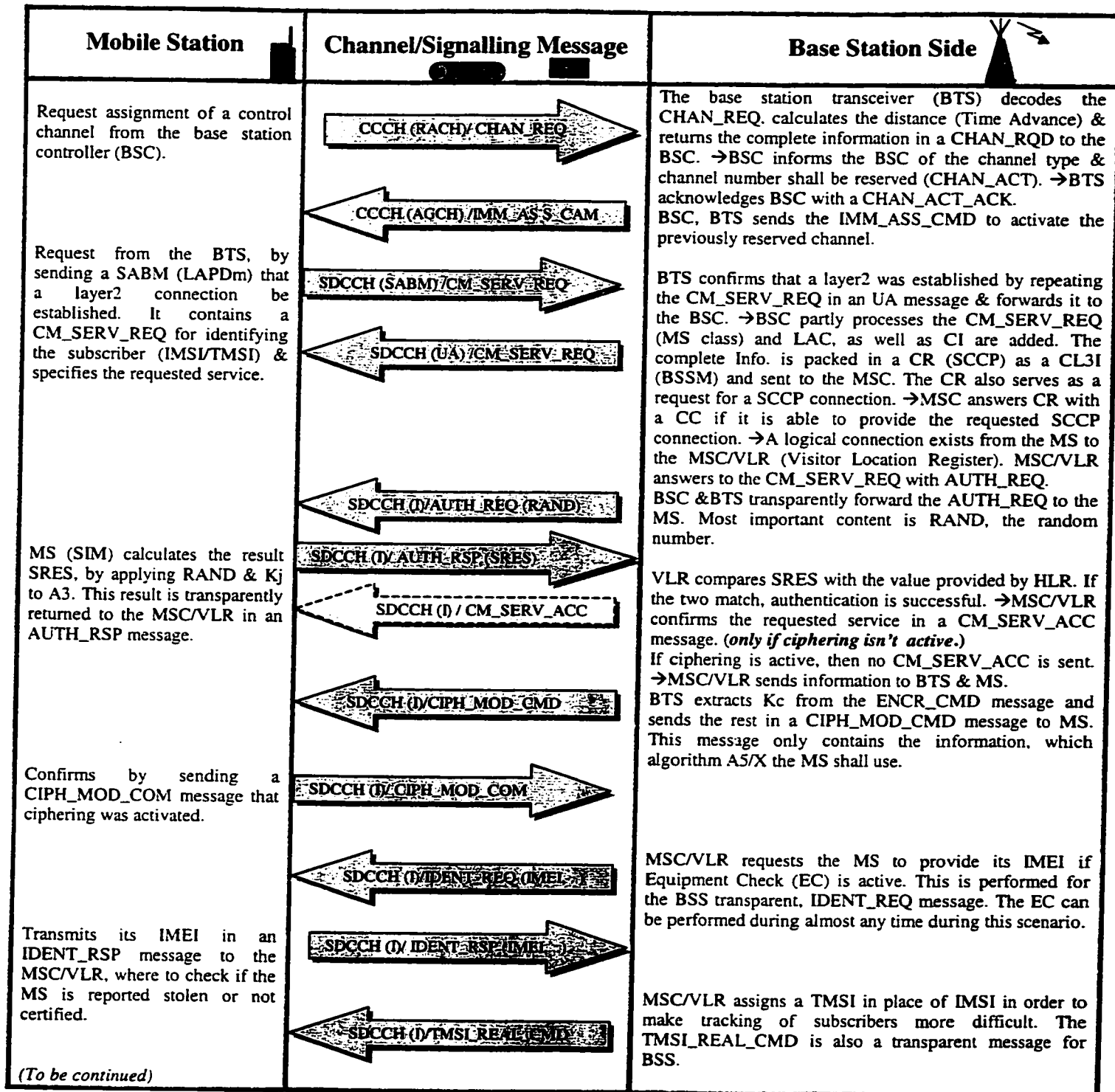


Figure 2.5 Mobile Station Origination Call Establishment (I)



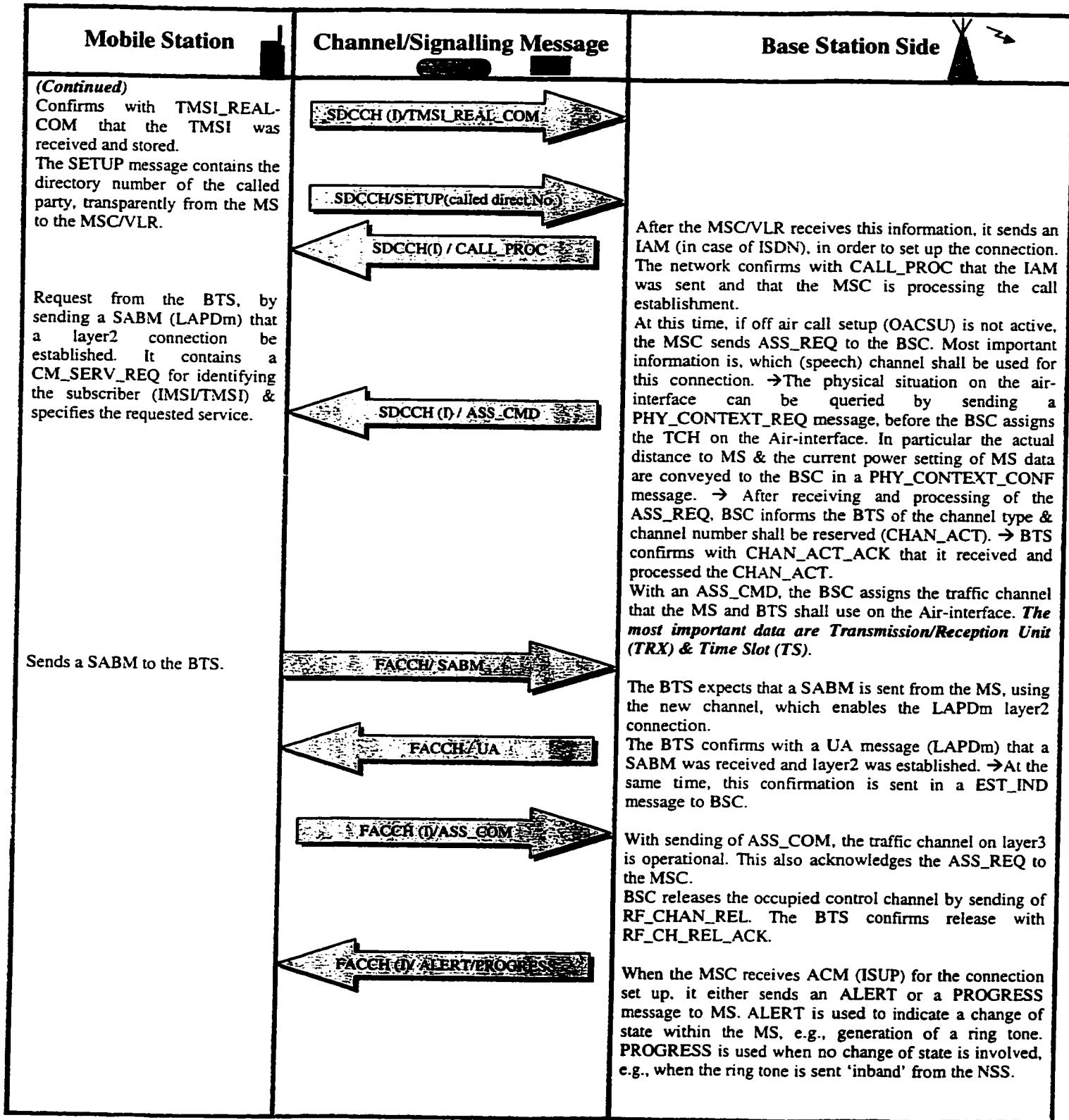


Figure 2.5 Mobile Station Origination Call Establishment (II)

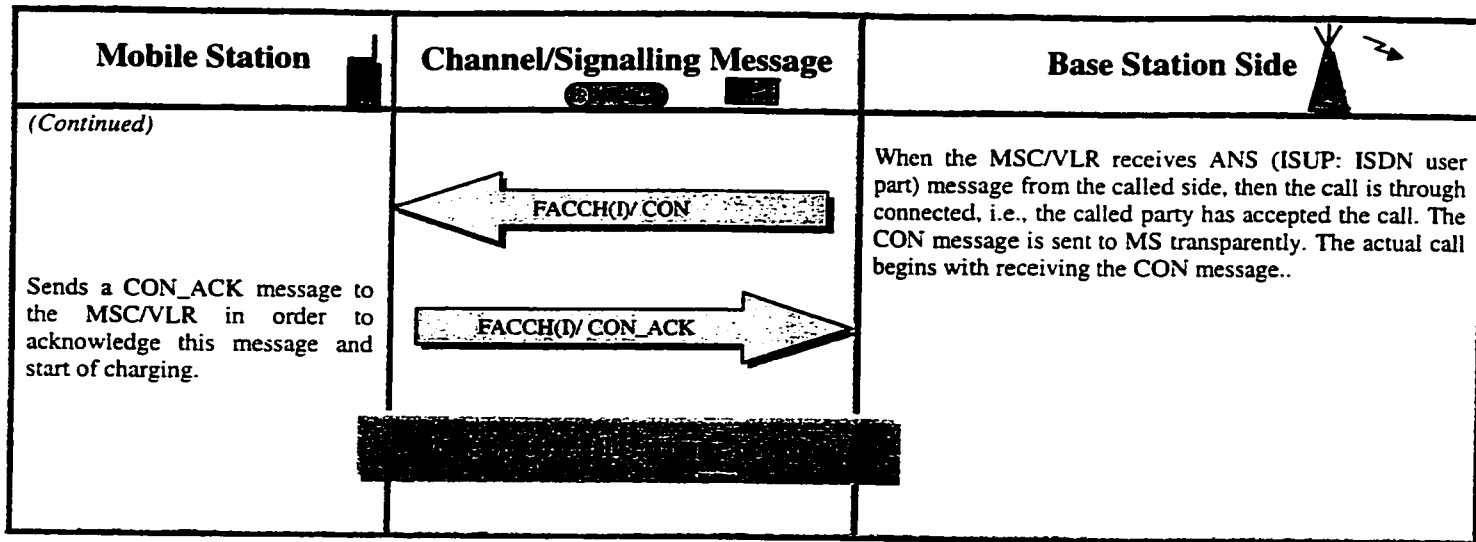


Figure 2.5 Mobile Station Origination Call Establishment (III)

### 2.2.3.3 Handoff /Handover Process

#### 2.2.3.3.1 The Concept of Handoff /Handover

An obstacle in the development of the cellular mobile network involved the problem created when a mobile subscriber traveled from one cell to another during a call. As adjacent areas do not use the same radio channels (control channel or traffic channel), a call must either be dropped or transferred from one radio channel to another when a user crosses the line between adjacent cells in the same system or different systems. Because dropping the call is unacceptable, the process of handoff/handover was created.

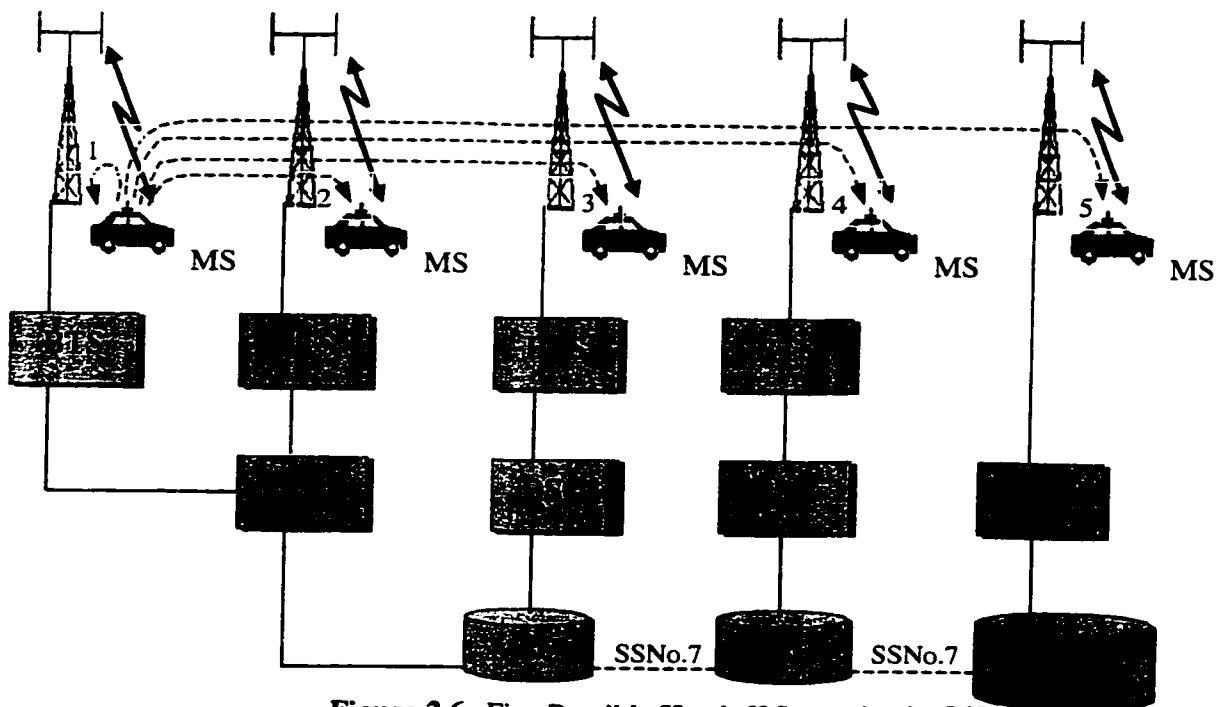
A *handoff* is defined as the change of the currently used radio channel to another radio channel during an existing and active connection between mobile station (MS) and base station (BS). Note that the GSM-specific term handover corresponds to the same concept as handoff; in Europe, handover is used, while in North America handoff is used. The smaller the cell size and the faster the movement of a mobile station through the cells (up to 250 Km/h for GSM), the

more handoffs/handovers of ongoing calls are required. In summary, there are two reasons for a handover.

- The mobile station moves out of the range of a base station transceiver (BTS) or a certain antenna of a BTS respectively. Thus, the received signal level becomes lower continuously until it falls underneath the minimal requirements for communication. Or the error rate may grow due to interference, the distance to the BTS may be too high etc. -- all these effects may diminish the quality of the radio link and make radio transmission impossible in the near future.
- The wire infrastructure such as mobile switching centre (MSC), base station centre (BSC) may decide that the traffic in one cell is too high and shift some MS to other cells with a lower load if possible. Thus, handover may be due to load balancing.

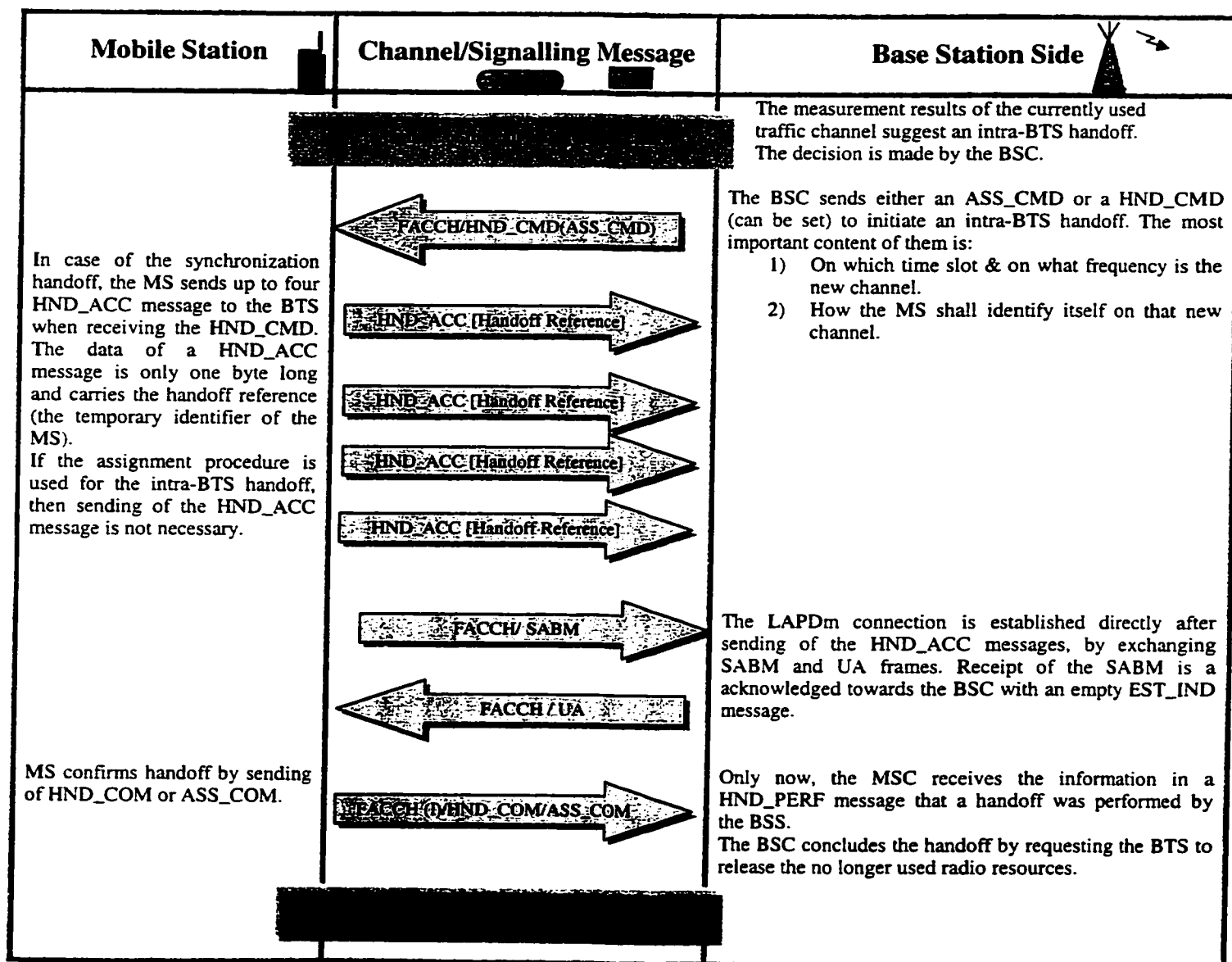
#### 2.2.3.3.2 Handoff/Handover Processing

Figure 2.6 shows five possible handover scenarios in GSM:



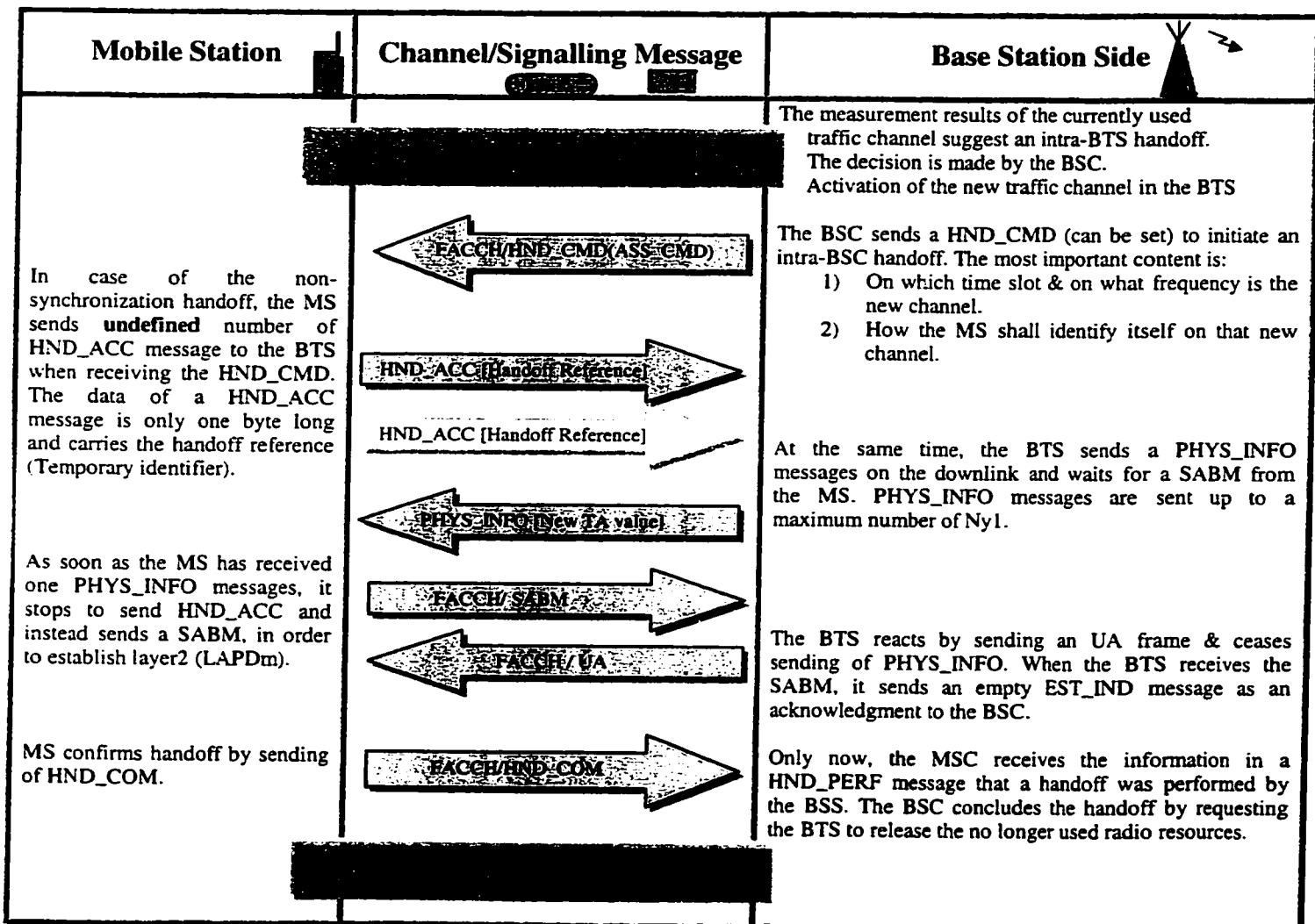
**Figure 2.6** Five Possible Handoff Scenarios in GSM

**1) Intra-BTS Handoff (Scenario 1):** Within a cell, narrow-band interference could make transition at a certain frequency impossible. The BSC could then decide to change the carrier frequency. The procedure usually is executed autonomously by the BSC, but the MSC may also be in charge. In the intra-BTS handoff, a new channel in the same BTS is assigned to the MS. Note that an intra-BTS handoff is always synchronized, since all TRXs of a BTS have to use the same clock. Figure 2.7 shows a synchronized handoff process during a connection [1].



**Figure 2.7** The Synchronized intra-BTS Handoff

**2) Intra-BSC Handoff (Scenario 2):** This is a typical handoff scenario. In the intra-BSC handoff, an MS changes the BTS but not the BSC. The intra-BSC handoff may be carried out autonomously by the BSC, without support from the MSC. It is an option by the network operator to decide that the MSC supervises the process. For intra-BSC handoff, depending on the circumstances, both synchronized and non-synchronized handoff are possible. A non-synchronized intra-BSC handoff process is shown in Figure 2.8. [1] The difference from the synchronized intra-BSC handoff is simply that the PHYS\_INFO messages from the BTS would not have to be sent.



**Figure 2.8** The Non-synchronized Intra-BSC Handoff

**3) Intra-MSC Handoff (Scenario 3):** In an intra-MSC handoff, the MS changes not only the BTS but also the BSC as well (external handoff). In contrast to the intra-BTS and intra-BSC handoff, the MSC mandatory is in charge for the execution of the intra-MSC handoff. However, the responsibility for the MSC does not include processing the measurements of the BTS or the MS or to conclude that a handoff is necessary. These functions always remain with the BSC. Figure 2.9 describes this scenario. [1]

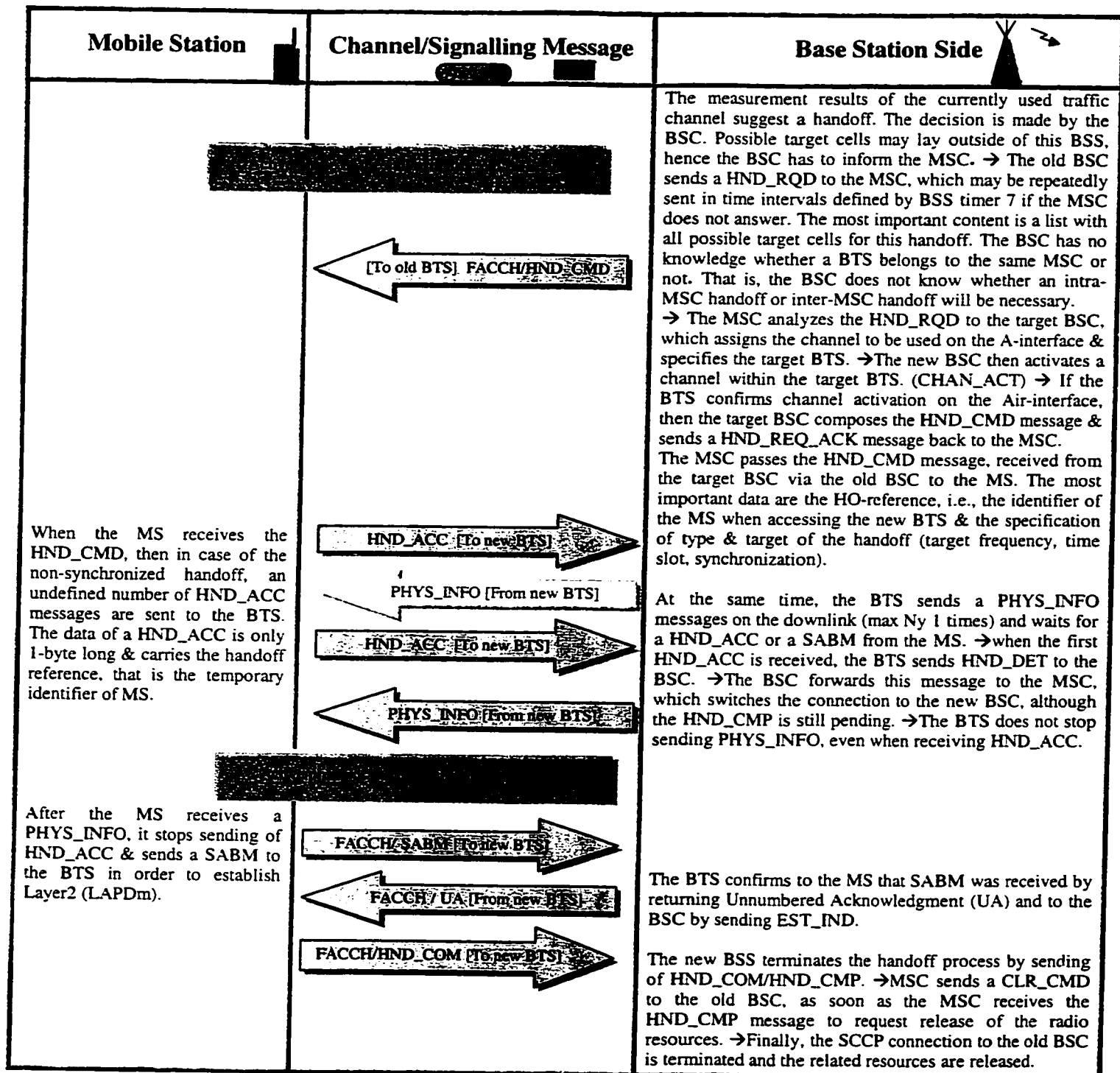
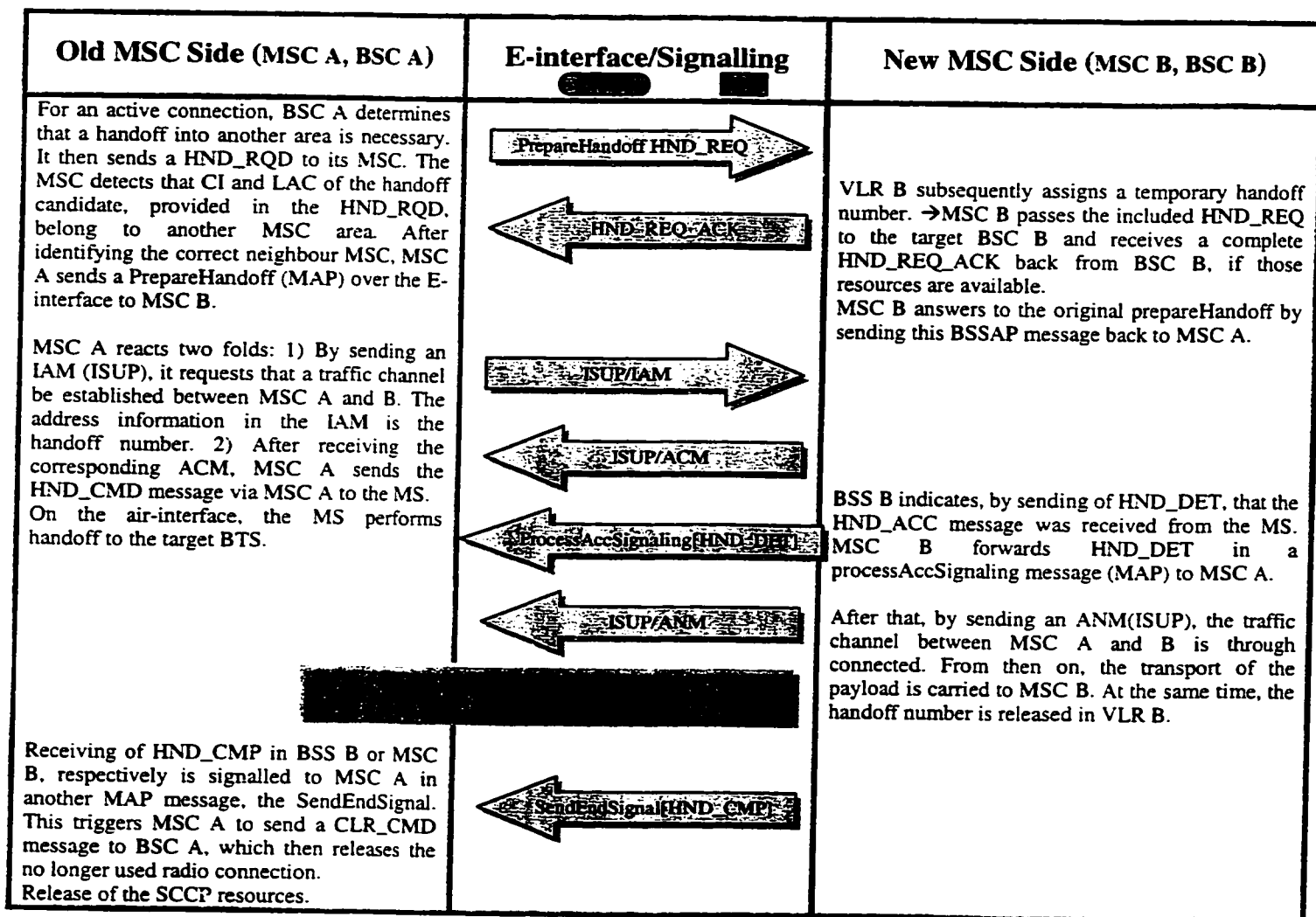


Figure 2.9 The intra-MSC Handoff

**4) Inter-MSA Handoff and Subsequent Handoff (Scenario 4):** *Inter-MSA handoff* is a handoff required between two cells belonging to different MSCs in the same type system. The control of the inter-MSA handoff stays with the old /original MSC. The original MSC always maintains the call control (CC) functionality, as the new MSC takes control over all radio resource (RR) task, which is internal to the MSC. These are in particular intra-MSA handoff-related tasks. Figure 2.10 shows this scenario. [1]



**Figure 2.10** The inter-MSA Handoff

*Subsequent handoff* is applied such a second inter-MSA handoff: One case is a handoff from the new MSC back to the original MSC (See Figure 2.11); another is a handoff from the new



MSC into a third MSC area (See Figure 2.12). Although the new MSC initiates a subsequent handoff, the original MSC still maintains overall control of the call, during and even after a subsequent handoff. Overall control means that, in any case, independent of whether the target of the handoff is the original MSC or a third MSC, the CC functionality always remains with the old MSC.

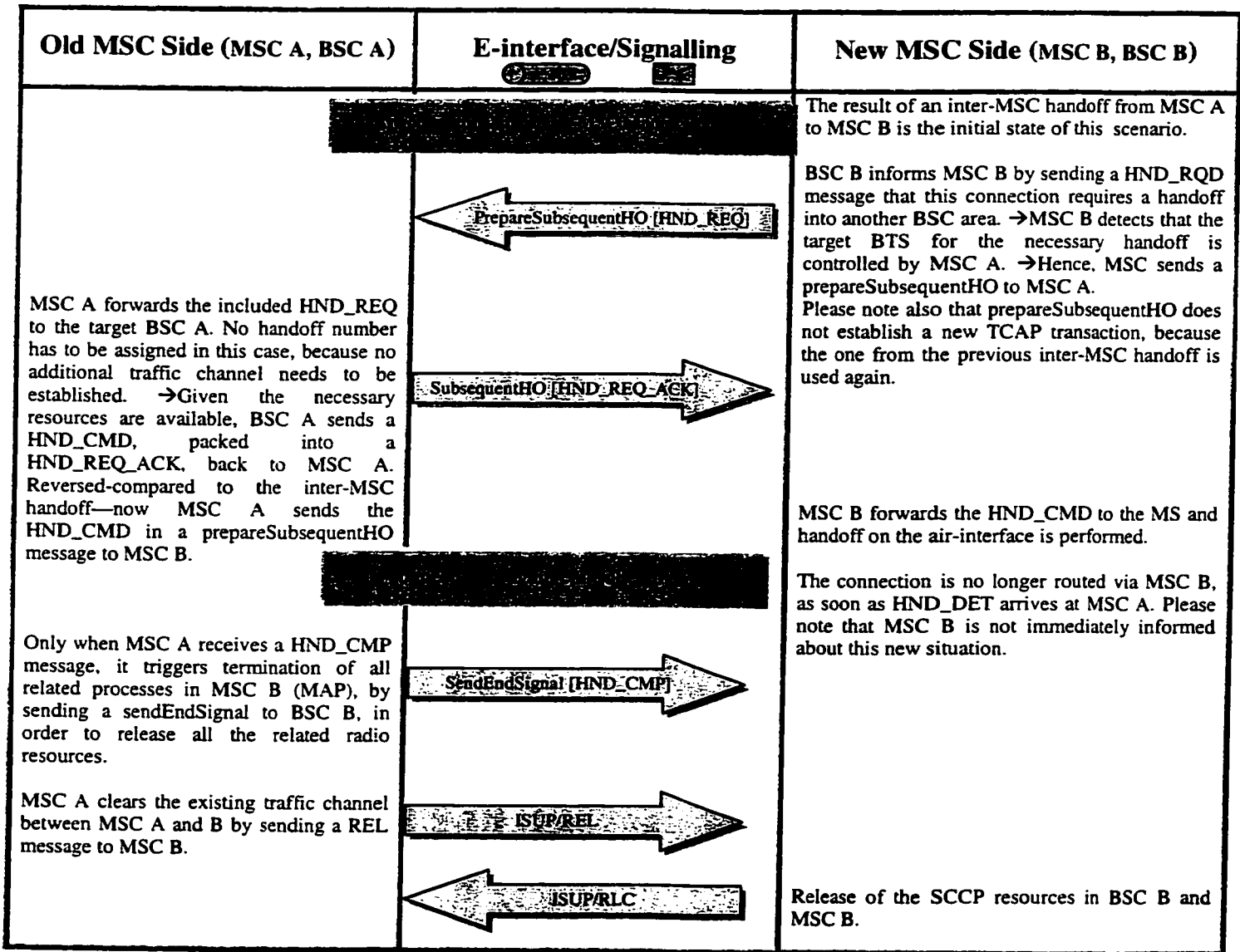


Figure 2.11 Scenario for Subsequent Handoff back to the Original MSC

Old MSC Side (MSC A, BSC A)	New MSC Side (MSC B, BSC B)	Third MSC Side (MSC C, BSC C)
<p>As an answer to the initial prepareHO (MAP), MSC A receives the final HND_CMD message, together with the handoff number from MSC C.</p> <p>MSC A sends the handoff number in an IAM (ISUP) message to establish a traffic channel between itself and MSC C.</p> <p>MSC A forwards the HND_CMD to MSC B as its answer to prepareSubsequentHO.</p>	<p style="text-align: center;">[REDACTED]</p> <p>BSC B requests a handoff into a BSC area, which is controlled by a foreign MSC. → MSC B sends a prepareSubsequentHO (MAP) to MSC A, which forwards this request in a prepareHandoff (MAP) to the target MSC (MSC C).</p> <p>←</p> <p>→</p> <p>MSC B sends the HND_CMD to the MS.</p>	<p>The initial state here is the same, as that of the previous scenario, which is the state after an inter-MSC handoff from MSC A to MSC B.</p> <p>→</p> <p>Now, MSC/VLR C have to provide the radio resources (HND_REQ) and have to assign a handoff number.</p> <p>MSC C confirms establishment of this channel (ACM).</p> <p>VLR(Visitor Location Register) C releases the handoff number. The MS executes handoff and reports this to BSS C. → BSS C then sends HND_DET, which is passed on from MSC C to MSC A.</p>

**Figure 2.12** Scenario for Subsequent Handoff to a Third MSC

**5) Handoff (Roaming) between Two Different Systems (Scenario 5):** is a handoff required between two cells belonging to different MSCs in the different systems, in order to provide seamless handoff. Currently, this requires a fix dual-/tri-mode mobile station and the inter-working of these two different systems to support this kind handoff operation (also called roaming). In Chapter 3, we will develop a new concept—which requires a re-configurable, multi-mode mobile station to support this kind of handoff operation (roaming). The main difference compared to traditional radios is thus the total programmability. Traditional mobile stations are typically composed of digital and analogue components. As most of the analogue components are not tuneable, SDR implementations in wireless handsets may be viewed in comparison with a generic PC model in the form of a multiple service model.

#### *2.2.3.3.3 Five Major Types of Handoff in Mobile Communication System*

For analog cellular, the MS is commanded to tune to a new frequency; the handoff process caused a short break in the voice path and a noticeable ‘click’ heard by both parties in the telephone call. For data modem, the click often causes data errors or loss of data synchronization. In CDMA, soft handoff greatly reduces the link outages in the transition region and in handoff using a technique that allows simultaneous transition to and from the user through two cells. During handoff, the signalling and voice information from multiple base stations must be combined in a common point with decisions made on the “quality” of the data. Similarly, voice and signalling information must be sent to multiple base stations, and the mobile station must combine the results. The common point could be anywhere in the network but is typically at the Mobile Switching Center (MSC). The call flows described here for handoff assume that the MSC contains the combining circuitry.

Subsequently, five types of handoff in current mobile systems, i.e. soft handoff, softer handoff, hard handoff, semi-soft handoff and idle handoff, are defined [6], [9]. Only detailed call flows of a soft handoff and idle handoff are presented, while other types of handoff process would be similar to the scenarios described before.

**1) Soft Handoff** occurs when the new base station (BS) begins communications with the mobile station (MS) while the MS is still communicating with the old BS. The MSC combines the received signals from both base stations to process an uninterrupted signal to the distant party. The MS will receive the transmissions from the two base stations as additional multi-paths in the RAKE receiver and will process them as one signal. RAKE receiver consists of correlators, each receiving a multipath signal. After spreading by correlators, the signals are combined using.

The BS directs the MS to perform a soft handoff only when all forward traffic channels assigned to the MS have identical frequency assignments. Soft handoff provides diversity of forward traffic channels and reverse traffic channel paths on the boundaries between base stations.

At call initiation, the MS is supplied a tailored set of handoff thresholds and a list of cells that are most likely to be the candidates for handoff. While tracking the signal from the original cell, the MS searches for all the possible pilots and maintains a list of all pilots whose signals are above a threshold established in the initial setup. This list is transmitted to the MSC whenever

- (1) It is requested;
- (2) The list changes by having a new pilot appear on the list;
- (3) When an existing pilot falls below a level that is useful to support the traffic.

A detail call flow of a soft handoff is illustrated in Figure 2.13.

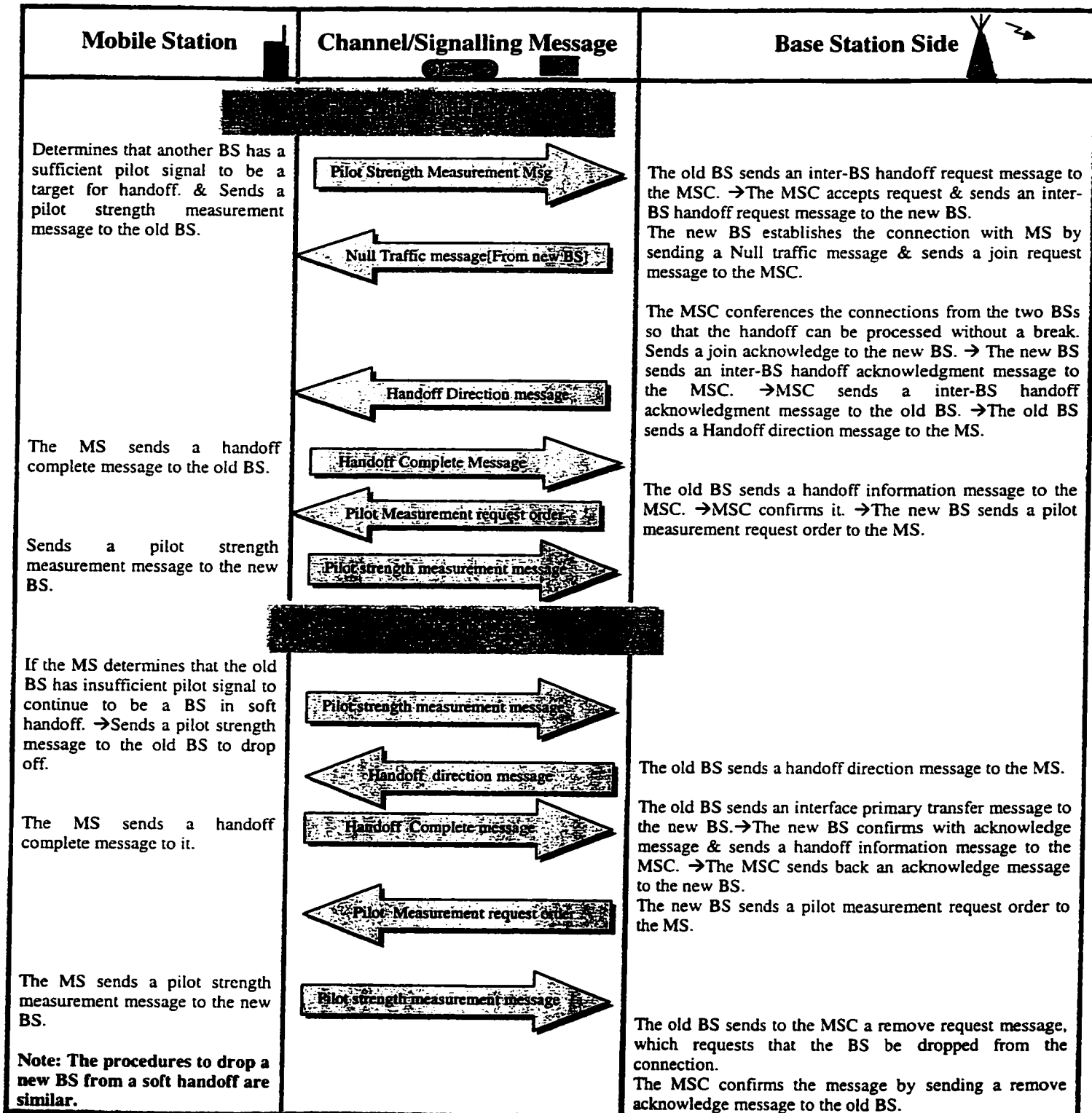


Figure 2.13 The Call Flow of a Soft Handoff

**2) Softer Handoff** occurs when the MS is in handoff between two different sectors at the same cell/BTS. Typically, a BS is designed so that an antenna transmits and receives over a  $120^\circ$  sector rather than a full  $360^\circ$ . For the discussion of softer handoffs, it is useful to designate a sector as a primary sector (the older sector serving the call). The operation of softer handoff is similar to that of intra-BTS handoff discussed before.

**3) Hard Handoff** occurs when the two base stations are not synchronized or not on the same frequency and an interruption in voice or data communication occurs. Hard handoffs can occur when more than one frequency band is used, or the two BSs are not synchronized, e.g., in two different systems. For CDMA IS-95 system, another type of hard handoff occurs when there is no serving CDMA base station available and the MS must be directed to an analog cellular channel. For example, CDMA to CDMA hard handoff, in which the BS directs the MS to transition between disjoint sets of base stations, different frequency assignments, or different frame offsets. In addition CDMA to analog handoff, in which the BS directs the MS from a forward traffic channel to an analog voice channel.

**4) Semi-soft handoff** occurs when the handoff appears as a soft handoff within the network but the MS processes it as a hard handoff. This handoff occurs in CDMA system only.

**5) Idle handoff procedures:** An idle handoff occurs when a MS has moved from the coverage area of one base station into the coverage area of another base station during the MS idle state. The MS determines that an idle handoff should occur when it detects a sufficiently strong pilot/broadcast channel signal other than that of the current base station's pilot/broadcast channel signal.

For CDMA IS-95 in the MS idle state, the mobile station continuously searches for the strongest pilot channel signal on the current CDMA frequency assignment whenever it monitors

the paging channel. If the MS determines that one of the neighbour set or remaining set pilot channel signals is sufficiently stronger than the active set pilot channel, the MS should performed an idle handoff as specified in the following.

While performing an idle handoff, the MS operates in the non-slotted mode until the MS has received at least one valid message on the new paging channel. Following the reception of this message the mobile station resumes slotted mode operation. After performing an idle handoff, the MS discards all unprocessed messages received on the old paging channel.

In CDMA, both the BS and the MS monitor the performance of the radio link and can request handoffs. Handoffs requested by a mobile station are called *mobile-assisted handoffs*; and those requested by the BS are called *base station assisted handoffs*. Either side can initiate the handoff process whenever the following triggers occur: base station traffic load, distance limits exceeded, pilot signal strength below threshold, power level exceeded. The mobile station determines the parameters for the handoff request from the system parameters message in the CDMA system and the broadcast message in the wideband code division multiple access (W-CDMA). Both messages are transmitted on their system's paging channels.

In the next Chapter 3, we propose a reconfigurable multi-mode MS that could perform seamless handoff/roaming between different wireless systems.

# **Chapter 3 Reconfigurable Multi-mode Mobile Station for Mobile Communication Systems**

## **3.1 Profile of the Reconfigurable Multi-mode Mobile Station**

**F**or a reconfigurable mobile station (MS), instead of changing the ROM for application software, new version of the software is downloaded from the universal base station. The new system software code could be saved as a new file or could replace the old one in the flash memory at a MS. Restrictions on the memory size and power consumption at mobile station should be considered for further design. Software radio can provide the terminal agent function, which is realized according to the user's favor such as cost effectiveness, quality of service (QoS), etc.

While the MS moves to a new area, in addition if the quality of service (QoS) of the mobile is bad and the same system is not available, the mobile will automatically switch to a new system by downloading new system software over-the-air. The downloaded new system software codes are then saved as a file in the memory. Possibility of the change of system is rather high when the systems are overlapped in the same area. This chapter mainly addresses the software download issues in a reconfigurable mobile station, all the transition probabilities and all transition times involved to all download. The downloaded software will consist of two parts: The first controls the hardware configuration of the MS unit and the second constitute the medium access control (MAC), signaling and higher networking layer at the MS.



### ***3.1.1 Over-the-Air Reconfiguration***

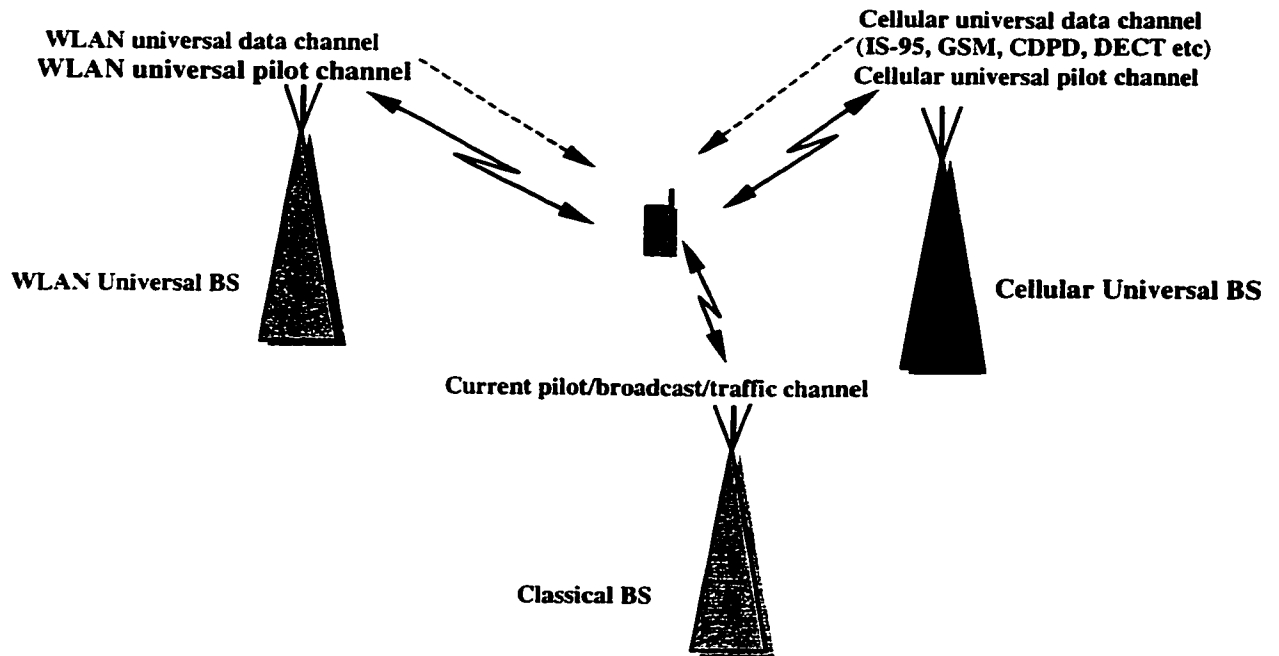
#### **3.1.1.1 Configuration of the Universal Base Station**

*Universal base station* means a base station that has the necessary software for all standard systems such as GSM, CDMA IS-95, DECT, UMTS etc. This BS will download such software code to a power-up or roaming mobile station upon request. Each universal base station has two types of channels—universal pilot channel and universal data channel.

*Universal pilot channel* is a synchronization reference, message broadcasting, and signaling channel. The mobile will use this channel to exchange signaling with the universal base station for system software to be downloaded. We assume that new universal pilot channels would be generating in each of the 900, 1800, 1900, 2400, 5000 MHz band.

*Universal data channel* is dedicated to the mobile station for downloading the system software code, which will configure the modulation, access, and network functionalities of the reconfigurable and transparent mobile station. This mobile station has general firmware that can be programmed to any standards.

In a general sense, *software download (SW\_DL)* can be defined as being the “process of introducing new program code to a terminal to modify its operation or performance”. Normally, there are two methods for downloading system software code to a mobile—a smart card loading (e.g. SIM) and air interface loading. Herein, we propose downloading the software data over the wireless link. When the mobile station is in areas defined as having a mixture of universal cellular base stations, universal wireless LAN base stations, and classical base stations having only one cellular standard, the scenario is shown in Figure 3.1.



**Figure 3.1** Over-the-Air Reconfiguration

### 3.1.1.2 Configuration of the Mobile Station

To make the mobile terminal reconfigurable, two configurations on the mobile station will be defined here. First of all, each mobile station would have *a certain ROM* for storing the default software code as defined by home location, such as GSM, CDMA IS-95, DECT etc, together with *a certain memory* for storing two system software code files. In addition, each mobile station would have a *universal save button*, which could be used by the user to control the system software download mode.

### 3.1.1.2-1 Code Tree

We define 7 function indication bits for a reconfigurable multi-mode mobile station as shown in Table 3.1. While the mobile station is power-up or roaming, it will check these functional indicator bits to make a initial state transition decision. Before discussing how the mobile station operates accordingly, we present a code tree that shows all the possible combinations of these indication bits in Figure 3.2. Note that the branch going up represents the value 1.

**Table 3.1 7 Function Indication Bits for the Mobile Station**

Indicator & Symbol		Probability	Meaning of symbol value $I_i=1$
Universal save button	$I_1$	$\theta_1$	MS battery level is low then it will be forced to switch on the universal button or the button is pressed so that the user can select different systems.
Cellular universal pilot channel	$I_2$	$\theta_2$	Cellular universal pilot channel is available in this area.
WLAN universal pilot channel	$I_3$	$\theta_3$	WLAN universal pilot channel is available in this area.
Same kind BS/system	$I_4$	$\theta_4$	Same kind of BS or system is available in this area.
QoS over the current system	$I_5$	$\theta_5$	Current quality of service is good.
Cellular universal data channel	$I_6$	$\theta_6$	Data channel for downloading new cellular software is available.
WLAN universal data channel	$I_7$	$\theta_7$	Data channel for downloading new WLAN software is available.

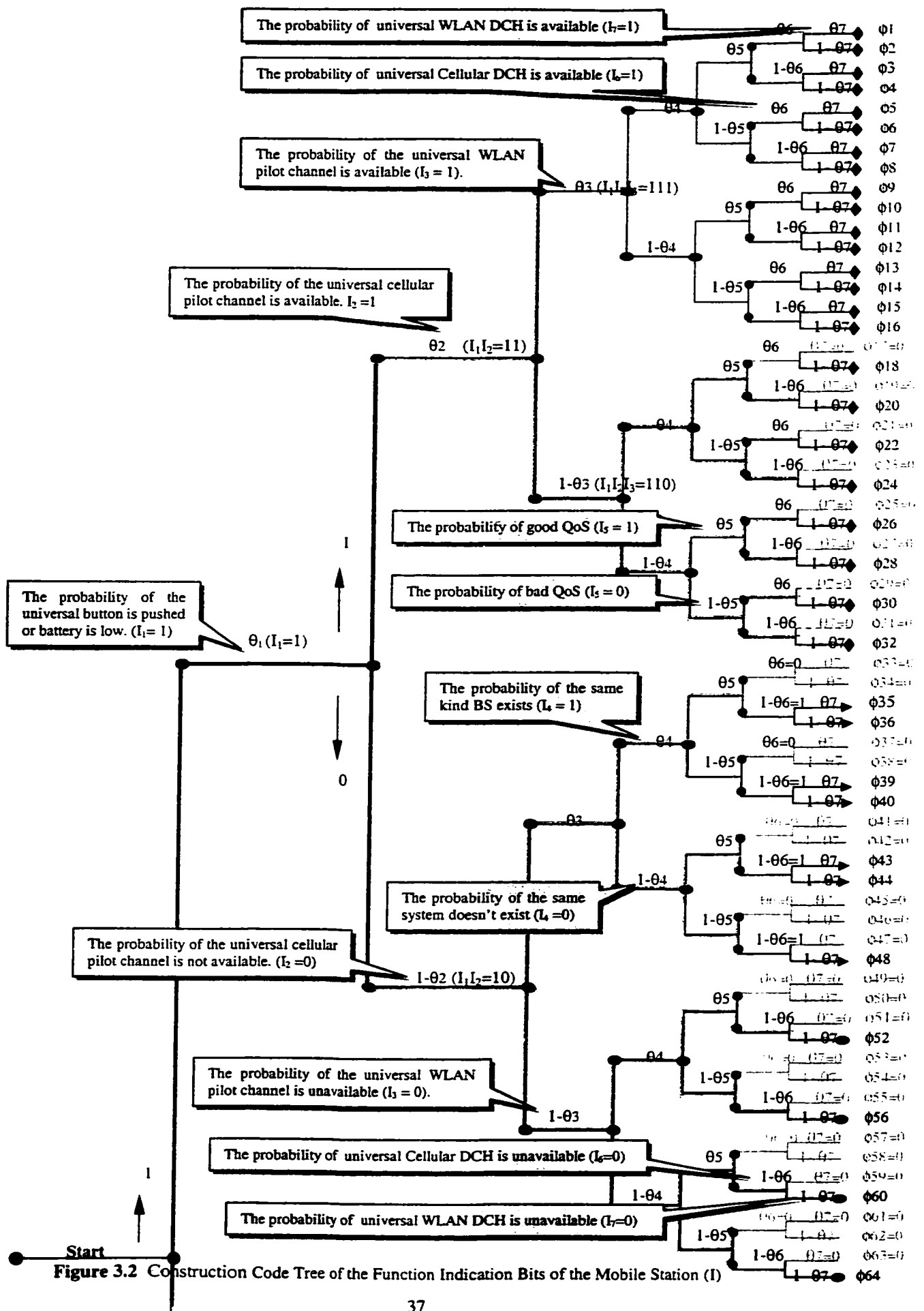


Figure 3.2 Construction Code Tree of the Function Indication Bits of the Mobile Station (I)

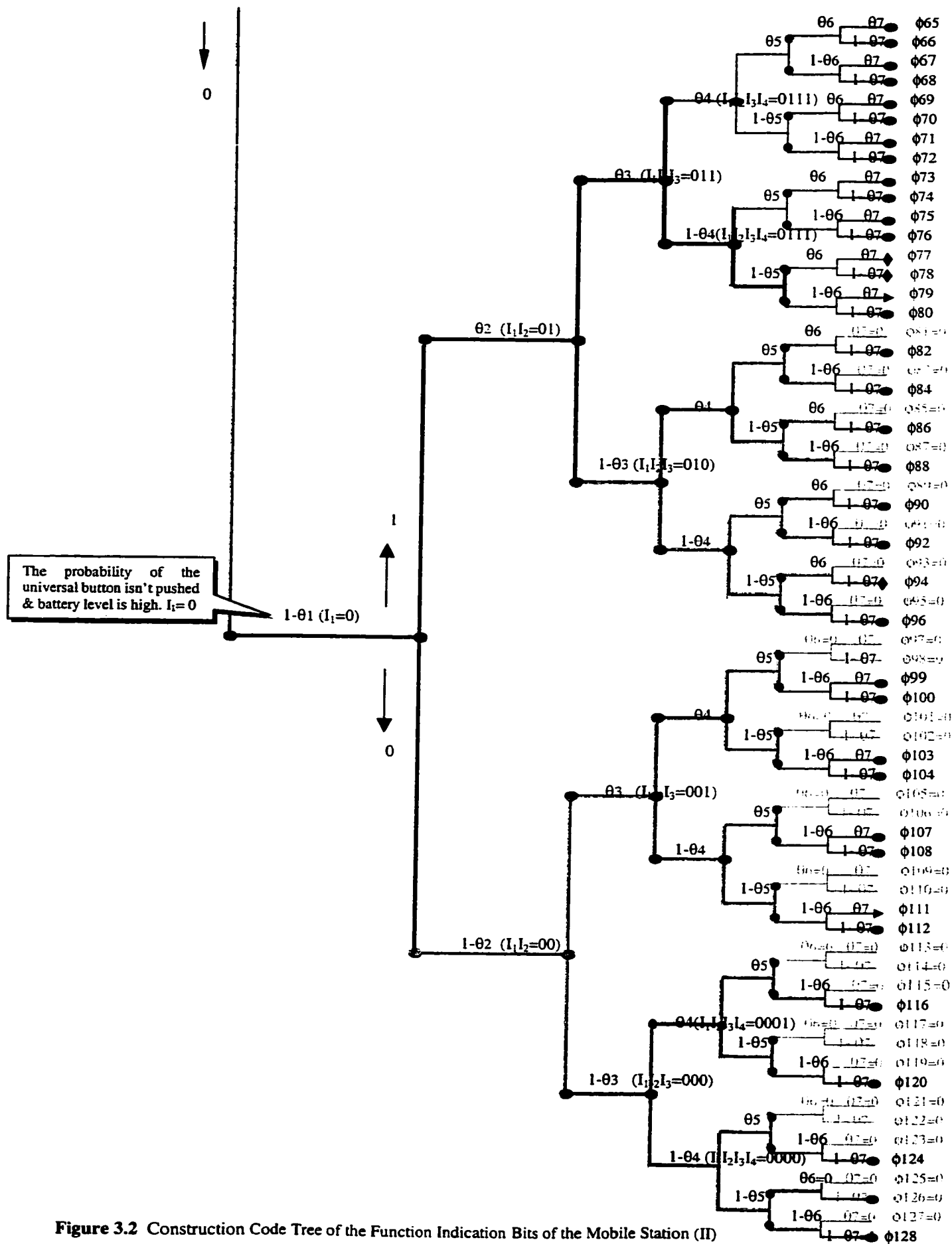


Figure 3.2 Construction Code Tree of the Function Indication Bits of the Mobile Station (II)

In this code tree, we labeled the probabilities of the functional bits beyond the branches or the leaves and placed the joint probabilities  $\phi_i$  on the right side of the leaves. The joint probability  $\phi_i$  is the probability of that the corresponding branch code value occurs. Based on this concept, it is clear that the probability of  $I_1I_2I_3I_4I_5I_6I_7 = 1111111$  occurring is  $\phi_1$ , the probability of  $I_1I_2I_3I_4I_5I_6I_7 = 1111110$  occurring is  $\phi_2$ , the probability of  $I_1I_2I_3I_4I_5I_6I_7 = 1111101$  occurring is  $\phi_3$ , the probability of  $I_1I_2I_3I_4I_5I_6I_7 = 0000000$  occurring is  $\phi_{128}$ , etc.

Since the construction of the code tree from the function indication bits is independent, the joint probability  $\phi_i$  corresponding to a branch equals to the products of all the probabilities labeled on this branch. For example,  $\phi_1 = \theta_1\theta_2\theta_3\theta_4\theta_5\theta_6\theta_7$ ,  $\phi_2 = \theta_1\theta_2\theta_3\theta_4\theta_5\theta_6(1-\theta_7)$ ,  $\phi_{128} = (1-\theta_1)(1-\theta_2)(1-\theta_3)(1-\theta_4)(1-\theta_5)(1-\theta_6)(1-\theta_7)$ , and so on. Further, the probability of  $I_1I_2I_3I_4I_5I_6I_7 = 1111111$  is  $\phi_1 = \theta_1\theta_2\theta_3\theta_4\theta_5\theta_6\theta_7$ , the probability of  $I_1I_2I_3I_4I_5I_6I_7 = 0000000$  is  $\phi_{128} = (1-\theta_1)(1-\theta_2)(1-\theta_3)(1-\theta_4)(1-\theta_5)(1-\theta_6)(1-\theta_7)$ , and so on.

In fact, some of the combinations in the code tree in Figure 3.2 will never occur, since  $I_6$  will be automatically set to zero if  $I_2 = 0$ ; similarly,  $I_7 = 0$  if  $I_3 = 0$ . This means that the cellular software code download is not available if there is no cellular universal pilot channel, and the wireless LAN software code download is not available if there is no wireless LAN universal pilot channel. This also implies that when the cellular universal pilot does not exist, i.e.  $I_2 = 0$ , the probability of the cellular software download data channel available  $\theta_6 = 0$ ; same principle applies to wireless LAN, i.e. when  $I_3 = 0$ , the probability of the wireless LAN software download available  $\theta_7 = 0$ . For those leaves, we marked  $\phi_i = 0$  in the code tree, which means it won't happen. For example,  $\phi_{17} = 0$  means the probability of  $I_1I_2I_3I_4I_5I_6I_7 = 1101111$  equals to zero;  $\phi_{105} = 0$  means the probability of  $I_1I_2I_3I_4I_5I_6I_7 = 0010110$  equals to zero, etc.

In order to show how the mobile station makes a path decision in automatic mode, we distribute all the branches in this code tree into four groups and mark them in different symbols - “◆”, “→”, “●”, “-”. This means that if the function indication bit  $I_1I_2I_3I_4I_5I_6I_7$  equal to:

- a) One of the values corresponding to the “◆” branches, the mobile station will make the transition to cellular system software code download path.
- b) One of the values corresponding to the “→” branches, the mobile station will make the transition to wireless LAN system software code download path.
- c) One of the values corresponding to the “●” branches, the mobile station will make the transition to the same system path.
- d) One of the values corresponding to the “-” branches, some errors may have occurred.

The mobile station ignores these values, since these branches represent the cases that will not happen.

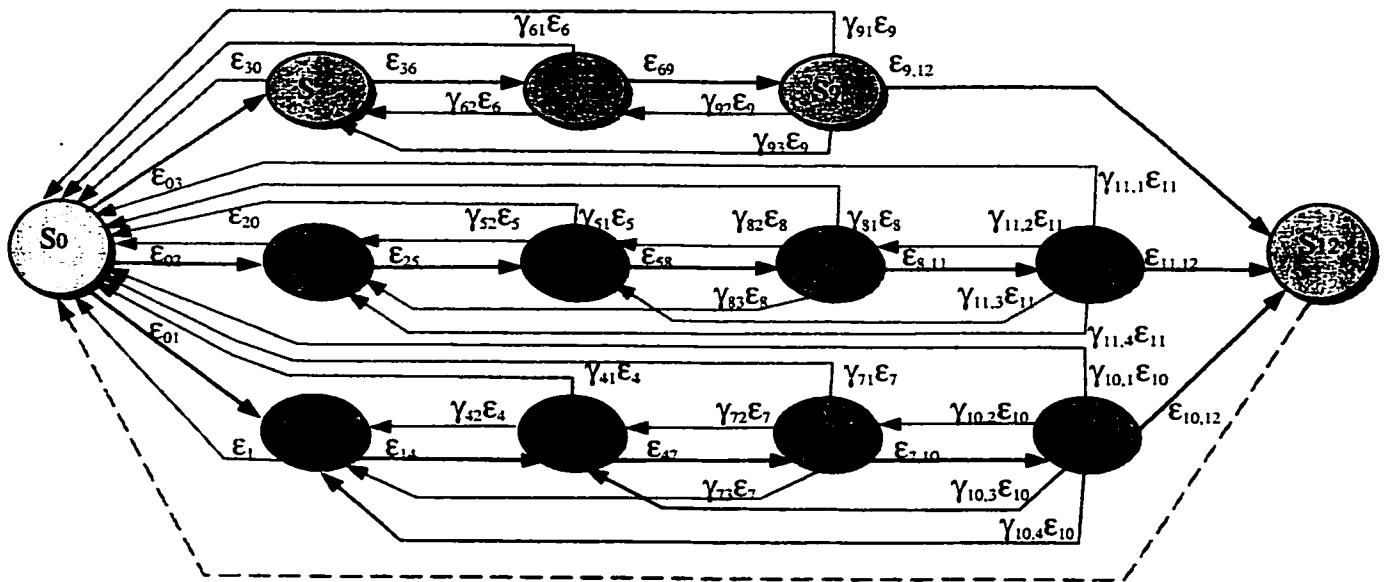
### **3.1.1.2-2 State Diagram**

To represent the set of events that can take place while the MS is roaming and trying to make a connection with the network, we build up a generalized roaming connection state diagram of the reconfigurable mobile station as illustrated in Figure 3.3. It consists of 12 states  $S_0, S_1, S_2, S_3, S_4, S_5, S_6, S_7, S_8, S_9, S_{10}, S_{11}, S_{12}$ ; their corresponding meanings are described in the following **Table**

### **3.2.**

**Table 3.2 The Possible States of the Mobile Station**

State	Meaning
S <sub>0</sub>	Starting state.
S <sub>1</sub>	Listening to the cellular universal pilot channel.
S <sub>2</sub>	Listening to the WLAN universal pilot channel.
S <sub>3</sub>	Listening to the same kind base station pilot /broadcast channel.
S <sub>4</sub>	Authentication, signaling exchange with cellular universal base station.
S <sub>5</sub>	Authentication, information exchange with WLAN universal base station.
S <sub>6</sub>	Authentication, information exchange with the same kind system.
S <sub>7</sub>	Authenticated MS is downloading new cellular system software from data channel.
S <sub>8</sub>	Authenticated MS is downloading new wireless LAN software from data channel.
S <sub>9</sub>	Call establishment in the same system (Handoff/roaming may happen at this time).
S <sub>10</sub>	New system update, call establishment signaling with the new cellular system.
S <sub>11</sub>	New system update, connection establishment signaling with WLAN.
S <sub>12</sub>	Connected to the network.



**Figure 3.3** The Generalized State Diagram of the Mobile Station

The cellular system download path is path 1, i.e.,  $S_0 \rightarrow S_1 \rightarrow S_4 \rightarrow S_7 \rightarrow S_{10} \rightarrow S_{12}$ .

The wireless LAN system download path is path 2, i.e.,  $S_0 \rightarrow S_2 \rightarrow S_5 \rightarrow S_8 \rightarrow S_{11} \rightarrow S_{12}$ .

The same system path is path 3, i.e.,  $S_0 \rightarrow S_3 \rightarrow S_6 \rightarrow S_9 \rightarrow S_{12}$ .



When the mobile station moves to a new area, if the quality of service (QoS) of the mobile is bad and the same system is not available, the mobile will automatically switch to a new system by downloading a new system software over-the-air. The downloaded new system software codes are then saved as a file in the memory of the MS. In next section, we mainly discuss the software download modes in a reconfigurable mobile station.

### 3.1.1.2-3 Software Download Modes

Here, we maintain that the user can choose automatic mode or preferred mode for the mobile station (MS). In *automatic mode*, the MS may take different paths in the state diagram, with initial transition probabilities of three paths are  $\epsilon_{01}$ ,  $\epsilon_{02}$ ,  $\epsilon_{03}$  respectively. These 3 paths correspond to downloading various cellular system software code, wireless LAN software code or staying in the same system.

In the *cellular system preferred mode*, the MS may take path 1 or path 3 in the state diagram, with transition probabilities  $\epsilon_{01}$  and  $\epsilon_{03}$  respectively. Thus, it may request universal cellular BS to download various cellular system software code or stay in the same system. The MS will never take path 2 in this mode, i.e.,  $\epsilon_{02} = 0$ . In *wireless LAN system preferred mode*, the MS may take path 2 or path 3 in the state diagram, with transition probabilities  $\epsilon_{02}$  and  $\epsilon_{03}$  respectively. Therefore, it may download various wireless LAN code or stay in the same system. The MS will never take path 3 in this mode, i.e.,  $\epsilon_{03} = 0$ . We can conclude that:

- 1) In the **automatic mode**,  $I_1 = 1$  (probability is  $\theta_1$ ):
  - o If  $I_2 = 1$ , transition is made to state  $S_1$  (See Figure 3.3).
  - o If  $I_2 = 0$  and  $I_3 = 1$ , transition is made to state  $S_2$  (See Figure 3.3).
  - o Else,  $I_2 = 0$  and  $I_3 = 0$ , transition is made to state  $S_3$  (See Figure 3.3).

That is to say, in the automatic mode, the MS will select the cellular download path once the universal cellular pilot is available, whatever the other conditions are satisfied or not. The MS will select the WLAN download path only when the universal cellular pilot is not available but the WLAN pilot is available. Otherwise, the MS will still operate on the current system.

2) In the **cellular system preferred mode**,  $I_1 = 1$  (probability is  $\theta_1$ ):

- If  $I_2 = 1$ , transition is made to state  $S_1$ . (See Figure 3.3)
- Else,  $I_2 = 0$ , transition is made to state  $S_3$ . (See Figure 3.3)

3) In the **wireless LAN (WLAN) preferred mode**,  $I_1 = 1$  (probability is  $\theta_1$ ):

- If  $I_3 = 1$ , transition is made to state  $S_2$ . (See Figure 3.3)
- Else,  $I_3 = 0$ , transition is made to state  $S_3$ . (See Figure 3.3)

That is to say, in the cellular preferred mode, the mobile station will select the cellular download path once the universal cellular pilot is available, whatever the other conditions are satisfied or not; otherwise, the mobile station will still operate on the current system. In the WLAN preferred mode, the mobile station will select the WLAN download path once the universal WLAN pilot is available, whether other conditions are satisfied or not; otherwise, the mobile station will still operate on the current system.

4) When the universal button is **OFF**,  $I_1 = 0$  (probability is  $1-\theta_1$ ):

a) In the case of  $I_4$  **OR**  $I_5 = 0$ ,

- If  $I_2$  **AND**  $I_6 = 1$ , transition is made to state  $S_1$ .
- If  $I_2$  **AND**  $I_6 = 0$  &  $I_3$  **AND**  $I_7 = 1$ , transition is made to state  $S_2$ .
- Else, transition is made to state  $S_3$ .

b) In the case of  $I_4$  **OR**  $I_5 = 1$ , transition is made to state  $S_3$ .

That is to say, in the OFF mode, the mobile station will select the cellular download path, only when the QoS is bad and the same system is not available, but the cellular universal pilot channel and software download data channel are available. The MS will select the WLAN download path, if the QoS is bad and the same type system is not available, in addition the cellular universal pilot and software download are not available, but the Wireless LAN universal pilot channel and software download data channel are available. Otherwise, the mobile station will still operate on the current system.

Next, we further present how these will be taken into account in the initial transition probabilities of different pathes of the state diagram. The calculation of initial transition probabilities  $\epsilon_{01}$ ,  $\epsilon_{02}$ ,  $\epsilon_{03}$  are given below:

1) In automatic mode:

$$\epsilon_{01} = \sum_{i=1}^{32} \phi_i + \phi_{77} + \phi_{78} + \phi_{94} = \theta_1 * \theta_2 + (1 - \theta_1) * \theta_2 * (1 - \theta_4) * (1 - \theta_5) * \theta_6$$

$$\epsilon_{02} = \sum_{i=33}^{48} \phi_i + \phi_{79} + \phi_{111} = \theta_1 * (1 - \theta_2) * \theta_3 + (1 - \theta_1) * \theta_3 * (1 - \theta_4) * (1 - \theta_5) * (1 - \theta_6) * \theta_7$$

$$\epsilon_{03} = 1 - \epsilon_{01} - \epsilon_{02}$$

2) In the cellular preferred mode:

$$\epsilon_{01} = \sum_{i=1}^{32} \phi_i + \phi_{77} + \phi_{78} + \phi_{94} = \theta_1 * \theta_2 + (1 - \theta_1) * \theta_2 * (1 - \theta_4) * (1 - \theta_5) * \theta_6$$

$$\epsilon_{02} = 0$$

$$\epsilon_{03} = 1 - \epsilon_{01}$$

3) In the WLAN preferred mode:

$$\epsilon_{01} = 0$$

$$\epsilon_{02} = \sum_{i=1}^{16} \phi_i + \sum_{i=33}^{48} \phi_i + \phi_{79} + \phi_{111} = \theta_1 * \theta_3 + (1 - \theta_1) * \theta_3 * (1 - \theta_4) * (1 - \theta_5) * (1 - \theta_6) * \theta_7$$

$$\epsilon_{03} = 1 - \epsilon_{02}$$

### ***3.1.2 Description of the Power-up Registration, Roaming Process***

In general, there are two scenarios that possibly require software download process. One is when the mobile station just powers up; another is when the mobile station roams to a new area. Since the roaming process is somewhat similar to the power-up process for a mobile, we describe the power-up process as an example.

When a reconfigurable mobile station just powers up, its first task is to acquire a universal pilot and data channel if the user wants new system software, or to acquire a classical pilot channel if the user wants to use the default mode or last registered (history) system. After the mobile station has successfully downloaded the system software, it updates its hardware according to the new system and operates as the classical single-mode mobile station. Hence, we can describe the power-up registration of the mobile station roughly in two distinct phases.

Phase1: New system software acquisition (Operating on the universal base station).

Phase2: Classical system updating, registration, connection establishment (Operating on the classical base station).

A power-up registration is performed according to the flowchart of Figure 3.4. A mobile station first checks the universal button indicator  $I_1$ .

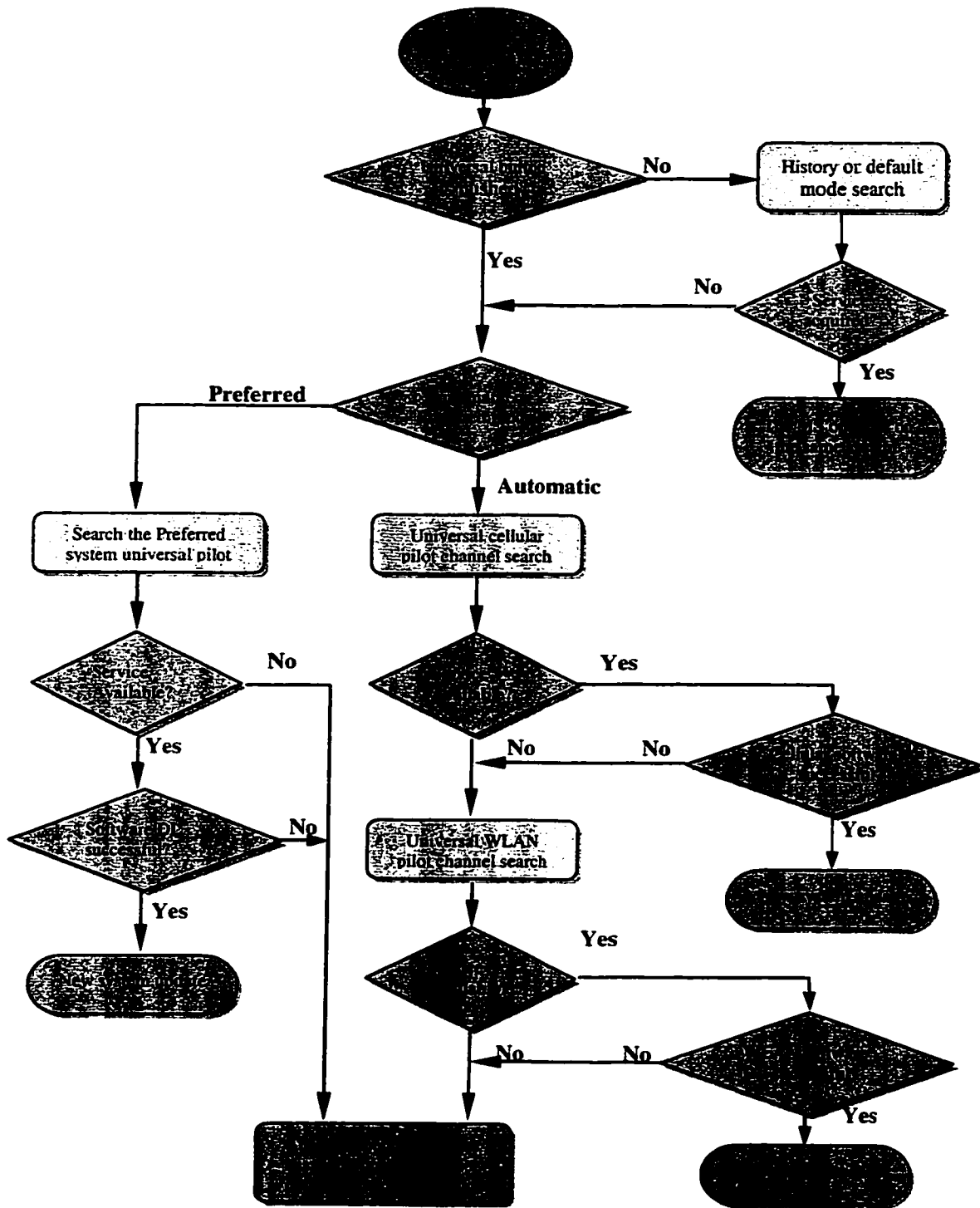


Figure 3.4 Flowchart of the MS Power-up or Roaming Procedure

1) If the user has not pushed the universal save button (i.e.,  $I_1 = 0$ ), the MS calls the system software stored in file 1 and conducts what is called a history search of a list of channels, where the MS either has obtained service in the past or has obtained information in the past indicating there is a high probability of obtaining service on these channels. The entries in the pilot/paging channel history table (PCHHT) are checked. The received signal strength on the PCHHT entries must be above a certain prespecified history threshold in order to be considered during the historic search. If the mobile station obtains service from the last registered system, it will start the initialization, registration process, or connection establishment in this system.

If the mobile station completes the historic search portion of the power-up scan without obtaining service, it enters a default mode/home system scan. During a default/home system scan, the mobile scans the default/home system frequency bands trying to obtain service from the base station that is available. If the mobile station fails to find service on an acceptable service provider while checking the last registered mode and default/home system, “**system X is no service here**” message is shown in the mobile station. At the same time, the mobile station will automatically switch the universal button on and sets  $I_1 = 1$ , then it operates as if the universal button has been pushed.

**This guarantees that** if the mobile is powered up in the same general area where it was powered down, or in the area that was served by the home service provider, the mobile will quickly find service on the same/home service provider.

2) If the universal button is pushed (i.e.,  $I_1 = 1$ ), the user may choose the automatic software download mode or the preferred system download mode. **In the automatic mode**, the mobile station begins searching the universal cellular and wireless LAN pilot channels, which enables

the signaling exchange between the mobile station requiring new system software and the universal base station.

In the universal base station, the available software codes of new systems are listed in a certain order so called software database (SWDB) order here. Correspondingly, a system database (SYSDB) list will broadcast to the mobile stations covered by the universal base station through the universal pilot channel. The SYSDB within a mobile may be updated as the roaming situation change using the over-the-air programming tele-service. Reprogramming of the SYSDB is a valuable feature for the mobile and service provider, because the new system configurations may change in some areas. The basic principle to build the SWDB is that the system providing voice and data services and requiring less memory space for downloading is placed in the first order, the system that can only provide voice service is placed in the middle order, the system that can only provide data service and needs much memory for downloading is placed in the last order, etc. For instance, if the universal cellular pilot channel is detected, the mobile station will take the cellular software download path. The mobile station will select the wireless LAN download path only when the universal cellular pilot channel is not available but the wireless LAN pilot channel is available, since the wireless LAN provides only computer/data communication. The traffic situation in different serving areas is also considered while the universal base station builds the SWDB.

In each software code download path, the mobile station firstly tunes to the pilot channel and begins authentication and signaling exchange with the universal base station through this channel. If the mobile station is authenticated, the universal base station will dedicate a data channel to the mobile station for downloading the new system software. When the system

software is downloaded successfully, the mobile station may obtain service and may initiate a mobile originated/terminated call as the single-mode mobile immediately.

Note that:

- *To avoid the unnecessary software download, the MS will reset the universal button to OFF after the software download procedure finished, until the software download mode is activated again.*
- *It is suggested that the mobile station move slowly while downloading.*

If all the universal software download data channel are busy, a “**Traffic is blocking**” message is sent to the mobile station, then the mobile station will check the function indication bits to make a new decision again. The network providers should reduce the occurrence of network resource blocking.

If the mobile station searches all the bands in the band order without finding a universal pilot channel in this area, it has to search the system using the default mode and the last stored file. In the event that no service is available, the MS will periodically restart the power-up registration as described above.

**When the mobile station is in automatic mode, it is worth mentioning:**

- a) In normal cases, the mobile station will select the cellular universal BS for new system software downloading if there exist such services in this area, even though the traffic is crowded. According to the software database (SWDB) order, the universal base station will dedicate a data channel for downloading the software code of a new system that can provides both voice and data service.
- b) In some specific cases, the universal BS can only download voice or data service system software codes to the mobile station, such as the mobile power or memory limitation, the



system or network configuration limitation in some area. For example, when the cellular universal pilot channel is not available but the wireless LAN universal pilot channel is available (i.e., I2=0 & I3=1), the mobile station will select the wireless LAN software download path. Or for instance, the memory size in a mobile station is only enough for storing the AMPS system software code, in such case the mobile station can obtain voice service only.

In the user **preferred mode**, the mobile station begins searching the cellular universal pilot channel and wireless LAN universal pilot channel, which is responsible for the signaling exchange between the universal base station and the mobile station requiring new system software. A system database (SYSDB) list will broadcast to the mobile stations covered by the universal base station through the universal pilot channel. Immediately following the download of a new SYSDB, the user knows about the new systems around him. If the user selects the cellular preferred mode, the mobile station will take the cellular software download path once the cellular universal pilot channel is available, whether the other conditions are satisfied or not. If the user selects the wireless LAN preferred mode, the mobile station will select the wireless LAN software download path once the WLAN universal pilot channel is available, whether the other conditions are satisfied or not. Upon entering each path, the mobile station repeats the same procedure as the automatic mode.

Nonetheless, if the mobile station searches all the bands in the band order without finding an universal pilot channel in this area, it has to search the system using the default mode and the last stored file. In the event that no service is available, the MS will periodically restart the power-up registration as described above and the whole process repeats.

## **3.2 Connection Establishment of the Roaming Mobile Station**

### **3.2.1 Description**

#### **3.2.1.1 The Transition Operation of the MS State Diagram**

When the mobile station (MS) is roaming, the connection processing can proceed in two possible ways – roaming in the current system or roaming to a new system. In the former situation, the mobile station operates in the way no different from a classical mobile station, such that no new software code downloading is required. In the later situation, the mobile station will register in a new system, using the existing software stored in the memory or downloading a system software code through a universal base station. After the mobile station has registered in the new base station, it can make a connection to the network as a classical mobile station. The details about connection/call establishment, handoff signalings for a classical mobile station have been presented in Chapter 2. In the following, we focus on discussing the new concepts about the reconfigurable multi-mode mobile station, referring to the state diagram in Figure 3.3.

For the state diagram in Figure 3.3,  $S_0, S_1, S_2, S_4, S_5, S_7, S_8$  belong to phase 1, and  $S_3, S_6, S_9, S_{10}, S_{11}, S_{12}$  belong to phase 2. This implies that:

- a) The mobile station operates on the universal base station and their channels when it is in the state  $S_0, S_1, S_2, S_4, S_5, S_7, S_8$  in path 1 and path 2;
- b) The mobile station operates on the classical base station and their channels when it is in the state  $S_3, S_6, S_9, S_{12}$  in path 3 and  $S_{10}, S_{11}, S_{12}$  in path 1 and path 2.
- c) The mobile station will skip the Phase 1 and takes the path 3 if it doesn't download the new system software code.

When the mobile just powers up or the mobile is currently listening to a system pilot/broadcast channel but initiates a transition request, it enters the start state  $S_0$ . In this state,

the mobile station begins searching for the universal pilot channel signals from the universal cellular (or wireless LAN) base station and the pilot channel signal from the classical base station. The mobile station will check the functional indicator bits to make a state transition decision, possible cases are listed in Table 3.3. The initial transition probabilities of three paths are  $\epsilon_{01}$ ,  $\epsilon_{02}$ ,  $\epsilon_{03}$  respectively.

**Table 3.3 Mobile Station Transition Operation Table (X – Don't care 1 or 0)**

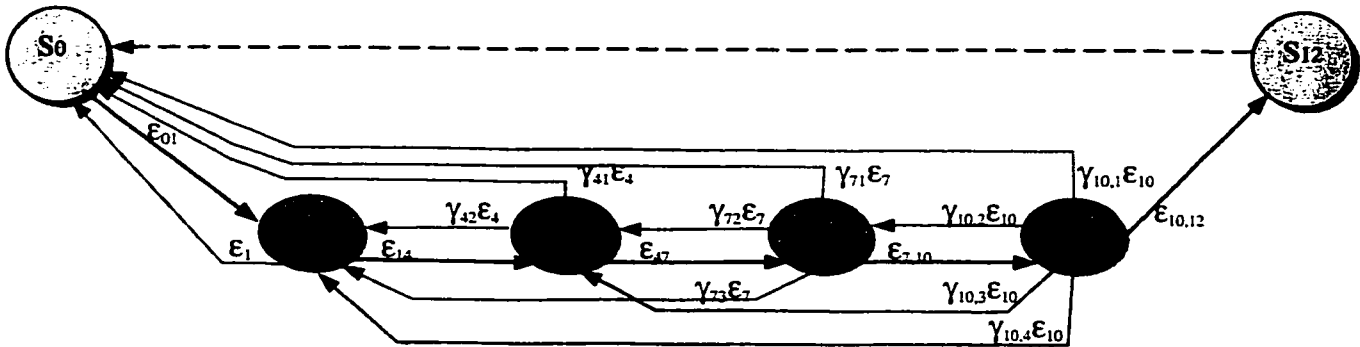
Mode	I <sub>1</sub>	I <sub>2</sub>	I <sub>3</sub>	I <sub>4</sub>	I <sub>5</sub>	I <sub>6</sub>	I <sub>7</sub>	MS Operations
AUTOMATIC	1	1	X	X	X	1	X	Transition is made to S <sub>1</sub> , Chooses the cellular SW_DL path1 & data channel is available to the mobile station.
	0	1	X	0	0	1	X	
	1	1	X	X	X	0	X	Transition is made to S <sub>1</sub> , Chooses the cellular SW_DL path1, but data channel is NOT available to the mobile station.
	1	0	1	X	X	X	1	Transition is made to S <sub>2</sub> , Chooses the WLAN SW_DL path2 & data channel is available to the mobile station.
	0	1	1	0	0	0	1	
	0	0	1	0	0	0	1	
1	0	1	X	X	X	0	Transition is made to S <sub>2</sub> , Chooses the WLAN SW_DL path2, but data channel is NOT available to the mobile.	
E L S E								Transition is made to S <sub>3</sub> , Chooses the same system path3.
CELLULAR	1	1	X	X	X	1	X	Transition is made to S <sub>1</sub> , Chooses the cellular SW_DL path1 & data channel is available to the mobile station.
	0	1	X	0	0	1	X	
	1	1	X	X	X	0	X	Transition is made to S <sub>1</sub> , Chooses the cellular SW_DL path1, but data channel is NOT available to the mobile station.
	E L S E							
WLAN	1	X	1	X	X	X	1	Transition is made to S <sub>2</sub> , Chooses the WLAN SW_DL path2 & data channel is available to the mobile station.
	0	1	1	0	0	0	1	
	0	0	1	0	0	0	1	
	1	X	1	X	X	X	0	Transition is made to S <sub>2</sub> , Chooses the WLAN SW_DL path2, but data channel is NOT available to the mobile station.
	E L S E							

In general, in each state S<sub>i</sub> for i = 1, 2, ..., 11, if the mobile station have transmitted and received the required signaling data packets successfully within the timer period, it will move to the next state in the path; otherwise if it fails to deliver the data packets or timeout, the mobile station may go back to one of the previous states. Figure 3.3 shows this idea and all the possible

backward transitions in each state  $S_i$ . We have labeled all transition probabilities for each states and the calculation of these values will be given in Section 3.2.2.1. In fact, when the packets in each state fails to deliver within a certain limit, the mobile station will choose only one of the previous states to move according to different design scenarios. Different scenario can be obtained by setting  $\gamma_{ij}$  to 1 or 0 in the general state diagram in Figure 3.3, each scenario corresponds to a different roaming times and delays that we will show in Chapter 5 Test Results.

Next, we will describe the operation of the mobile station in each path. Because the operation of the mobile station in path 2 is quite similar to that in path 1, we mainly discuss the operation of the mobile station in path1 (See Figure 3.4) and path3 (See Figure 3.5).

**3.2.1.2 The Transition Operation of the MS in Path 1 and Path 2**



**Figure 3.5** Cellular System Software Download Path of the Mobile Station Connection Establishment

Upon entering state  $S_1$  (path1), with probability  $\epsilon_{01}$ , the mobile station synchronizes to the universal base station in time and frequency. Then, it can listen to the cellular universal pilot channel and receive broadcast messages. In state  $S_1$ , the mobile station sends the software download request (Cellular\_DL\_Request) to the universal base station and listens to the universal cellular pilot channel, waiting for the authentication request (Authen\_Request) from this pilot channel. However, if the mobile station cannot tune to the cellular universal pilot

channel, it will return to the start state; this may happen with the probability  $\epsilon_1$  and corresponds to one of the feedback scenarios mentioned.

Subscriber authentication is performed at each new system software download process, at each call set-up attempt (mobile originating or terminated), and before performing some supplementary services such as activation or deactivation of the mobile. A universal base station should apply the authentication procedure to the mobile station in order to forbid the illegal mobile station access. The authentication procedure is performed after the subscriber identity (IMSI/TMSI) is known by the network and before the mobile station is dedicated a data channel for new system software download.

Upon receipt of the authentication request (Authen\_Request) message, the mobile station sends authentication confirmation (Cellular\_DL\_Authen\_Confirm) message. This implies it is entering the authentication and association state  $S_4$ . The mobile station begins authentication, association and signaling exchange with the universal base station through a universal pilot channel. *(The details about how the universal base station reaches the database and details of the universal authentication method are beyond the scope of this thesis.)* During this period, the MS may encounter one of the three possible situations.

- If the mobile station is authenticated, it will firstly send out a “short file”—memory and battery message to the universal base station. By considering these messages, the universal base station will send a CellularSW\_DL\_Ready message and dedicate a data channel (DCH) to the MS if the system resource is available. The mobile station will move to the next state  $S_7$  with transition probability  $\epsilon_{47}$ .
- If the authentication and signaling process fails due to error or system resource blocking, the MS will return to one of the previous state that depends on the design scenario. Or

else, the mobile station is illegal, it will never be permitted to access the data channel for download the system software codes. The mobile station may move to state  $S_0$ ,  $S_1$ , with backward transition probability  $\gamma_{41}\epsilon_4$ ,  $\gamma_{42}\epsilon_4$  respectively.

Upon receipt of CellularSW\_DL\_Ready message and the download data channel (DCH) message, the mobile station enters state  $S_7$  and begins to download the new system software code through the universal data channel. What kind of system software code will be downloaded? This is depending on both the traffic situation of the system and the mobile station resource situation. For instance, when the mobile station is in automatic mode, there are two general cases that have been discussed in Section 3.1.2 (See page 49).

On the other hand, when the MS is in the user preferred mode, by checking the new downloaded SYSDB, the user knows about the systems around him. If the user selects the system he wants, the mobile station will send this information to the universal base station during the authentication and signaling exchange period.

In state  $S_7$ , if the mobile resource is enough for the downloading process, the mobile station receives the codes on the data channel and stores them as a file so that the mobile station may call it anytime later. However, if the remained memory size of the MS is not enough for the codes, an blocking indication message is sent to the user **“Memory is full, would you like to delete the old file for more space?”** In this case, if the user answers with “Yes”, the mobile station will lose the system file stored in the other memory address; furthermore, if the mobile station is communicating with that system, the communication will be terminated immediately. Otherwise, if the user answers with “No”, the download process will be terminated immediately. *(We propose that each re-configurable mobile station could have a default mode whose data is*

***stored in a ROM by the manufacture and have two download modes whose data are saved as file1 and file2 stored in the memory such details are left for further research.)***

During this period, the MS may encounter one of four possible situations:

- If the system software has been downloaded completely, the mobile station sends out a download completed (CellularSW\_DL\_Completed) message to the universal cellular base station. The mobile station will moves to the next state  $S_{10}$  with transition probability  $\epsilon_{7,10}$ .
- If the system software code downloading process fails due to error or resource blocking, the mobile station will return to one of the previous state that depends on the design scenario. But if the user terminates the process, the mobile station will return to the start state and begins a new searching. The mobile station may move to state  $S_0, S_1, S_4$  with backward transition probability  $\gamma_{71}\epsilon_7, \gamma_{72}\epsilon_7, \gamma_{73}\epsilon_7$  respectively.

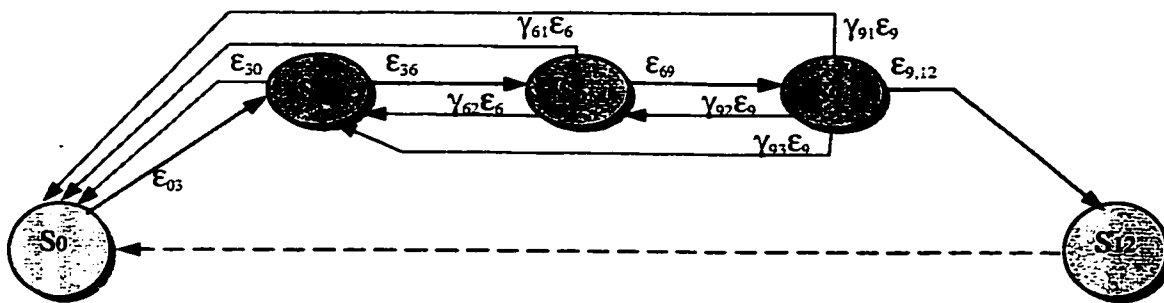
Having finished downloading the system software, the mobile station enters state  $S_{10}$ . In this state, it may process new system update, connection establishment signaling with the new cellular system. During this period, the mobile may result in five possible scenarios.

- If the downloaded system software code can be called correctly, the mobile station updates its hardware according to the new system, processes connection establishment signaling with the new network. Up to now, the user may initiate a mobile originated/terminated call using the single-mode mobile. The details about the registration and call procedure of different systems have been discussed before in Chapter 2. By receiving a connected (Cellular\_Connected) message, such as alert signaling, from the new classical base station. The mobile station will move to the next state  $S_{12}$  with transition probability  $\epsilon_{10,12}$ .

- If the connection establishment fails due to error or system resource blocking, the mobile station may return to one of the previous states that depends on the design scenario. If the new system updating fails due to some part of the software code error, it is a more effective design to return to  $S_7$ . But if the mobile station terminates the process, it will return to the start state  $S_0$  and begins a new searching. The mobile station may move to state  $S_0$ ,  $S_1$ ,  $S_4$ ,  $S_7$  with backward transition probability  $\gamma_{10,1}\epsilon_{10}$ ,  $\gamma_{10,2}\epsilon_{10}$ ,  $\gamma_{10,3}\epsilon_{10}$ ,  $\gamma_{10,3}\epsilon_{10}$  respectively.

Similar principle and process may be applied to the mobile station while it takes **path2**.

### 3.2.1.3 The Transition Operation of the MS in Path 3



**Figure 3.6** Same System Path of the Mobile Station Connection Establishment

As we have discussed before, start state  $S_0$  may imply that the mobile station (MS) just powers up or the mobile is currently listening to a system pilot/broadcast channel but initiates a transition request. If the MS just powers up, firstly, it starts a historic search by calling the system software in file 1 or 2. If the mobile station completes the historic search portion of the power-up scan without obtaining service, it enters a default mode/home system scan. The mobile station may obtain service, with probability  $\epsilon_{03}$ , moving from the start state  $S_0$  to the state  $S_3$  and synchronizing to the base station. If the mobile station is currently operating on a given system,



entering the state  $S_3$  means that the mobile should continue to listen to the pilot/broadcast channel of the same system.

Upon entering state  $S_3$  (path3), with probability  $\epsilon_{03}$ , the mobile station listens to the pilot channel and may receive broadcast messages from the classical base station. In state  $S_3$ , the mobile station sends the connection (SameSystem\_Setup) message or handoff request message while necessary to the classical base station and listens to the pilot/paging channel, waiting for the authentication request (Authen\_Request) from the network. However, if the mobile station cannot register in the classical base stations, it will return to the start state; this may happen with the probability  $\epsilon_{30}$ .

Upon receipt of the authentication request (Authen\_Request) message, the mobile station sends authentication confirmation (SameSys\_Authen\_Confirm) message. This implies it is entering the authentication and association state  $S_6$ . The mobile station begins authentication, association and signaling exchange with the classical base station. Subscriber authentication is performed at each registration, at each call set-up attempt (mobile originating or terminated), at each handoff and intelligent roaming process, and before performing some supplementary services such as activation or deactivation of the mobile. This procedure is different among different wireless systems, for details, the reader can refer to the references [1], [2], [3], [4], [6]. During this period, the mobile may encounter one of three possible situations.

- If the mobile station is authenticated, it will move to the next state  $S_9$  with transition probability  $\epsilon_{69}$ .
- If the authentication and signaling process fails due to error or system resource blocking, the mobile station will return to one of the previous states that as per design scenario selected. Or else, the mobile station is illegal, it will never be permitted to access the

traffic channel for communication. The mobile station may move to state  $S_0$ ,  $S_3$ , with backward transition probability  $\gamma_{61}\epsilon_6$ ,  $\gamma_{62}\epsilon_6$  respectively.

In state  $S_{10}$ , it may process system handoff, connection establishment signaling with the new cellular system. By successfully handoff, the base station will send a SameSys\_HO\_Completed message and dedicate a new control channel (CCH) or traffic channel (TCH) to the mobile if the system resource is available. During this period, the mobile may encounter one of four possible situations.

- The user may initiate a mobile origination and termination connection establishment immediately as using the single-mode mobile. Or handoff may occur in the same system while necessary. The details about the registration, connection, and handoff procedure of different systems have been discussed before in Section. By receiving a connected (SameSys\_Connected) message, such as alert signaling, from the new classical base station. The mobile station will move to the next state  $S_{12}$  with transition probability  $\epsilon_{9,12}$ .
- If the connection establishment fails due to error or system resource blocking, the mobile station may return to one of the previous state as per design scenario selected. But if the user terminates the process, the mobile station will return to the start state  $S_0$  and begins a new searching. The mobile station may move to state  $S_0$ ,  $S_3$ ,  $S_6$  with backward transition probability  $\gamma_{91}\epsilon_9$ ,  $\gamma_{92}\epsilon_9$ ,  $\gamma_{93}\epsilon_9$  respectively.

Note that: the connection procedure while the mobile station is in state  $S_6$  and  $S_9$  are the same as a classical single- or dual-mode mobile station. The main difference between them is only that the re-configurable mobile station can provide more intelligent roaming process. When the mobile station moves to a new area, if the same type of system is available in this area, the

handoff and roaming process of the mobile station in the current system is the same as a single-mode MS described in Chapter 2. However, for the case where there is no “same band” or “same mode” system provided to the mobile station, we have to introduce one new concept—intelligent roaming, which are originally derived from Digital PCS [4].

*Intelligent roaming* is a method for ensuring that a mobile station (MS) obtains service from the best provider in an area without requiring user intervention. While the MS moves to a new area, if the quality of service (QoS) of the MS is bad and the same system is not available, the MS will automatically switch to a new system by calling the file saved in the memory or downloading a new system software over-the-air. Intelligent roaming is only possible from a service provider using the same air interface technology, such as Digital PCS, by using a classical dual-mode mobile. But with the introduction of software radio concept to the RF circuit design, it would also be possible for multi standards.

The primary event that triggered the need for intelligent roaming was the opening of the various frequency bands and standards for cellular service, cordless service and the wireless local area network (wireless LAN), which are possible at 800MHz, 900MHz, 1800MHz, 1900MHz, 2.4GHz or 5GHz bands. Also, the development of multi-band, re-configurable multi-mode mobile stations urges this feature.

There are two basic ways of providing intelligent roaming to mobile users: network-directed and mobile-directed. In *network-directed intelligent roaming*, the MS finds a universal pilot channel on one of the available bands and signaling is used to direct the mobile to the most appropriate band and system for it to obtain service in the area. In *mobile-directed intelligent roaming*, the mobile has all the information necessary to decide which band to operate on in any given area. Both air interface and intersystem signaling are required for network-directed

intelligent roaming. Which method should be adopted? Both. (*Now, many research works have proved that a SDR radio system is realizable, but the most difficult part to put these ideas into commercial is the implementation of a multi-function DSP, that is the hardware implementation issue*).

### **3.2.2 Calculation of the Transition Probability for the State Diagram**

#### **3.2.2.1 Transition Probabilities**

In the state diagram shown in Figure 3.3, each transition of the diagram has been labeled with the probability of occurrence of the transition. The transition probabilities  $\epsilon_{ij}$  are the forward transition probabilities of successfully passing from state  $S_i$  to the next state  $S_j$ ;  $\epsilon_i$  are the backward transition probabilities of state  $S_i$ ;  $\gamma_{ik}$  are the transition probabilities from state  $S_i$  returned to state  $S_k$  when the MS fails to reach the next state.

The transition probabilities  $\gamma_{ik} = 1$  or  $0$  are decided by the prior choice of one out of different scenarios, while the transition probabilities  $\epsilon_i$ ,  $\epsilon_{ij}$  are calculated from the universal base station resource blocking probability  $P_{s_u}$ , the classical base station resource blocking probability  $P_{s_c}$ , and the mobile station resource blocking probability  $P_{m_i}$ . Where:  $P_{s_u}$  is the probability of universal base station resource blocking such that the mobile station (MS) cannot be assigned a pilot or data channel for signaling or downloading;  $P_{s_c}$  is the probability of classical base station resource blocking such that the MS cannot be assigned a control or traffic channel for signaling and communication;  $P_{m_i}$  is the probability of the MS resource is blocking in state  $S_i$ , e.g, the memory size is not enough for downloading the new system software, or the battery level is low.

The initial transition probabilities  $\epsilon_{01}$ ,  $\epsilon_{02}$ ,  $\epsilon_{03}$  have been discussed in the previous section (See Page 44 - 45). The remaining transition probabilities are defined according to the following formulas. In these formulas, we assume that the resource blocking probabilities of the universal cellular base station and the universal wireless LAN base station in each state are the same, denoted as  $P_{s_u}$ , the resource blocking probabilities of the mobile station in each state are the same, denoted as  $P_m$ .

$$\epsilon_{01} + \epsilon_{02} + \epsilon_{03} = 1$$

$$\epsilon_{14} = (1 - P_{s_u}) * (1 - P_m)$$

$$\epsilon_1 = 1 - \epsilon_{14}$$

$$\epsilon_{25} = (1 - P_{s_u}) * (1 - P_m)$$

$$\epsilon_{20} = 1 - \epsilon_{25}$$

$$\epsilon_{36} = (1 - P_{s_c}) * (1 - P_m)$$

$$\epsilon_{30} = 1 - \epsilon_{36}$$

$$\epsilon_{47} = (1 - P_{s_u}) * (1 - P_m)$$

$$\epsilon_4 = 1 - \epsilon_{47}$$

$$\gamma_{41} + \gamma_{42} = 1$$

$$\epsilon_{58} = (1 - P_{s_u}) * (1 - P_m)$$

$$\epsilon_5 = 1 - \epsilon_{58}$$

$$\gamma_{51} + \gamma_{52} = 1$$

$$\epsilon_{69} = (1 - P_{s_c}) * (1 - P_m)$$

$$\epsilon_6 = 1 - \epsilon_{69}$$

$$\gamma_{61} + \gamma_{62} = 1$$

$$\epsilon_{7,10} = (1 - P_{s_u}) * (1 - P_m)$$

$$\epsilon_7 = 1 - \epsilon_{7,10}$$

$$\gamma_{71} + \gamma_{72} + \gamma_{73} = 1$$

$$\epsilon_{8,11} = (1 - P_{s_u}) * (1 - P_m)$$

$$\epsilon_8 = 1 - \epsilon_{8,11}$$

$$\gamma_{81} + \gamma_{82} + \gamma_{83} = 1$$

$$\epsilon_{9,12} = (1 - P_{s_c}) * (1 - P_m)$$

$$\epsilon_9 = 1 - \epsilon_{9,12}$$

$$\gamma_{91} + \gamma_{92} + \gamma_{93} = 1$$

$$\epsilon_{10,12} = (1 - P_{s_c}) * (1 - P_m)$$

$$\epsilon_{10} = 1 - \epsilon_{10,12}$$

$$\gamma_{10,1} + \gamma_{10,2} + \gamma_{10,3} + \gamma_{10,4} = 1$$

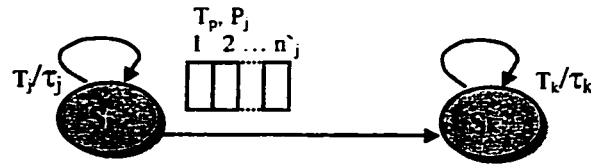
$$\epsilon_{11,12} = (1 - P_{s_c}) * (1 - P_m)$$

$$\epsilon_{11} = 1 - \epsilon_{11,12}$$

$$\gamma_{11,1} + \gamma_{11,2} + \gamma_{11,3} + \gamma_{11,4} = 1$$

### 3.2.2.2 Total Time in Each State

It is certain that the total time required in each state is related to the transmission bit error rate and the minimum time spent in that state. Assuming that the signaling data and the system software code are transmitted in forms of packets, then we can use packet successful transmission probability to reflect the transmission bit error rate. In the following discuss, we show the relationship among the total time, the minimum time and the packet successful transmission probability.



**Figure 3.7** Calculation of the Total Time in Each State

In Figure 3.7, we denote  $T_j$  as the minimum time required to transmit and receive the packets in state  $S_j$ ,  $\Delta T_j$  as the increased time in  $T_j$  due to channel packet error. Then, the total time required for the packets transmission in each state due to error will be the sum of the minimum time  $T_j$  and the retransmission time for the failure channel packets  $\Delta T_j$ , denoted by  $\tau_j$ .

Thus, if the transmission time for one packet is  $T_p$ , then the minimum number of the required transmission packets in state  $S_j$ , let's denote it as  $n_j$ , will equal to the quotient of the minimum required time  $T_j$  divided by one packet time  $T_p$  when the remainder is zero and will equal to the quotient +1 when the remainder is not zero, i.e.  $n_j = \lfloor T_j/T_p \rfloor$

Also, we denote  $P_j$  as the successful packet transmission probability in state  $S_j$ ,  $k$  (maximum  $n_j$ ) as the number of failure deliver packets due to errors. Then, the number of failure deliver packets  $k$  has the “Binomial probability density function” [20]

$$P(k) = \binom{n_j}{k} (1-P_j)^k P_j^{(n_j-k)}, \quad \text{for } k = 0, 1, 2, 3, \dots, n_j$$

With mean:  $E[k] = n_j * (1-P_j)$ ,

Furthermore, let  $i$  represents the extra retransmission times for one failed transmitted packets, then  $i$  has the “Geometric probability density function” [20]

$$P(i) = (1-P_j)^i P_j \quad \text{for } i = 0, 1, 2, 3, \dots$$

$$\text{Such that } \sum_{i=0}^{\infty} (1-P_j)^i P_j = 1, \quad (3.1)$$

Differentiating both sides of the equation (3.1) with respect to  $P_j$  and simplifying gives

$$\sum_{i=1}^{\infty} i (1-P_j)^{i-1} P_j = 1/P_j, \text{ or } \sum_{i=0}^{\infty} i (1-P_j)^i P_j = (1-P_j)/P_j$$

$$\text{The mean of } i: E[i] = \sum_i i P(i) = (1-P_j)/P_j$$

Finally, since the number of failed packets due to errors  $k$  and the retransmission times for one failure transmitted packets  $i$  are independent, we obtain the mean number of increased packets needed to transmit due to error:

$$\begin{aligned} \overline{\Delta n_j(i,k)} &= \sum_i \sum_k k P(k) (1 + i P(i)) \\ &= E[k] * (1 + E[i]) = n_j * (1-P_j)/P_j \end{aligned}$$

Hence, the total number of transmitted packets in state  $S_j$  is:

$$n_j = n_j + \overline{\Delta n_j(i,k)} = n_j * [1 + (1-P_j)/P_j] = n_j/P_j$$

The total time spent in state  $S_j$  is:

$$\begin{aligned} \tau_j &= n_j T_p = [n_j + \overline{\Delta n_j(i,k)}] T_p \\ &= (T_p * n_j)/P_j \\ &= T_j/P_j \end{aligned} \quad \text{for } j = 1, 2, \dots, 11 \quad (3.2)$$

## Chapter 4 Estimation of the Roaming Acquisition Time

### 4.1 Transition Function and Roaming Connection Establishment Acquisition Time

#### 4.1.1 Roaming Connection Establishment Acquisition Time

*Roaming acquisition time* is the necessary time for the mobile station (MS) to roam from one wireless standard to another. During this period, the MS maybe handoff to the same system or the need may arise to download new system software for the roaming. With the state diagram shown in Figure 3.3, the mobile station roaming connection acquisition time is the average acquisition time to move from state  $S_0$  to  $S_{12}$ .

In order to find out the mobile station acquisition time (should not be confused with spread spectrum codes acquisition time) from state  $S_0$  to  $S_{12}$ , we apply flow graph technique similar to the one that was first presented by DiCarlo, DiCarlo and Weber[10], where they calculated the mean and standard deviation of the synchronization time for a spread spectrum code serial-search system. The concept of representing all possible paths through a state-transition diagram by a function  $H(z)$  leads to the generalized solution for average acquisition time, this function  $H(z)$  is defined as the *transition function of the state diagram*. The roaming connection acquisition time for a mobile station to proceed from state  $S_0$  to  $S_{12}$  is defined as:

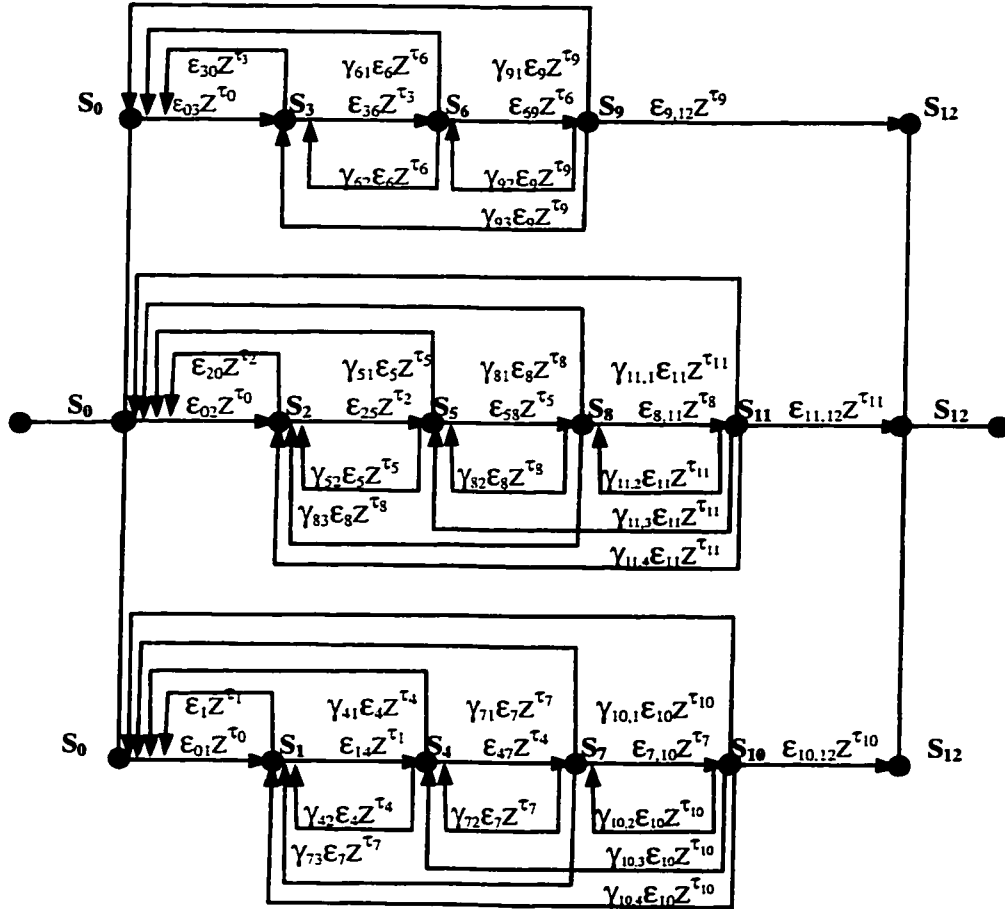
$$T_{sum} = \left. \frac{dH(z)}{dz} \right|_{z=1} \quad (4.1)$$

#### 4.1.2 Transition Function

The state diagram in Figure 3.3 can be represented by a signal-flow graph as shown in Figure 4.1(a),(b). In this figure, each transition branch of the diagram has been labeled with the probability of occurrence of the transition and  $Z$  raised to a power equal to the total time



associated with the 'from' state. The transition probabilities  $\epsilon_{ij}$  are the probabilities of moving from state  $S_i$  to state  $S_j$ , and the parameter  $Z$  is used to mark time as one proceeds through the graph and its power represents the total time spent in traversing that branch.



**Figure 4.1(a)** A Signal Flow Graph I

To calculate the transition function of the state diagram, there are two basic techniques, block diagram reduction technique and signal flow graph gain formula. Block diagrams are adequate for the representation of the interrelationships of controlled and input variables. However, for a system with reasonably complex interrelationships, such as a mobile station having the state diagram shown in Figure 3.3, the block diagram reduction technique is often quite difficult. The signal-flow graph gain formula provides a reasonably straightforward approach for the

evaluation of complicated systems. Therefore, a flow graph gain formula developed by Mason is adopted here. The transition function can be determined by considering the state diagram as a signal flow graph and applying Mason's formula [21].

A signal-flow graph is a diagram consisting of nodes that are connected by several directed branches and is a graphical representation of a set of linear relations. The basic element of a signal-flow graph is a unidirectional path segment called a *branch*. The gain of each branch is marked in the simplified flow graph Figure 4.1(a). In a signal flow graph, a path connecting the initial state (node) to the final state (node) which does not go through any state twice is called a *forward path*. Let  $F_i$  be the gain of the  $i$ th forward path. A closed path starting at any state and returning to that state without going through any other state twice is called a *loop*. Let  $C_i$  be the gain of the  $i$ th loop. A set of loops is *nontouching* if no state belongs to more than one loop in in the set. Two touching loops share one or more common states (nodes). Then define:

$$\begin{aligned} \text{Determinant of the graph } \Delta &= 1 - (\text{sum of all different loop gains}) + (\text{sum of the gain products of all} \\ &\quad \text{combinations of 2 nontouching loops}) - (\text{sum of the gain products} \\ &\quad \text{of all combinations of 3 nontouching loops}) + \dots \\ &= 1 - \sum_i C_i + \sum_{j,k} C_j C_k - \sum_{l,m,n} C_l C_m C_n + \dots \end{aligned}$$

Forward path gain  $F_i$  is defined as the continuous succession of branches that are traversed in the direction of the arrows and with no node encountered more than once.

Cofactor of the path  $F_i$ ,  $\Delta_i$  is defined exactly like  $\Delta$ , but only for that portion of the graph not touching the  $i$ th forward path; that is, all states along the  $i$ th forward path, together with all branches connected to these states, are removed from the graph when computing  $\Delta_i$ .

Mason's formula for computing the transition function  $H(z)$  of a graph can now be stated as:

$$H(z) = \frac{\sum_i F_i \Delta_i}{\Delta} \quad (4.2)$$

By applying this theory to the signal flow diagram shown in Figure 4.1(a), we can obtain a simplified flow graph shown in Figure 4.1(b)

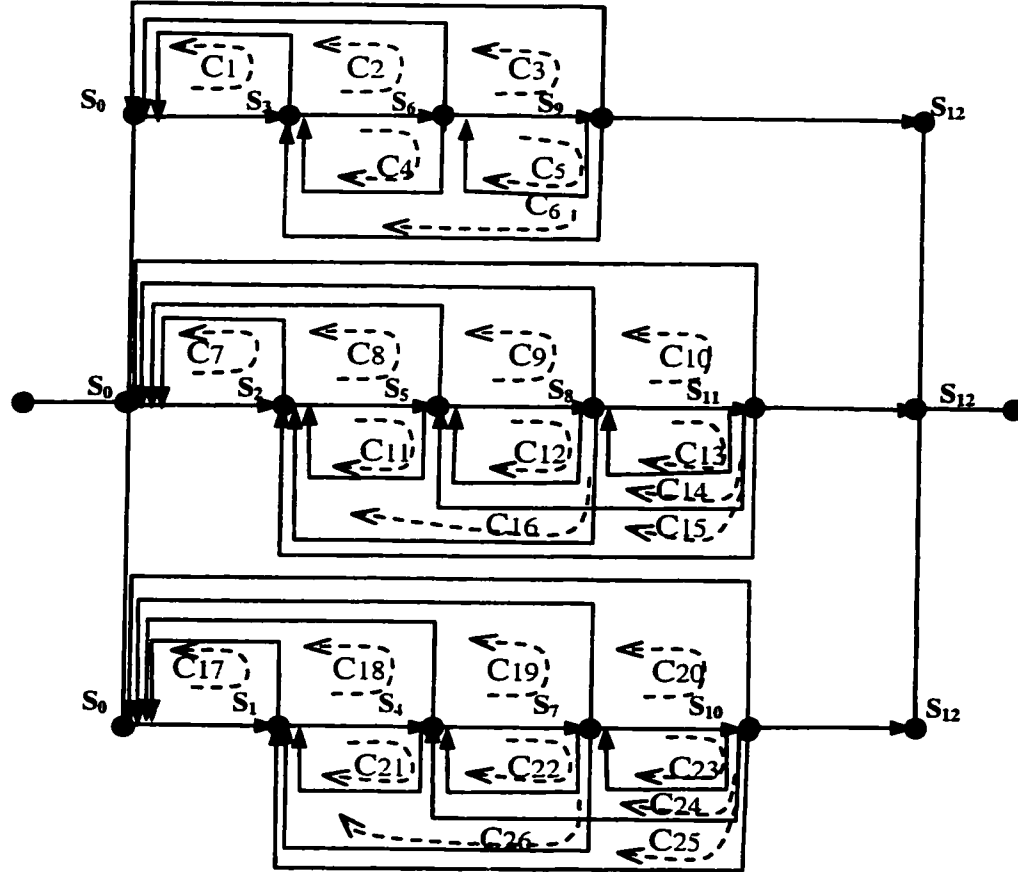


Figure 4.1(b) A Simplified Flow Graph II

There are 26 self-loops in the state diagram:

$$C_1 = \epsilon_{30}\epsilon_{03}Z^{\tau_0+\tau_3}$$

$$C_3 = \gamma_{91}\epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}Z^{\tau_0+\tau_3+\tau_6+\tau_9}$$

$$C_5 = \gamma_{92}\epsilon_9\epsilon_{69}Z^{\tau_6+\tau_9}$$

$$C_7 = \epsilon_{20}\epsilon_{02}Z^{\tau_0+\tau_2}$$

$$C_9 = \gamma_{81}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58}Z^{\tau_0+\tau_2+\tau_5+\tau_8}$$

$$C_{11} = \gamma_{52}\epsilon_5\epsilon_{25}Z^{\tau_2+\tau_5}$$

$$C_2 = \gamma_{61}\epsilon_6\epsilon_{03}\epsilon_{36}Z^{\tau_0+\tau_3+\tau_6}$$

$$C_4 = \gamma_{62}\epsilon_6\epsilon_{36}Z^{\tau_3+\tau_6}$$

$$C_6 = \gamma_{93}\epsilon_9\epsilon_{36}\epsilon_{69}Z^{\tau_3+\tau_6+\tau_9}$$

$$C_8 = \gamma_{51}\epsilon_5\epsilon_{02}\epsilon_{25}Z^{\tau_0+\tau_2+\tau_5}$$

$$C_{10} = \gamma_{11,1}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}}$$

$$C_{12} = \gamma_{82}\epsilon_8\epsilon_{58}Z^{\tau_5+\tau_8}$$

$$\begin{aligned}
C_{13} &= \gamma_{11,2} \epsilon_{11} \epsilon_{8,11} Z^{\tau_8 + \tau_{11}} \\
C_{15} &= \gamma_{11,4} \epsilon_{11} \epsilon_{25} \epsilon_{58} \epsilon_{8,11} Z^{\tau_2 + \tau_5 + \tau_8 + \tau_{11}} \\
C_{17} &= \epsilon_1 \epsilon_{01} Z^{\tau_0 + \tau_1} \\
C_{19} &= \gamma_{71} \epsilon_7 \epsilon_{01} \epsilon_{14} \epsilon_{47} Z^{\tau_0 + \tau_1 + \tau_4 + \tau_7} \\
C_{21} &= \gamma_{42} \epsilon_4 \epsilon_{14} Z^{\tau_1 + \tau_4} \\
C_{23} &= \gamma_{10,2} \epsilon_{10} \epsilon_{7,10} Z^{\tau_7 + \tau_{10}} \\
C_{25} &= \gamma_{10,4} \epsilon_{10} \epsilon_{14} \epsilon_{47} \epsilon_{7,10} Z^{\tau_1 + \tau_4 + \tau_7 + \tau_{10}}
\end{aligned}$$

$$\begin{aligned}
C_{14} &= \gamma_{11,3} \epsilon_{11} \epsilon_{8,11} \epsilon_{58} Z^{\tau_5 + \tau_8 + \tau_{11}} \\
C_{16} &= \gamma_{8,3} \epsilon_8 \epsilon_{25} \epsilon_{58} Z^{\tau_2 + \tau_5 + \tau_8} \\
C_{18} &= \gamma_{41} \epsilon_4 \epsilon_{01} \epsilon_{14} Z^{\tau_0 + \tau_1 + \tau_4} \\
C_{20} &= \gamma_{10,1} \epsilon_{10} \epsilon_{01} \epsilon_{14} \epsilon_{47} \epsilon_{7,10} Z^{\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10}} \\
C_{22} &= \gamma_{72} \epsilon_7 \epsilon_{47} Z^{\tau_4 + \tau_7} \\
C_{24} &= \gamma_{10,3} \epsilon_{10} \epsilon_{7,10} \epsilon_{47} Z^{\tau_4 + \tau_7 + \tau_{10}} \\
C_{26} &= \gamma_{7,3} \epsilon_7 \epsilon_{14} \epsilon_{47} Z^{\tau_1 + \tau_4 + \tau_7}
\end{aligned}$$

At the end of this section, we present the generalized form of acquisition time calculation result of three specific events, in which the mobile station is 100% certain to take one of the path1, path2, or path3 while ignoring the other paths. This may happen when the mobile station is set in preferred mode, together with the universal base station or classical base station resource is available, which has been discussed in Section 3.1.1.2-3. In these events, the acquisition time in different scenarios can be obtained by substituting their corresponding  $\gamma_{ij}$  values to the generalized form of the acquisition time.

**Event 1:** If the initial transition probability distributions of path1, 2, 3 are  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 0/0/1$ , i.e., the transition is made to  $S_3$  in path3, then  $H(z)$  equals to the path3 transition function.

There are 6 self-loops:

$$\begin{aligned}
C_1 &= \epsilon_{30} \epsilon_{03} Z^{\tau_0 + \tau_3} & C_2 &= \gamma_{61} \epsilon_6 \epsilon_{03} \epsilon_{36} Z^{\tau_0 + \tau_3 + \tau_6} \\
C_3 &= \gamma_{91} \epsilon_9 \epsilon_{03} \epsilon_{36} \epsilon_{69} Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9} & C_4 &= \gamma_{62} \epsilon_6 \epsilon_{36} Z^{\tau_3 + \tau_6} \\
C_5 &= \gamma_{92} \epsilon_9 \epsilon_{69} Z^{\tau_6 + \tau_9} & C_6 &= \gamma_{93} \epsilon_9 \epsilon_{36} \epsilon_{69} Z^{\tau_3 + \tau_6 + \tau_9}
\end{aligned}$$

There is 1 pair of nontouching loop:

$$C_1 C_5 = \gamma_{92} \epsilon_9 \epsilon_{69} \epsilon_{30} \epsilon_{03} Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9}$$

Thus,

$$\Delta = 1 - \sum_{i=1}^6 C_i + C_1 C_5 = 1 - \epsilon_{30} \epsilon_{03} Z^{\tau_0 + \tau_3} - \gamma_{61} \epsilon_6 \epsilon_{03} \epsilon_{36} Z^{\tau_0 + \tau_3 + \tau_6} - \gamma_{62} \epsilon_6 \epsilon_{36} Z^{\tau_3 + \tau_6} - \gamma_{91} \epsilon_9 \epsilon_{03} \epsilon_{36} \epsilon_{69} Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9} - \gamma_{92} \epsilon_9 \epsilon_{69} Z^{\tau_6 + \tau_9} - \gamma_{93} \epsilon_9 \epsilon_{36} \epsilon_{69} Z^{\tau_3 + \tau_6 + \tau_9} + \gamma_{92} \epsilon_9 \epsilon_{69} \epsilon_{30} \epsilon_{03} Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9}$$

There is only one forward path:  $F_1 = \epsilon_{03} \epsilon_{36} \epsilon_{69} \epsilon_{9,12} Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9}$ ,  $\Delta_1 = 1$ ,  $F(z) = F_1 * \Delta_1$

$$H(z) = \frac{F(z)}{\Delta} = \frac{\epsilon_{03} \epsilon_{36} \epsilon_{69} \epsilon_{9,12} Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9}}{\Delta}$$

$$\frac{dH(z)}{dz} = \frac{F'(z)}{\Delta(z)} - \frac{F(z) * \Delta'(z)}{\Delta^2(z)}$$

Where:

$$F(z) = \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12} * (\tau_0 + \tau_3 + \tau_6 + \tau_9) Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9 - 1}$$

$$\Delta^-(z) = \frac{-\epsilon_{30}\epsilon_{03} * (\tau_0 + \tau_3) Z^{\tau_0 + \tau_3 - 1} - \gamma_{61}\epsilon_6\epsilon_{03}\epsilon_{36} * (\tau_0 + \tau_3 + \tau_6) Z^{\tau_0 + \tau_3 + \tau_6 - 1} - \gamma_{62}\epsilon_6\epsilon_{36} * (\tau_3 + \tau_6) Z^{\tau_3 + \tau_6 - 1} - \gamma_{91}\epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69} * (\tau_0 + \tau_3 + \tau_6 + \tau_9) Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9 - 1} - \gamma_{92}\epsilon_9\epsilon_{69} * (\tau_6 + \tau_9) Z^{\tau_6 + \tau_9 - 1} - \gamma_{93}\epsilon_9\epsilon_{36}\epsilon_{69} * (\tau_3 + \tau_6 + \tau_9) Z^{\tau_3 + \tau_6 + \tau_9 - 1} + \gamma_{92}\epsilon_9\epsilon_{69}\epsilon_{30}\epsilon_{03} * (\tau_0 + \tau_3 + \tau_6 + \tau_9) Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9 - 1}}$$

The acquisition time from  $S_0$  to  $S_{12}$  can be found by setting  $z = 1$  in  $dH(z)/dz$ , then we get

$$T_{sum} = \left. \frac{dH(z)}{dz} \right|_{z=1} = N_1/M_1 + N_2/M_1^2 \quad (4.3)$$

where :

$$N_1 = F(z) \Big|_{z=1} = \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12} * (\tau_0 + \tau_3 + \tau_6 + \tau_9)$$

$$N_2 = -F(z) * \Delta^-(z) \Big|_{z=1} = -\epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12} * [-\epsilon_{30}\epsilon_{03} * (\tau_0 + \tau_3) - \gamma_{61}\epsilon_6\epsilon_{03}\epsilon_{36} * (\tau_0 + \tau_3 + \tau_6) - \gamma_{62}\epsilon_6\epsilon_{36} * (\tau_0 + \tau_3) - \gamma_{91}\epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69} * (\tau_0 + \tau_3 + \tau_6 + \tau_9) - \gamma_{92}\epsilon_9\epsilon_{69} * (\tau_6 + \tau_9) - \gamma_{93}\epsilon_9\epsilon_{36}\epsilon_{69} * (\tau_3 + \tau_6 + \tau_9) + \gamma_{92}\epsilon_9\epsilon_{69}\epsilon_{30}\epsilon_{03} * (\tau_0 + \tau_3 + \tau_6 + \tau_9)]$$

$$M_1 = \Delta(z) \Big|_{z=1} = 1 - \epsilon_{30}\epsilon_{03} - \gamma_{61}\epsilon_6\epsilon_{03}\epsilon_{36} - \gamma_{62}\epsilon_6\epsilon_{36} - \gamma_{91}\epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69} - \gamma_{92}\epsilon_9\epsilon_{69} - \gamma_{93}\epsilon_9\epsilon_{36}\epsilon_{69} + \gamma_{92}\epsilon_9\epsilon_{69}\epsilon_{30}\epsilon_{03}$$

**Event 2:** If the initial transition probability distributions of path1, 2, 3 are  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 0/1/0$ , i.e,

the transition is made to  $S_2$  in path2, then  $H(z)$  equals to the path2 transition function.

There are 10 self-loops:

$$C_7 = \epsilon_{20}\epsilon_{02} Z^{\tau_0 + \tau_2}$$

$$C_9 = \gamma_{81}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8}$$

$$C_{11} = \gamma_{52}\epsilon_5\epsilon_{25} Z^{\tau_2 + \tau_5}$$

$$C_{13} = \gamma_{11,2}\epsilon_{11}\epsilon_{8,11} Z^{\tau_8 + \tau_{11}}$$

$$C_{15} = \gamma_{11,4}\epsilon_{11}\epsilon_{25}\epsilon_{58}\epsilon_{8,11} Z^{\tau_2 + \tau_5 + \tau_8 + \tau_{11}}$$

$$C_8 = \gamma_{51}\epsilon_5\epsilon_{02}\epsilon_{25} Z^{\tau_0 + \tau_2 + \tau_5}$$

$$C_{10} = \gamma_{11,1}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}}$$

$$C_{12} = \gamma_{82}\epsilon_8\epsilon_{58} Z^{\tau_5 + \tau_8}$$

$$C_{14} = \gamma_{11,3}\epsilon_{11}\epsilon_{8,11}\epsilon_{58} Z^{\tau_5 + \tau_8 + \tau_{11}}$$

$$C_{16} = \gamma_{8,3}\epsilon_8\epsilon_{25}\epsilon_{58} Z^{\tau_2 + \tau_5 + \tau_8}$$

There are 5 groups of nontouching loop:

$$C_7 C_{12} = \gamma_{82}\epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8}$$

$$C_7 C_{13} = \gamma_{11,2}\epsilon_{20}\epsilon_{02}\epsilon_{11}\epsilon_{8,11} Z^{\tau_0 + \tau_2 + \tau_8 + \tau_{11}}$$

$$C_7 C_{14} = \gamma_{11,3}\epsilon_{11}\epsilon_{8,11}\epsilon_{58}\epsilon_{20}\epsilon_{02} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}}$$

$$C_8 C_{13} = \gamma_{51}\gamma_{11,2}\epsilon_{11}\epsilon_{8,11}\epsilon_5\epsilon_{02}\epsilon_{25} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}}$$

$$C_{11} C_{13} = \gamma_{52}\gamma_{11,2}\epsilon_{11}\epsilon_{8,11}\epsilon_5\epsilon_{25} Z^{\tau_2 + \tau_5 + \tau_8 + \tau_{11}}$$

Thus,

$$\Delta = 1 - \sum_{i=7}^{16} C_i + \sum_{i=12}^{14} C_7 C_i + C_8 C_{13} = 1 - \epsilon_{20}\epsilon_{02} Z^{\tau_0 + \tau_2} - \gamma_{51}\epsilon_5\epsilon_{02}\epsilon_{25} Z^{\tau_0 + \tau_2 + \tau_5} - \gamma_{52}\epsilon_5\epsilon_{25} Z^{\tau_2 + \tau_5} - \gamma_{81}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8} - \gamma_{82}\epsilon_8\epsilon_{58} Z^{\tau_5 + \tau_8} - \gamma_{8,3}\epsilon_8\epsilon_{25}\epsilon_{58} Z^{\tau_2 + \tau_5 + \tau_8} - \gamma_{11,1}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}} - \gamma_{11,2}\epsilon_{11}\epsilon_{8,11} Z^{\tau_8 + \tau_{11}} - \gamma_{11,3}\epsilon_{11}\epsilon_{8,11}\epsilon_{58} Z^{\tau_5 + \tau_8 + \tau_{11}} - \gamma_{11,4}\epsilon_{11}\epsilon_{25}\epsilon_{58}\epsilon_{8,11} Z^{\tau_2 + \tau_5 + \tau_8 + \tau_{11}} + \gamma_{82}\epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8} + \gamma_{11,2}\epsilon_{20}\epsilon_{02}\epsilon_{11}\epsilon_{8,11} Z^{\tau_0 + \tau_2 + \tau_8 + \tau_{11}} + \gamma_{11,3}\epsilon_{11}\epsilon_{8,11}\epsilon_{58}\epsilon_{20}\epsilon_{02} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}} + \gamma_{51}\gamma_{11,2}\epsilon_{11}\epsilon_{8,11}\epsilon_5\epsilon_{02}\epsilon_{25} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}} + \gamma_{52}\gamma_{11,2}\epsilon_{11}\epsilon_{8,11}\epsilon_5\epsilon_{25} Z^{\tau_2 + \tau_5 + \tau_8 + \tau_{11}}$$

Forward path :  $F_2 = \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}}$ ,  $\Delta_2 = 1$ ,  $F(z) = F_2 \Delta_2$

$$H(z) = \frac{F(z)}{\Delta} = \frac{\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12} Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}}}{\Delta}$$

$$\frac{dH(z)}{dz} = \frac{F(z)}{\Delta(z)} - \frac{F(z)*\Delta'(z)}{\Delta^2(z)}$$

Where:

$$F(z) = \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11}\epsilon_{11.12}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11})Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1}$$

$$\begin{aligned} \Delta'(z) = & -\epsilon_{20}\epsilon_{02}*(\tau_0+\tau_2)Z^{\tau_0+\tau_2-1} - \gamma_{51}\epsilon_5\epsilon_{02}\epsilon_{25}*(\tau_0+\tau_2+\tau_5)Z^{\tau_0+\tau_2+\tau_5-1} - \gamma_{52}\epsilon_5\epsilon_{25}*(\tau_2+\tau_5)Z^{\tau_2+\tau_5-1} - \gamma_{81}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58}*(\tau_0+\tau_2+\tau_5+\tau_8) \\ & *Z^{\tau_0+\tau_2+\tau_5+\tau_8-1} - \gamma_{82}\epsilon_8\epsilon_{58}*(\tau_5+\tau_8)Z^{\tau_5+\tau_8-1} - \gamma_{8.3}\epsilon_8\epsilon_{25}\epsilon_{58}*(\tau_2+\tau_5+\tau_8)Z^{\tau_2+\tau_5+\tau_8-1} - \gamma_{11.1}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}) \\ & *Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1} - \gamma_{11.2}\epsilon_{11}\epsilon_{8.11}*(\tau_8+\tau_{11})Z^{\tau_8+\tau_{11}-1} - \gamma_{11.3}\epsilon_{11}\epsilon_{8.11}\epsilon_{58}*(\tau_5+\tau_8+\tau_{11})Z^{\tau_5+\tau_8+\tau_{11}-1} \\ & - \gamma_{11.4}\epsilon_{11}\epsilon_{25}\epsilon_{58}\epsilon_{8.11}*(\tau_2+\tau_5+\tau_8+\tau_{11})Z^{\tau_2+\tau_5+\tau_8+\tau_{11}-1} + \gamma_{82}\epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}*(\tau_0+\tau_2+\tau_5+\tau_8)Z^{\tau_0+\tau_2+\tau_5+\tau_8-1} \\ & + \gamma_{11.2}\epsilon_{20}\epsilon_{02}\epsilon_{11}\epsilon_{8.11}*(\tau_0+\tau_2+\tau_8+\tau_{11})Z^{\tau_0+\tau_2+\tau_8+\tau_{11}-1} + \gamma_{11.3}\epsilon_{11}\epsilon_{8.11}\epsilon_{58}\epsilon_{20}\epsilon_{02}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11})Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1} \\ & + \gamma_{51}\gamma_{11.2}\epsilon_{11}\epsilon_{8.11}\epsilon_5\epsilon_{02}\epsilon_{25}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11})Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1} + \gamma_{52}\gamma_{11.2}\epsilon_{11}\epsilon_{8.11}\epsilon_5\epsilon_{25}*(\tau_2+\tau_5+\tau_8+\tau_{11})Z^{\tau_2+\tau_5+\tau_8+\tau_{11}-1} \end{aligned}$$

The acquisition time from  $S_0$  to  $S_{12}$  can be found by setting  $z=1$  in  $dH(z)/dz$ , then we get

$$T_{sum} = \left. \frac{dH(z)}{dz} \right|_{z=1} = N_1/M_1 + N_2/M_1^2 \quad (4.4)$$

where :

$$N_1 = F(z) \Big|_{z=1} = \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11}\epsilon_{11.12}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11})$$

$$\begin{aligned} N_2 = -F(z)*\Delta'(z) \Big|_{z=1} = & -\epsilon_{25}\epsilon_{58}\epsilon_{8.11}\epsilon_{11.12}*[ -\epsilon_{20}\epsilon_{02}*(\tau_0+\tau_2) - \gamma_{51}\epsilon_5\epsilon_{02}\epsilon_{25}*(\tau_0+\tau_2+\tau_5) - \gamma_{52}\epsilon_5\epsilon_{25}*(\tau_2+\tau_5) \\ & - \gamma_{81}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58}*(\tau_0+\tau_2+\tau_5+\tau_8) - \gamma_{82}\epsilon_8\epsilon_{58}*(\tau_5+\tau_8) - \gamma_{8.3}\epsilon_8\epsilon_{25}\epsilon_{58}*(\tau_2+\tau_5+\tau_8) - \gamma_{11.1}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}) \\ & - \gamma_{11.2}\epsilon_{11}\epsilon_{8.11}*(\tau_8+\tau_{11}) - \gamma_{11.3}\epsilon_{11}\epsilon_{8.11}\epsilon_{58}*(\tau_5+\tau_8+\tau_{11}) - \gamma_{11.4}\epsilon_{11}\epsilon_{25}\epsilon_{58}\epsilon_{8.11}*(\tau_2+\tau_5+\tau_8+\tau_{11}) + \gamma_{82}\epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}*(\tau_0+\tau_2+\tau_5+\tau_8) \\ & + \gamma_{11.2}\epsilon_{20}\epsilon_{02}\epsilon_{11}\epsilon_{8.11}*(\tau_0+\tau_2+\tau_8+\tau_{11}) + \gamma_{11.3}\epsilon_{11}\epsilon_{8.11}\epsilon_{58}\epsilon_{20}\epsilon_{02}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}) + \gamma_{51}\gamma_{11.2}\epsilon_{11}\epsilon_{8.11}\epsilon_5\epsilon_{02}\epsilon_{25}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}) \\ & + \gamma_{52}\gamma_{11.2}\epsilon_{11}\epsilon_{8.11}\epsilon_5\epsilon_{25}*(\tau_2+\tau_5+\tau_8+\tau_{11})] \end{aligned}$$

$$\begin{aligned} M_1 = \Delta(z) \Big|_{z=1} = & 1 - \epsilon_{20}\epsilon_{02} - \gamma_{51}\epsilon_5\epsilon_{02}\epsilon_{25} - \gamma_{52}\epsilon_5\epsilon_{25} - \gamma_{81}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} - \gamma_{82}\epsilon_8\epsilon_{58} - \gamma_{8.3}\epsilon_8\epsilon_{25}\epsilon_{58} - \gamma_{11.1}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11} - \gamma_{11.2}\epsilon_{11}\epsilon_{8.11} \\ & - \gamma_{11.3}\epsilon_{11}\epsilon_{8.11}\epsilon_{58} - \gamma_{11.4}\epsilon_{11}\epsilon_{25}\epsilon_{58}\epsilon_{8.11} + \gamma_{82}\epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02} + \gamma_{11.2}\epsilon_{20}\epsilon_{02}\epsilon_{11}\epsilon_{8.11} + \gamma_{11.3}\epsilon_{11}\epsilon_{8.11}\epsilon_{58}\epsilon_{20}\epsilon_{02} + \gamma_{51}\gamma_{11.2}\epsilon_{11}\epsilon_{8.11}\epsilon_5\epsilon_{02}\epsilon_{25} \\ & + \gamma_{52}\gamma_{11.2}\epsilon_{11}\epsilon_{8.11}\epsilon_5\epsilon_{25} \end{aligned}$$

**Event 3:** If the transition probability distributions of path1, 2, 3 are  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ , i.e, the transition is made to  $S_1$  in path1, then  $H(z)$  equals to the path1 transition function.

There are 10 self-loops:

$$\begin{aligned} C_{17} &= \epsilon_1\epsilon_{01}Z^{\tau_0+\tau_1} \\ C_{19} &= \gamma_{71}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47}Z^{\tau_0+\tau_1+\tau_4+\tau_7} \\ C_{21} &= \gamma_{42}\epsilon_4\epsilon_{14}Z^{\tau_1+\tau_4} \\ C_{23} &= \gamma_{10.2}\epsilon_{10}\epsilon_{7.10}Z^{\tau_7+\tau_{10}} \\ C_{25} &= \gamma_{10.4}\epsilon_{10}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}Z^{\tau_1+\tau_4+\tau_7+\tau_{10}} \\ C_{18} &= \gamma_{41}\epsilon_4\epsilon_{01}\epsilon_{14}Z^{\tau_0+\tau_1+\tau_4} \\ C_{20} &= \gamma_{10.1}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}} \\ C_{22} &= \gamma_{72}\epsilon_7\epsilon_{47}Z^{\tau_4+\tau_7} \\ C_{24} &= \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47}Z^{\tau_4+\tau_7+\tau_{10}} \\ C_{26} &= \gamma_{7.3}\epsilon_7\epsilon_{14}\epsilon_{47}Z^{\tau_1+\tau_4+\tau_7} \end{aligned}$$

There are 5 groups of nontouching loop:

$$\begin{aligned} C_{17}C_{22} &= \gamma_{72}\epsilon_7\epsilon_{47}\epsilon_1\epsilon_{01}Z^{\tau_0+\tau_1+\tau_4+\tau_7} \\ C_{17}C_{23} &= \gamma_{10.2}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7.10}Z^{\tau_0+\tau_1+\tau_7+\tau_{10}} \\ C_{17}C_{24} &= \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47}\epsilon_1\epsilon_{01}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}} \end{aligned}$$

$$C_{18}C_{23} = \gamma_{41}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{01}\epsilon_{14}Z^{20+\tau_1-\tau_4+\tau_7+\tau_{10}}$$

$$C_{21}C_{23} = \gamma_{42}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{14}Z^{21+\tau_4+\tau_7+\tau_{10}}$$

Thus,

$$\Delta = 1 - \sum_{i=17}^{26} C_i + \sum_{i=22}^{24} C_{17}C_i + C_{18}C_{23} = 1 - \epsilon_1\epsilon_{01}Z^{20+\tau_1} - \gamma_{41}\epsilon_4\epsilon_{01}\epsilon_{14}Z^{20+\tau_1-\tau_4} - \gamma_{42}\epsilon_4\epsilon_{14}Z^{21+\tau_4}$$

$$- \gamma_{71}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47}Z^{20+\tau_1+\tau_4+\tau_7} - \gamma_{72}\epsilon_7\epsilon_{47}Z^{24+\tau_7} - \gamma_{7.3}\epsilon_7\epsilon_{14}\epsilon_{47}Z^{21+\tau_4+\tau_7} - \gamma_{10.1}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}Z^{20+\tau_1+\tau_4+\tau_7+\tau_{10}} - \gamma_{10.2}\epsilon_{10}\epsilon_{7.10}Z^{27+\tau_{10}}$$

$$- \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47}Z^{24+\tau_7+\tau_{10}} - \gamma_{10.4}\epsilon_{10}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}Z^{21+\tau_4+\tau_7+\tau_{10}} + \gamma_{72}\epsilon_7\epsilon_{47}\epsilon_{14}\epsilon_{01}Z^{20+\tau_1+\tau_4+\tau_7} + \gamma_{10.2}\epsilon_{10}\epsilon_{01}\epsilon_1\epsilon_{7.10}Z^{20+\tau_1+\tau_7+\tau_{10}}$$

$$+ \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47}\epsilon_1\epsilon_{01}Z^{20+\tau_1+\tau_4+\tau_7+\tau_{10}} + \gamma_{41}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{01}\epsilon_{14}Z^{20+\tau_1+\tau_4+\tau_7+\tau_{10}} + \gamma_{42}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{01}\epsilon_{14}Z^{21+\tau_4+\tau_7+\tau_{10}}$$

Forward path :  $F_3 = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}\epsilon_{10.12}Z^{20-\tau_1-\tau_4-\tau_7-\tau_{10}}$ ,  $\Delta_3 = 1$ ,  $F(z) = F_3 * \Delta_3$

$$H(z) = \frac{F(z)}{\Delta} = \frac{\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}\epsilon_{10.12}Z^{20+\tau_1+\tau_4+\tau_7+\tau_{10}}}{\Delta}$$

$$\frac{dH(z)}{dz} = \frac{F'(z)}{\Delta(z)} - \frac{F(z) * \Delta'(z)}{\Delta^2(z)}$$

Where:

$$F'(z) = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}\epsilon_{10.12} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10}) Z^{20+\tau_1+\tau_4+\tau_7+\tau_{10}-1}$$

$$\Delta'(z) = -\epsilon_1\epsilon_{01} * (\tau_0 + \tau_1) Z^{20+\tau_1-1} - \gamma_{41}\epsilon_4\epsilon_{01}\epsilon_{14} * (\tau_0 + \tau_1 + \tau_4) Z^{20+\tau_1+\tau_4-1} - \gamma_{42}\epsilon_4\epsilon_{14} * (\tau_1 + \tau_4) Z^{21+\tau_4-1} - \gamma_{10.2}\epsilon_{10}\epsilon_{7.10} * (\tau_7 + \tau_{10}) Z^{27+\tau_{10}-1}$$

$$- \gamma_{71}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} * (\tau_0 + \tau_1 + \tau_4 + \tau_7) Z^{20+\tau_1+\tau_4+\tau_7-1} - \gamma_{72}\epsilon_7\epsilon_{47} * (\tau_4 + \tau_7) Z^{24+\tau_7-1} - \gamma_{7.3}\epsilon_7\epsilon_{14}\epsilon_{47} * (\tau_1 + \tau_4 + \tau_7) Z^{21+\tau_4+\tau_7-1}$$

$$- \gamma_{10.1}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10}) Z^{20+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47} * (\tau_4 + \tau_7 + \tau_{10}) Z^{24+\tau_7+\tau_{10}-1}$$

$$- \gamma_{10.4}\epsilon_{10}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} * (\tau_1 + \tau_4 + \tau_7 + \tau_{10}) Z^{21+\tau_4+\tau_7+\tau_{10}-1} + \gamma_{72}\epsilon_7\epsilon_{47}\epsilon_1\epsilon_{01} * (\tau_0 + \tau_1 + \tau_4 + \tau_7) Z^{20+\tau_1+\tau_4+\tau_7-1}$$

$$+ \gamma_{10.2}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7.10} * (\tau_0 + \tau_1 + \tau_7 + \tau_{10}) Z^{20+\tau_1+\tau_7+\tau_{10}-1} + \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47}\epsilon_1\epsilon_{01} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10}) Z^{20+\tau_1+\tau_4+\tau_7+\tau_{10}-1}$$

$$+ \gamma_{41}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{01}\epsilon_{14} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10}) Z^{20+\tau_1+\tau_4+\tau_7+\tau_{10}-1} + \gamma_{42}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{14} * (\tau_1 + \tau_4 + \tau_7 + \tau_{10}) Z^{21+\tau_4+\tau_7+\tau_{10}-1}$$

The acquisition time from  $S_0$  to  $S_{12}$  can be found by setting  $z=1$  in  $dH(z)/dz$ , then we get

$$T_{sum} = \left. \frac{dH(z)}{dz} \right|_{z=1} = N_1/M_1 + N_2/M_1^2 \quad (4.5)$$

where :

$$N_1 = F'(z) \Big|_{z=1} = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}\epsilon_{10.12} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})$$

$$N_2 = -F(z) * \Delta'(z) \Big|_{z=1} = -\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10}\epsilon_{10.12} * [-\epsilon_1\epsilon_{01} * (\tau_0 + \tau_1) - \gamma_{41}\epsilon_4\epsilon_{01}\epsilon_{14} * (\tau_0 + \tau_1 + \tau_4) - \gamma_{42}\epsilon_4\epsilon_{14} * (\tau_1 + \tau_4)$$

$$- \gamma_{71}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} * (\tau_0 + \tau_1 + \tau_4 + \tau_7) - \gamma_{72}\epsilon_7\epsilon_{47} * (\tau_4 + \tau_7) - \gamma_{7.3}\epsilon_7\epsilon_{14}\epsilon_{47} * (\tau_1 + \tau_4 + \tau_7) - \gamma_{10.1}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})$$

$$- \gamma_{10.2}\epsilon_{10}\epsilon_{7.10} * (\tau_7 + \tau_{10}) - \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47} * (\tau_4 + \tau_7 + \tau_{10}) - \gamma_{10.4}\epsilon_{10}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} * (\tau_1 + \tau_4 + \tau_7 + \tau_{10}) + \gamma_{72}\epsilon_7\epsilon_{47}\epsilon_1\epsilon_{01} * (\tau_0 + \tau_1 + \tau_4 + \tau_7)$$

$$+ \gamma_{10.2}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7.10} * (\tau_0 + \tau_1 + \tau_7 + \tau_{10}) + \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47}\epsilon_1\epsilon_{01} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10}) + \gamma_{41}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{01}\epsilon_{14} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})$$

$$+ \gamma_{42}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{14} * (\tau_1 + \tau_4 + \tau_7 + \tau_{10})]$$

$$M_1 = \Delta(z) \Big|_{z=1} = 1 - \epsilon_1\epsilon_{01} - \gamma_{41}\epsilon_4\epsilon_{01}\epsilon_{14} - \gamma_{42}\epsilon_4\epsilon_{14} - \gamma_{71}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} - \gamma_{72}\epsilon_7\epsilon_{47} - \gamma_{7.3}\epsilon_7\epsilon_{14}\epsilon_{47} - \gamma_{10.1}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} - \gamma_{10.2}\epsilon_{10}\epsilon_{7.10}$$

$$- \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47} - \gamma_{10.4}\epsilon_{10}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} + \gamma_{72}\epsilon_7\epsilon_{47}\epsilon_1\epsilon_{01} + \gamma_{10.2}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7.10} + \gamma_{10.3}\epsilon_{10}\epsilon_{7.10}\epsilon_{47}\epsilon_1\epsilon_{01} + \gamma_{41}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{01}\epsilon_{14}$$

$$+ \gamma_{42}\gamma_{10.2}\epsilon_{10}\epsilon_{7.10}\epsilon_4\epsilon_{14}$$

## 4.2 The Five Scenarios Considered

As we mentioned before in Section 3.2.1, different scenarios can be obtained by setting  $\gamma_{ij}$  to 1 or 0 in the generalized state diagram in Figure 3.3. We assume that the mobile station will have only one forward transition branch and one backward transition branch for each state in the state diagram corresponding to one scenario. There are 36 combinations of  $\gamma_{ij}$  listed in Table 4.1, corresponding to 36 possible state diagrams designed scenarios. In fact, there are more than 36 possible combinations and scenarios generated from different values of  $\gamma_{ij}$ , but similar principle can be applied. Therefore, we choose five of them to evaluate and analyze the roaming acquisition time. These scenarios are highlighted in the Table 4.1, scenario number 1, 6, 19, 20, 26.

**Table 4.1**

Scenario Number	$\gamma_{6,1}$	$\gamma_{6,2}$										
	$\gamma_{5,1}$	$\gamma_{5,2}$	$\gamma_{8,1}$	$\gamma_{8,2}$	$\gamma_{8,3}$	$\gamma_{11,1}$	$\gamma_{11,2}$	$\gamma_{11,3}$	$\gamma_{11,4}$			
	$\gamma_{4,1}$	$\gamma_{4,2}$	$\gamma_{7,1}$	$\gamma_{7,2}$	$\gamma_{7,3}$	$\gamma_{10,1}$	$\gamma_{10,2}$	$\gamma_{10,3}$	$\gamma_{10,4}$	$\gamma_{9,1}$	$\gamma_{9,2}$	$\gamma_{9,3}$
1	1	0	1	0	0	1	0	0	0	1	0	0
2	1	0	0	1	0	1	0	0	0	1	0	0
3	1	0	0	1	0	1	0	0	0	0	1	0
4	1	0	0	0	1	1	0	0	0	1	0	0
5	1	0	0	0	1	1	0	0	0	0	0	1
6	1	0	1	0	0	0	1	0	0	1	0	0
7	1	0	1	0	0	0	1	0	0	0	1	0
8	1	0	0	1	0	0	1	0	0	0	1	0
9	1	0	0	0	1	0	1	0	0	0	0	1
10	1	0	0	0	1	0	1	0	0	0	1	0
11	1	0	1	0	0	0	0	1	0	1	0	0
12	1	0	1	0	0	0	0	1	0	0	0	1
13	1	0	0	1	0	0	0	1	0	0	1	0
14	1	0	0	1	0	0	0	1	0	0	0	1
15	1	0	0	0	1	0	0	1	0	0	0	1
16	1	0	1	0	0	0	0	0	1	1	0	0
17	1	0	0	1	0	0	0	0	1	0	1	0
18	1	0	0	0	1	0	0	0	1	0	0	1



19	0	1	1	0	0	1	0	0	0	1	0	0
20	0	1	0	1	0	1	0	0	0	1	0	0
21	0	1	0	1	0	1	0	0	0	0	1	0
22	0	1	0	0	1	1	0	0	0	0	0	1
23	0	1	0	0	1	1	0	0	0	1	0	0
24	0	1	1	0	0	0	1	0	0	1	0	0
25	0	1	1	0	0	0	1	0	0	0	1	0
26	0	1	0	1	0	0	1	0	0	0	1	0
27	0	1	0	0	1	0	1	0	0	0	0	1
28	0	1	0	0	1	0	1	0	0	0	1	0
29	0	1	1	0	0	0	0	1	0	1	0	0
30	0	1	1	0	0	0	0	1	0	0	0	1
31	0	1	0	1	0	0	0	1	0	0	1	0
32	0	1	0	1	0	0	0	1	0	0	0	1
33	0	1	0	0	1	0	0	1	0	0	0	1
34	0	1	1	0	0	0	0	0	1	1	0	0
35	0	1	0	1	0	0	0	0	1	0	1	0
36	0	1	0	0	1	0	0	0	1	0	0	1

#### 4.2.1 Scenario 1

##### 4.2.1.1 State Diagram for Connection Establishment

By substituting  $\gamma_{42} = \gamma_{52} = \gamma_{62} = \gamma_{72} = \gamma_{73} = \gamma_{82} = \gamma_{83} = \gamma_{92} = \gamma_{93} = \gamma_{10,2} = \gamma_{10,3} = \gamma_{10,4} = \gamma_{11,2} = \gamma_{11,3} = \gamma_{11,4} = 0$  and  $\gamma_{41} = \gamma_{51} = \gamma_{61} = \gamma_{71} = \gamma_{81} = \gamma_{91} = \gamma_{10,1} = \gamma_{11,1} = 1$  to the general state diagram in Figure 3.3, we obtain the following state diagram of the MS Figure 4.2 Figure 4.2, which corresponds to scenario number 1 in the Table 4.1. In this design scheme, in each state on a path  $i$ , the MS will move to the next state if the transmission is successful; otherwise, the MS will return to the start state  $S_0$  and make a decision again. Table 4.2 presents a summary of the most important messages and their effect on the state diagram Figure 4.2.

The advantage of this design is that the software process is simple, and it is suitable for all scenarios irrespective of the MS's speed. The main disadvantage is long processing time in the

case of high transmission error rate. This is attributed to the fact that the MS always goes back to the starting point to make a decision again if the transmission fails.

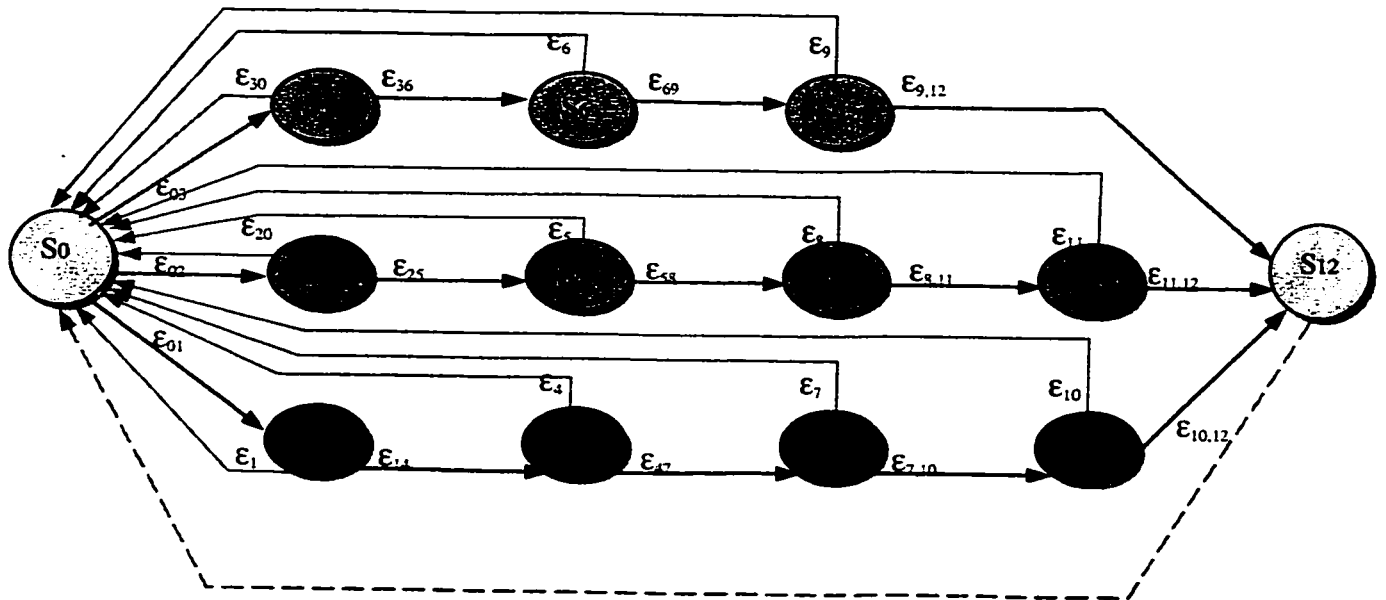


Figure 4.2 State Diagram for Connection Control of a reconfigurable Mobile Station (Scenario 1)

Table 4.2 The transitions in the state diagram (Scenario 1)

From State	S <sub>0</sub>	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	S <sub>4</sub>	S <sub>5</sub>	S <sub>6</sub>	S <sub>7</sub>	S <sub>8</sub>	S <sub>9</sub>	S <sub>10</sub>	S <sub>11</sub>	S <sub>12</sub>	T <sub>0</sub>
Cellular_DL_Request	X													S <sub>1</sub>
WLAN_DL_Request	X													S <sub>2</sub>
SameSystem_Setup	X													S <sub>3</sub>
Cellular_DL_Authen_Confirm		X												S <sub>4</sub>
WLAN_DL_Authen_Confirm			X											S <sub>5</sub>
SameSys_HO_Authen_Confirm				X										S <sub>6</sub>
Cellular SW_DL_Ready					X									S <sub>7</sub>
WLAN SW_DL_Ready						X								S <sub>8</sub>
SameSys_HO_Completed							X							S <sub>9</sub>
CellSW_DL_Completed								X						S <sub>10</sub>
WLAN SW_DL_Completed									X					S <sub>11</sub>
SameSys_Connected										X				S <sub>12</sub>
Cellular_Connected											X			S <sub>12</sub>
WLAN_Connected												X		S <sub>12</sub>
Process_Fails & Timeout (Auto) Or Release_Req (Manual)		X	X	X	X	X	X	X	X	X	X	X	X	S <sub>0</sub>

Where: X denotes the two states are connected and transition is possible for example.

### 4.2.1.2 Roaming Acquisition Time Calculation for Scenario 1

#### 1) Transition Function

There are 11 loops in the diagram, which corresponds to the general flow graph  $C_1, C_2, C_3, C_7, C_8, C_9, C_{10}, C_{17}, C_{18}, C_{19}, C_{20}$ .

$$\begin{aligned}
 C_1 &= \varepsilon_{30}\varepsilon_{03}Z^{t_0+t_3} & C_2 &= \varepsilon_6\varepsilon_{03}\varepsilon_{36}Z^{t_0+t_3+t_6} \\
 C_3 &= \varepsilon_9\varepsilon_{03}\varepsilon_{36}\varepsilon_{69}Z^{t_0+t_3+t_6+t_9} & C_7 &= \varepsilon_{20}\varepsilon_{02}Z^{t_0+t_2} \\
 C_8 &= \varepsilon_5\varepsilon_{02}\varepsilon_{25}Z^{t_0+t_2+t_5} & C_9 &= \varepsilon_8\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}Z^{t_0+t_2+t_5+t_8} \\
 C_{10} &= \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}Z^{t_0+t_2+t_5+t_8+t_{11}} & C_{17} &= \varepsilon_1\varepsilon_{01}Z^{t_0+t_1} \\
 C_{18} &= \varepsilon_4\varepsilon_{01}\varepsilon_{14}Z^{t_0+t_1+t_4} & C_{19} &= \varepsilon_7\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}Z^{t_0+t_1+t_4+t_7} \\
 C_{20} &= \varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}Z^{t_0+t_1+t_4+t_7+t_{10}}
 \end{aligned}$$

There are no non-touching loops in the state diagram, thus

$$\begin{aligned}
 \Delta(z) &= 1 - \sum_{i=1}^3 C_i - \sum_{i=7}^{10} C_i - \sum_{i=17}^{20} C_i = 1 - \varepsilon_{30}\varepsilon_{03}Z^{t_0+t_3} - \varepsilon_6\varepsilon_{03}\varepsilon_{36}Z^{t_0+t_3+t_6} - \varepsilon_9\varepsilon_{03}\varepsilon_{36}\varepsilon_{69}Z^{t_0+t_3+t_6+t_9} - \varepsilon_{20}\varepsilon_{02}Z^{t_0+t_2} \\
 &- \varepsilon_5\varepsilon_{02}\varepsilon_{25}Z^{t_0+t_2+t_5} - \varepsilon_8\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}Z^{t_0+t_2+t_5+t_8} - \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}Z^{t_0+t_2+t_5+t_8+t_{11}} - \varepsilon_1\varepsilon_{01}Z^{t_0+t_1} - \varepsilon_4\varepsilon_{01}\varepsilon_{14}Z^{t_0+t_1+t_4} - \varepsilon_7\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}Z^{t_0+t_1+t_4+t_7} \\
 &- \varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}Z^{t_0+t_1+t_4+t_7+t_{10}}
 \end{aligned}$$

There are 3 forward paths :

$$\text{Forward path1: } F_1 = \varepsilon_{03}\varepsilon_{36}\varepsilon_{69}\varepsilon_{9.12}Z^{t_0+t_3+t_6+t_9}, \Delta_1 = 1$$

$$\text{Forward path2: } F_2 = \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}Z^{t_0+t_2+t_5+t_8+t_{11}}, \Delta_2 = 1$$

$$\text{Forward path3: } F_3 = \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}Z^{t_0+t_1+t_4+t_7+t_{10}}, \Delta_3 = 1$$

$$\begin{aligned}
 F(z) &= F_1*\Delta_1+F_2*\Delta_2 +F_3*\Delta_3 \\
 &= \varepsilon_{03}\varepsilon_{36}\varepsilon_{69}\varepsilon_{9.12}Z^{t_0+t_3+t_6+t_9} + \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}Z^{t_0+t_2+t_5+t_8+t_{11}} + \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}Z^{t_0+t_1+t_4+t_7+t_{10}}
 \end{aligned}$$

Then, according to the definition given in equation (4.2), we get the transition function of this state diagram as below :

$$H(z) = \frac{F_1*\Delta_1+F_2*\Delta_2 +F_3*\Delta_3}{\Delta(z)} = \frac{F(z)}{\Delta(z)}$$

$$\frac{dH(z)}{dz} = \frac{F(z)}{\Delta(z)} - \frac{F(z)*\Delta'(z)}{\Delta^2(z)}$$

Where:

$$\begin{aligned}
 F(z) &= \varepsilon_{03}\varepsilon_{36}\varepsilon_{69}\varepsilon_{9.12}*(\tau_0+\tau_3+\tau_6+\tau_9)Z^{t_0+t_3+t_6+t_9-1} + \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11})Z^{t_0+t_2+t_5+t_8+t_{11}-1} \\
 &+ \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}*(\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10})Z^{t_0+t_1+t_4+t_7+t_{10}-1}
 \end{aligned}$$

$$\begin{aligned}
 \Delta'(z) &= -\varepsilon_{30}\varepsilon_{03}*(\tau_0+\tau_3)Z^{t_0+t_3-1} - \varepsilon_6\varepsilon_{03}\varepsilon_{36}*(\tau_0+\tau_3+\tau_6)Z^{t_0+t_3+t_6-1} - \varepsilon_9\varepsilon_{03}\varepsilon_{36}\varepsilon_{69}*(\tau_0+\tau_3+\tau_6+\tau_9)Z^{t_0+t_3+t_6+t_9-1} - \varepsilon_{20}\varepsilon_{02}*(\tau_0+\tau_2)Z^{t_0+t_2-1} \\
 &- \varepsilon_5\varepsilon_{02}\varepsilon_{25}*(\tau_0+\tau_2+\tau_5)Z^{t_0+t_2+t_5-1} - \varepsilon_8\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}*(\tau_0+\tau_2+\tau_5+\tau_8)Z^{t_0+t_2+t_5+t_8-1} - \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}*(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11})Z^{t_0+t_2+t_5+t_8+t_{11}-1} \\
 &- \varepsilon_1\varepsilon_{01}*(\tau_0+\tau_1)Z^{t_0+t_1-1} - \varepsilon_4\varepsilon_{01}\varepsilon_{14}*(\tau_0+\tau_1+\tau_4)Z^{t_0+t_1+t_4-1} - \varepsilon_7\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}*(\tau_0+\tau_1+\tau_4+\tau_7)Z^{t_0+t_1+t_4+t_7-1} \\
 &- \varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}*(\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10})Z^{t_0+t_1+t_4+t_7+t_{10}-1}
 \end{aligned}$$

## 2) Roaming Acquisition time of Scenario 1

According to the definition given in equation (4.1) that the acquisition time from  $S_0$  to  $S_{12}$  can be found by setting  $z=1$  in  $dH(z)/dz$ , then we obtain the roaming acquisition time of Scenario 1 :

$$T_{sum} = \left. \frac{dH(z)}{dz} \right|_{z=1} = N_1/M_1 + N_2/M_1^2 \quad (4.6)$$

where :

$$N_1 = F(z) \Big|_{z=1}$$

$$= \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12} * (\tau_0 + \tau_3 + \tau_6 + \tau_9) + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12} * (\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}) + \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})$$

$$N_2 = -F(z) * \Delta'(z) \Big|_{z=1} = (\epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12} + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12} + \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}) * [\epsilon_{30}\epsilon_{03} * (\tau_0 + \tau_3) + \epsilon_{60}\epsilon_{03}\epsilon_{36} * (\tau_0 + \tau_3 + \tau_6) + \epsilon_{20}\epsilon_{02} * (\tau_0 + \tau_2) + \epsilon_{90}\epsilon_{03}\epsilon_{36}\epsilon_{69} * (\tau_0 + \tau_3 + \tau_6 + \tau_9) + \epsilon_{50}\epsilon_{02}\epsilon_{25} * (\tau_0 + \tau_2 + \tau_5) + \epsilon_{80}\epsilon_{02}\epsilon_{25}\epsilon_{58} * (\tau_0 + \tau_2 + \tau_5 + \tau_8) + \epsilon_{110}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11} * (\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}) + \epsilon_{10}\epsilon_{01} * (\tau_0 + \tau_1) + \epsilon_{40}\epsilon_{01}\epsilon_{14} * (\tau_0 + \tau_1 + \tau_4) + \epsilon_{70}\epsilon_{01}\epsilon_{14}\epsilon_{47} * (\tau_0 + \tau_1 + \tau_4 + \tau_7) + \epsilon_{100}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10} * (\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})]$$

$$M_1 = \Delta(z) \Big|_{z=1}$$

$$= 1 - \epsilon_{30}\epsilon_{03} - \epsilon_{60}\epsilon_{03}\epsilon_{36} - \epsilon_{90}\epsilon_{03}\epsilon_{36}\epsilon_{69} - \epsilon_{20}\epsilon_{02} - \epsilon_{50}\epsilon_{02}\epsilon_{25} - \epsilon_{80}\epsilon_{02}\epsilon_{25}\epsilon_{58} - \epsilon_{110}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11} - \epsilon_{10}\epsilon_{01} - \epsilon_{40}\epsilon_{01}\epsilon_{14} - \epsilon_{70}\epsilon_{01}\epsilon_{14}\epsilon_{47} - \epsilon_{100}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}$$

### 4.2.2 Scenario 6

#### 4.2.2.1 State Diagram for Connection Establishment

By substituting  $\gamma_{42} = \gamma_{52} = \gamma_{62} = \gamma_{72} = \gamma_{73} = \gamma_{82} = \gamma_{83} = \gamma_{92} = \gamma_{93} = \gamma_{10,1} = \gamma_{10,3} = \gamma_{10,4} = \gamma_{11,1} = \gamma_{11,3} = \gamma_{11,4} = 0$  and  $\gamma_{41} = \gamma_{51} = \gamma_{61} = \gamma_{71} = \gamma_{81} = \gamma_{91} = \gamma_{10,2} = \gamma_{11,2} = 1$  to the generalized state diagram, we obtain the following state diagram of the mobile station (MS) Figure 4.3, which corresponds to scenario number 6 in the Table 4.1. Table 4.3 presents a summary of the most important messages and their effects on the state diagram Figure 4.3.

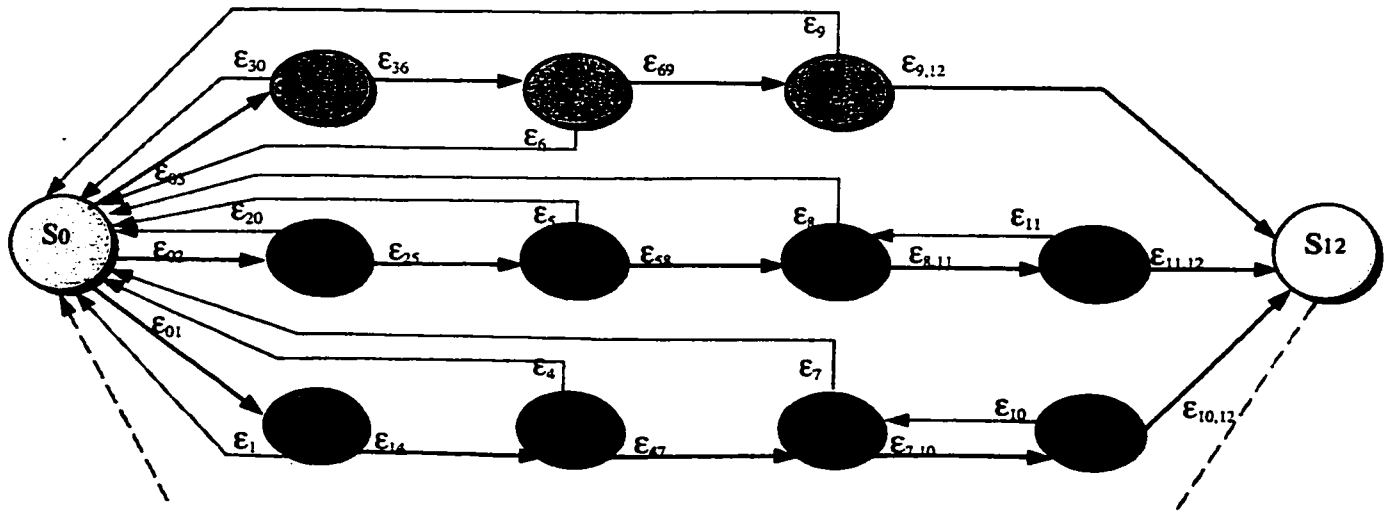


Figure 4.3 State Diagram for Connection Control of a reconfigurable Mobile Station

**Table 4.3** The transitions in the state diagram (Scenario 6)

From State	S <sub>0</sub>	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	S <sub>4</sub>	S <sub>5</sub>	S <sub>6</sub>	S <sub>7</sub>	S <sub>8</sub>	S <sub>9</sub>	S <sub>10</sub>	S <sub>11</sub>	S <sub>12</sub>	To
Cellular_DL_Request	X													S <sub>1</sub>
WLAN_DL_Request	X													S <sub>2</sub>
SameSystem_Setup	X													S <sub>3</sub>
Cellular_DL_Authen_Confirm		X												S <sub>4</sub>
WLAN_DL_Authen_Confirm			X											S <sub>5</sub>
SameSys_HO_Authen_Confirm				X										S <sub>6</sub>
Cellular SW_DL_Ready					X									S <sub>7</sub>
WLAN SW_DL_Ready						X								S <sub>8</sub>
SameSys_HO_Completed							X							S <sub>9</sub>
CellSW_DL_Completed								X						S <sub>10</sub>
WLANSW_DL_Completed									X					S <sub>11</sub>
SameSys_Connected										X				S <sub>12</sub>
Cellular_Connected											X			S <sub>12</sub>
WLAN_Connected												X		S <sub>12</sub>
Process_Fails & Timeout (Auto) Or Release_Req (Manual)		X	X	X	X	X	X	X	X	X			X	S <sub>0</sub>
NewSysUpdate_Fails & Timeout											X			S <sub>7</sub>
NewSysUpdate_Fails & Timeout												X		S <sub>8</sub>

Where: X denotes the two states are connected and transition is possible for example.

#### 4.2.2.2 Roaming Acquisition Time Calculation of Scenario 6

##### 1) Transition Function

There are 11 loops in the diagram, which are corresponding to the general flow graph C<sub>1</sub>, C<sub>2</sub>, C<sub>3</sub>, C<sub>7</sub>, C<sub>8</sub>, C<sub>9</sub>, C<sub>13</sub>, C<sub>17</sub>, C<sub>18</sub>, C<sub>19</sub>, C<sub>23</sub>.

$$\begin{aligned}
 C_1 &= \epsilon_{30}\epsilon_{03}Z^{t_0+t_3} & C_2 &= \epsilon_6\epsilon_{03}\epsilon_{36}Z^{t_0+t_3+t_6} \\
 C_3 &= \epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}Z^{t_0+t_3+t_6+t_9} & C_7 &= \epsilon_{20}\epsilon_{02}Z^{t_0+t_2} \\
 C_8 &= \epsilon_5\epsilon_{02}\epsilon_{25}Z^{t_0+t_2+t_5} & C_9 &= \epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58}Z^{t_0+t_2+t_5+t_8} \\
 C_{13} &= \epsilon_{11}\epsilon_{8,11}Z^{t_8+t_{11}} & C_{17} &= \epsilon_1\epsilon_{01}Z^{t_0+t_1} \\
 C_{18} &= \epsilon_4\epsilon_{01}\epsilon_{14}Z^{t_0+t_1+t_4} & C_{19} &= \epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47}Z^{t_0+t_1+t_4+t_7} \\
 C_{23} &= \epsilon_{10}\epsilon_{7,10}Z^{t_7+t_{10}}
 \end{aligned}$$

There are 17 groups of two non-touching loops :

$$\begin{aligned}
 &C_1C_{13}, \quad C_1C_{23}, \quad C_2C_{13}, \quad C_2C_{23}, \quad C_3C_{13}, \quad C_3C_{23}, \quad C_7C_{13}, \quad C_7C_{23}, \quad C_8C_{13}, \quad C_8C_{23}, \quad C_9C_{23}, \quad C_{13}C_{17}, \quad C_{13}C_{18}, \quad C_{13}C_{19}, \\
 &C_{13}C_{23}, \quad C_{17}C_{23}, \quad C_{18}C_{23}
 \end{aligned}$$

There are 7 groups of three non-touching loops :

$$C_1C_{13}C_{23}, \quad C_2C_{13}C_{23}, \quad C_3C_{13}C_{23}, \quad C_7C_{13}C_{23}, \quad C_8C_{13}C_{23}, \quad C_{13}C_{17}C_{23}, \quad C_{13}C_{18}C_{23}$$

Thus,

$$\Delta(Z) = 1 - C_1 - C_2 - C_3 - C_7 - C_8 - C_9 - C_{13} - C_{17} - C_{18} - C_{19} - C_{23} + (C_1 + C_2 + C_3 + C_7 + C_8) * (C_{13} + C_{23}) + C_9 C_{23} + C_{13} * (C_{17} + C_{18} + C_{19} + C_{23}) + C_{23} * (C_{17} + C_{18}) - C_{13} C_{23} * (C_1 + C_2 + C_3 + C_7 + C_8 + C_{17} + C_{18})$$

$$\begin{aligned} &= 1 - \epsilon_{30}\epsilon_{03}Z^{\tau_0+\tau_3} - \epsilon_6\epsilon_{03}\epsilon_{36}Z^{\tau_0+\tau_3+\tau_6} - \epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}Z^{\tau_0+\tau_3+\tau_6+\tau_9} - \epsilon_{20}\epsilon_{02}Z^{\tau_0+\tau_2} - \epsilon_5\epsilon_{02}\epsilon_{25}Z^{\tau_0+\tau_2+\tau_5} - \epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58}Z^{\tau_0+\tau_2+\tau_5+\tau_8} - \epsilon_{11}\epsilon_{8,11}Z^{\tau_8+\tau_{11}} \\ &- \epsilon_{11}\epsilon_{01}Z^{\tau_0+\tau_{11}} - \epsilon_4\epsilon_{01}\epsilon_{14}Z^{\tau_0+\tau_{11}+\tau_{14}} - \epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47}Z^{\tau_0+\tau_{11}+\tau_{14}+\tau_{17}} - \epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}} + \epsilon_{11}\epsilon_{8,11}\epsilon_{30}\epsilon_{03}Z^{\tau_8+\tau_{11}+\tau_0+\tau_3} + \epsilon_{11}\epsilon_{8,11}\epsilon_6\epsilon_{03}\epsilon_{36}Z^{\tau_8+\tau_{11}+\tau_0+\tau_3+\tau_6} \\ &+ \epsilon_{11}\epsilon_{8,11}\epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}Z^{\tau_8+\tau_{11}+\tau_0+\tau_3+\tau_6+\tau_9} + \epsilon_{11}\epsilon_{8,11}\epsilon_{20}\epsilon_{02}Z^{\tau_8+\tau_{11}+\tau_0+\tau_2} + \epsilon_{11}\epsilon_{8,11}\epsilon_5\epsilon_{02}\epsilon_{25}Z^{\tau_8+\tau_{11}+\tau_0+\tau_2+\tau_5} + \epsilon_{10}\epsilon_{7,10}\epsilon_{30}\epsilon_{03}Z^{\tau_7+\tau_{10}+\tau_0+\tau_3} \\ &+ \epsilon_{10}\epsilon_{7,10}\epsilon_6\epsilon_{03}\epsilon_{36}Z^{\tau_7+\tau_{10}+\tau_0+\tau_3+\tau_6} + \epsilon_{10}\epsilon_{7,10}\epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}Z^{\tau_7+\tau_{10}+\tau_0+\tau_3+\tau_6+\tau_9} + \epsilon_{10}\epsilon_{7,10}\epsilon_{20}\epsilon_{02}Z^{\tau_7+\tau_{10}+\tau_0+\tau_2} + \epsilon_{10}\epsilon_{7,10}\epsilon_5\epsilon_{02}\epsilon_{25}Z^{\tau_7+\tau_{10}+\tau_0+\tau_2+\tau_5} \\ &+ \epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_7+\tau_{10}} + \epsilon_{11}\epsilon_{8,11}\epsilon_1\epsilon_{01}Z^{\tau_8+\tau_{11}+\tau_0+\tau_{11}} + \epsilon_{11}\epsilon_{8,11}\epsilon_4\epsilon_{01}\epsilon_{14}Z^{\tau_8+\tau_{11}+\tau_0+\tau_{14}} + \epsilon_{11}\epsilon_{8,11}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} \\ &* Z^{\tau_8+\tau_{11}+\tau_0+\tau_{14}+\tau_{17}} + \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}Z^{\tau_8+\tau_{11}+\tau_7+\tau_{10}} + \epsilon_{10}\epsilon_{7,10}\epsilon_1\epsilon_{01}Z^{\tau_7+\tau_{10}+\tau_0+\tau_{11}} + \epsilon_{10}\epsilon_{7,10}\epsilon_4\epsilon_{01}\epsilon_{14}Z^{\tau_7+\tau_{10}+\tau_0+\tau_{14}} \\ &- \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}\epsilon_{30}\epsilon_{03}Z^{\tau_7+\tau_{10}+\tau_3+\tau_{11}+\tau_0+\tau_3} - \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}\epsilon_6\epsilon_{03}\epsilon_{36}Z^{\tau_7+\tau_{10}+\tau_3+\tau_{11}+\tau_0+\tau_3+\tau_6} \\ &- \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}\epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}Z^{\tau_7+\tau_{10}+\tau_3+\tau_{11}+\tau_0+\tau_3+\tau_6+\tau_9} - \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}\epsilon_{20}\epsilon_{02}Z^{\tau_7+\tau_{10}+\tau_8+\tau_{11}+\tau_0+\tau_2} \\ &- \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}\epsilon_5\epsilon_{02}\epsilon_{25}Z^{\tau_7+\tau_{10}+\tau_8+\tau_{11}+\tau_0+\tau_2+\tau_5} - \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}\epsilon_1\epsilon_{01}Z^{\tau_7+\tau_{10}+\tau_8+\tau_{11}+\tau_0+\tau_{11}} - \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}\epsilon_4\epsilon_{01}\epsilon_{14}Z^{\tau_7+\tau_{10}+\tau_8+\tau_{11}+\tau_0+\tau_{14}} \end{aligned}$$

There are three forward paths :

Forward path1:  $F_1 = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}Z^{\tau_0+\tau_{14}+\tau_{17}+\tau_{10}}$ ,  $\Delta_1 = 1 - C_{13} = 1 - \epsilon_{11}\epsilon_{8,11}Z^{\tau_8+\tau_{11}}$

Forward path2:  $F_2 = \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}}$ ,  $\Delta_2 = 1 - C_{23} = 1 - \epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}}$

Forward path3:  $F_3 = \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12}Z^{\tau_0+\tau_3+\tau_6+\tau_9}$ ,

$$\Delta_3 = 1 - C_{13} - C_{23} + C_{13}C_{23} = 1 - \epsilon_{11}\epsilon_{8,11}Z^{\tau_8+\tau_{11}} - \epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}} + \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}+\tau_8+\tau_{11}}$$

$$\begin{aligned} F(z) &= F_1 * \Delta_1 + F_2 * \Delta_2 + F_3 * \Delta_3 = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}Z^{\tau_0+\tau_{14}+\tau_{17}+\tau_{10}} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_{11}\epsilon_{8,11}Z^{\tau_8+\tau_{11}+\tau_0+\tau_{14}+\tau_{17}+\tau_{10}} \\ &+ \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}} - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}+\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}} + \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12}Z^{\tau_0+\tau_3+\tau_6+\tau_9} \\ &- \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12}\epsilon_{11}\epsilon_{8,11}Z^{\tau_0+\tau_3+\tau_6+\tau_9+\tau_{11}} - \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_3+\tau_6+\tau_9+\tau_{10}} + \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12}\epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_3+\tau_6+\tau_9+\tau_{10}+\tau_{11}} \end{aligned}$$

Then, according to the definition given in equation (4.2), we get the transition function of this state diagram as below :

$$H(z) = \frac{F_1 * \Delta_1 + F_2 * \Delta_2 + F_3 * \Delta_3}{\Delta(z)} = \frac{F(z)}{\Delta(z)}$$

$$\frac{dH(z)}{dz} = \frac{F'(z)}{\Delta(z)} - \frac{F(z) * \Delta'(z)}{\Delta^2(z)}$$

Where:

$$\begin{aligned} F'(z) &= \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12} * (\tau_0 + \tau_{14} + \tau_{17} + \tau_{10}) Z^{\tau_0+\tau_{14}+\tau_{17}+\tau_{10}-1} + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12} * (\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}) Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1} \\ &- \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_{11}\epsilon_{8,11} * (\tau_0 + \tau_{14} + \tau_{17} + \tau_{10} + \tau_8 + \tau_{11}) Z^{\tau_8+\tau_{11}+\tau_0+\tau_{14}+\tau_{17}+\tau_{10}-1} \\ &- \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_{10}\epsilon_{7,10} * (\tau_7 + \tau_{10} + \tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}) Z^{\tau_7+\tau_{10}+\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1} \\ &+ \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12} * (\tau_0 + \tau_3 + \tau_6 + \tau_9) Z^{\tau_0+\tau_3+\tau_6+\tau_9-1} - \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12}\epsilon_{11}\epsilon_{8,11} * (\tau_0 + \tau_3 + \tau_6 + \tau_9 + \tau_8 + \tau_{11}) Z^{\tau_0+\tau_3+\tau_6+\tau_9+\tau_8+\tau_{11}-1} \\ &- \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12}\epsilon_{10}\epsilon_{7,10} * (\tau_0 + \tau_3 + \tau_6 + \tau_9 + \tau_7 + \tau_{10}) Z^{\tau_0+\tau_3+\tau_6+\tau_9+\tau_7+\tau_{10}-1} \\ &+ \epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_{9,12}\epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10} * (\tau_0 + \tau_3 + \tau_6 + \tau_9 + \tau_7 + \tau_{10} + \tau_8 + \tau_{11}) Z^{\tau_0+\tau_3+\tau_6+\tau_9+\tau_7+\tau_{10}+\tau_8+\tau_{11}-1} \end{aligned}$$

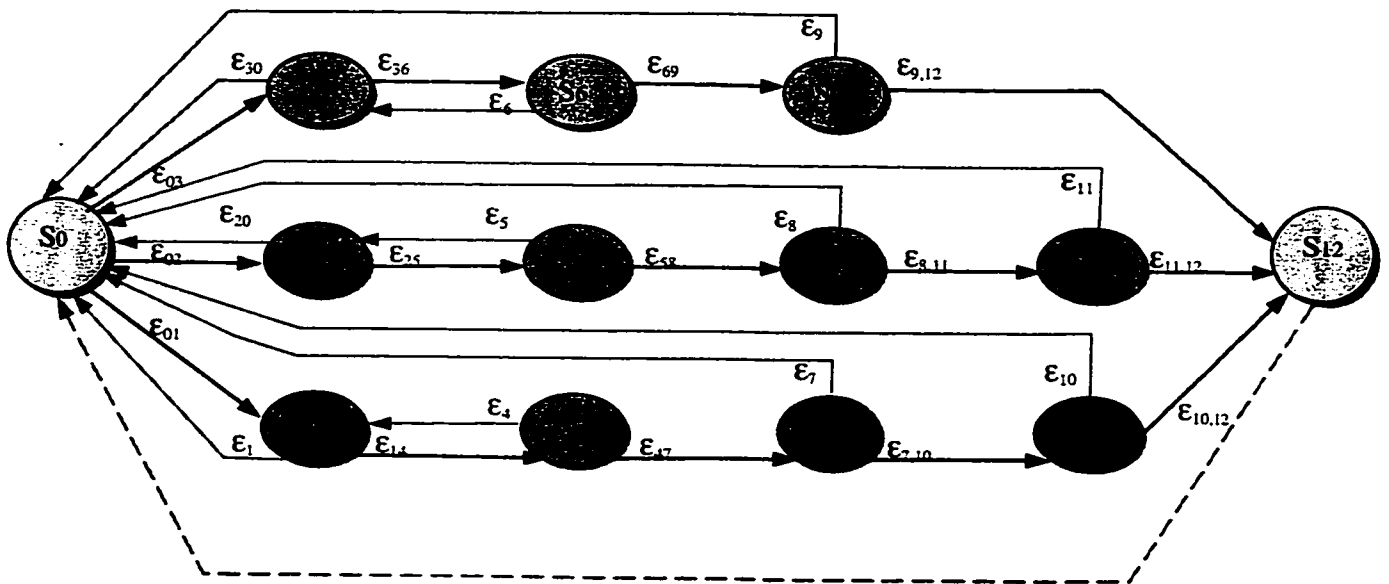
$$\begin{aligned} \Delta'(z) &= -\epsilon_{30}\epsilon_{03} * (\tau_0 + \tau_3) Z^{\tau_0+\tau_3-1} - \epsilon_6\epsilon_{03}\epsilon_{36} * (\tau_0 + \tau_3 + \tau_6) Z^{\tau_0+\tau_3+\tau_6-1} - \epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69} * (\tau_0 + \tau_3 + \tau_6 + \tau_9) Z^{\tau_0+\tau_3+\tau_6+\tau_9-1} \\ &- \epsilon_{20}\epsilon_{02} * (\tau_0 + \tau_2) Z^{\tau_0+\tau_2-1} - \epsilon_5\epsilon_{02}\epsilon_{25} * (\tau_0 + \tau_2 + \tau_5) Z^{\tau_0+\tau_2+\tau_5-1} - \epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} * (\tau_0 + \tau_2 + \tau_5 + \tau_8) Z^{\tau_0+\tau_2+\tau_5+\tau_8-1} - \epsilon_{11}\epsilon_{8,11} * (\tau_8 + \tau_{11}) Z^{\tau_8+\tau_{11}-1} \\ &- \epsilon_{11}\epsilon_{01} * (\tau_0 + \tau_{11}) Z^{\tau_0+\tau_{11}-1} - \epsilon_4\epsilon_{01}\epsilon_{14} * (\tau_0 + \tau_{14}) Z^{\tau_0+\tau_{14}-1} - \epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} * (\tau_0 + \tau_{14} + \tau_{17}) Z^{\tau_0+\tau_{14}+\tau_{17}-1} - \epsilon_{10}\epsilon_{7,10} * (\tau_7 + \tau_{10}) Z^{\tau_7+\tau_{10}-1} \\ &+ \epsilon_{11}\epsilon_{8,11}\epsilon_{30}\epsilon_{03} * (\tau_8 + \tau_{11} + \tau_0 + \tau_3) Z^{\tau_8+\tau_{11}+\tau_0+\tau_3-1} + \epsilon_{11}\epsilon_{8,11}\epsilon_6\epsilon_{03}\epsilon_{36} * (\tau_8 + \tau_{11} + \tau_0 + \tau_3 + \tau_6) Z^{\tau_8+\tau_{11}+\tau_0+\tau_3+\tau_6-1} \end{aligned}$$



### 4.2.3 Scenario 19

#### 4.2.3.1 State Diagram for Connection Establishment

By substituting  $\gamma_{41} = \gamma_{51} = \gamma_{61} = \gamma_{72} = \gamma_{73} = \gamma_{82} = \gamma_{83} = \gamma_{92} = \gamma_{93} = \gamma_{10,2} = \gamma_{10,3} = \gamma_{10,4} = \gamma_{11,2} = \gamma_{11,3} = \gamma_{11,4} = 0$  and  $\gamma_{42} = \gamma_{52} = \gamma_{62} = \gamma_{71} = \gamma_{81} = \gamma_{91} = \gamma_{10,1} = \gamma_{11,1} = 1$  to the generalized state diagram Figure 3.3, we obtain the following state diagram of the mobile station (MS) Figure 4.4, which is corresponding to scenario number 19 in the Table 4.1. Table 4.4 presents a summary of the most important messages and their effects on the state diagram Figure 4.4.



**Figure 4.4** State Diagram for Connection Control of a reconfigurable Mobile Station (Scenario 19)



**Table 4.4 The transitions in the state diagram (Scenario 19)**

From State	S <sub>0</sub>	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	S <sub>4</sub>	S <sub>5</sub>	S <sub>6</sub>	S <sub>7</sub>	S <sub>8</sub>	S <sub>9</sub>	S <sub>10</sub>	S <sub>11</sub>	S <sub>12</sub>	To
Cellular_DL_Request	X													S <sub>1</sub>
WLAN_DL_Request	X													S <sub>2</sub>
SameSystem_Setup	X													S <sub>3</sub>
Cellular_DL_Authen_Confirm		X												S <sub>4</sub>
WLAN_DL_Authen_Confirm			X											S <sub>5</sub>
SameSys_HO_Authen_Confirm				X										S <sub>6</sub>
Cellular SW_DL_Ready					X									S <sub>7</sub>
WLAN SW_DL_Ready						X								S <sub>8</sub>
SameSys_HO_Completed							X							S <sub>9</sub>
CellSW_DL_Completed								X						S <sub>10</sub>
WLAN SW_DL_Completed									X					S <sub>11</sub>
SameSys_Connected										X				S <sub>12</sub>
Cellular_Connected											X			S <sub>12</sub>
WLAN_Connected												X		S <sub>12</sub>
Process_Fails & Timeout (Auto) Or Release_Reg (Manual)		X	X	X				X	X	X	X	X	X	S <sub>0</sub>
Process_Fails & Timeout (Auto)					X									S <sub>1</sub>
Process_Fails & Timeout (Auto)						X								S <sub>2</sub>
Process_Fails & Timeout (Auto)							X							S <sub>3</sub>

Where: X denotes the two states are connected and transition is possible.

#### 4.2.3.2 Roaming Acquisition Time Calculation

##### 1) Transition Function

There are 11 loops in the diagram, which are corresponding to the general flow graph C<sub>1</sub>, C<sub>3</sub>, C<sub>4</sub>,

C<sub>7</sub>, C<sub>9</sub>, C<sub>10</sub>, C<sub>11</sub>, C<sub>17</sub>, C<sub>19</sub>, C<sub>20</sub>, C<sub>21</sub>

$$C_1 = \epsilon_{30}\epsilon_{03}Z^{\tau_0 + \tau_3}$$

$$C_4 = \epsilon_6\epsilon_{36}Z^{\tau_3 + \tau_6}$$

$$C_9 = \epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58}Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8}$$

$$C_{11} = \epsilon_5\epsilon_{25}Z^{\tau_2 + \tau_5}$$

$$C_{19} = \epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47}Z^{\tau_0 + \tau_1 + \tau_4 + \tau_7}$$

$$C_{21} = \epsilon_4\epsilon_{14}Z^{\tau_1 + \tau_4}$$

$$C_3 = \epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}Z^{\tau_0 + \tau_3 + \tau_6 + \tau_9}$$

$$C_7 = \epsilon_{20}\epsilon_{02}Z^{\tau_0 + \tau_2}$$

$$C_{10} = \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}Z^{\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11}}$$

$$C_{17} = \epsilon_1\epsilon_{01}Z^{\tau_0 + \tau_1}$$

$$C_{20} = \epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}Z^{\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10}}$$

There are 19 groups of two non-touching loops :

C<sub>1</sub>C<sub>11</sub>, C<sub>1</sub>C<sub>21</sub>, C<sub>3</sub>C<sub>11</sub>, C<sub>3</sub>C<sub>21</sub>, C<sub>4</sub>C<sub>7</sub>, C<sub>4</sub>C<sub>9</sub>, C<sub>4</sub>C<sub>10</sub>, C<sub>4</sub>C<sub>11</sub>, C<sub>4</sub>C<sub>17</sub>, C<sub>4</sub>C<sub>19</sub>, C<sub>4</sub>C<sub>20</sub>, C<sub>4</sub>C<sub>21</sub>, C<sub>7</sub>C<sub>21</sub>, C<sub>9</sub>C<sub>21</sub>,

C<sub>10</sub>C<sub>21</sub>, C<sub>11</sub>C<sub>17</sub>, C<sub>11</sub>C<sub>19</sub>, C<sub>11</sub>C<sub>20</sub>, C<sub>11</sub>C<sub>21</sub>

There are 9 groups of three non-touching loops :

C<sub>1</sub>C<sub>11</sub>C<sub>21</sub>, C<sub>3</sub>C<sub>11</sub>C<sub>21</sub>, C<sub>7</sub>C<sub>4</sub>C<sub>21</sub>, C<sub>9</sub>C<sub>4</sub>C<sub>21</sub>, C<sub>10</sub>C<sub>4</sub>C<sub>21</sub>, C<sub>17</sub>C<sub>4</sub>C<sub>11</sub>, C<sub>19</sub>C<sub>4</sub>C<sub>11</sub>, C<sub>20</sub>C<sub>4</sub>C<sub>11</sub>, C<sub>21</sub>C<sub>4</sub>C<sub>11</sub>





$$\begin{aligned}
& -\epsilon_6\epsilon_{36}\epsilon_4\epsilon_{14}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} * (\tau_1 + \tau_4 + \tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_3 + \tau_6) - \epsilon_6\epsilon_{36}\epsilon_4\epsilon_{14}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11} * (\tau_1 + \tau_4 + \tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11} + \tau_3 + \tau_6) \\
& -\epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01} * (\tau_3 + \tau_6 + \tau_2 + \tau_5 + \tau_0 + \tau_1) - \epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} * (\tau_3 + \tau_6 + \tau_2 + \tau_5 + \tau_0 + \tau_1 + \tau_4 + \tau_7) \\
& -\epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} * (\tau_2 + \tau_5 + \tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10} + \tau_3 + \tau_6) - \epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14} * (\tau_3 + \tau_6 + \tau_2 + \tau_5 + \tau_1 + \tau_4)
\end{aligned}$$

$$M_1 = \Delta(z) \Big|_{z=1}$$

$$\begin{aligned}
& = 1 - \epsilon_{30}\epsilon_{03} - \epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69} - \epsilon_6\epsilon_{36} - \epsilon_{20}\epsilon_{02} - \epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} - \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11} - \epsilon_5\epsilon_{25} - \epsilon_1\epsilon_{01} - \epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} - \epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} - \epsilon_4\epsilon_{14} + \epsilon_{30}\epsilon_{03}\epsilon_5\epsilon_{25} \\
& + \epsilon_{30}\epsilon_{03}\epsilon_4\epsilon_{14} + \epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_5\epsilon_{25} + \epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}\epsilon_4\epsilon_{14} + \epsilon_6\epsilon_{36}\epsilon_{20}\epsilon_{02} + \epsilon_6\epsilon_{36}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} + \epsilon_6\epsilon_{36}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11} + \epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25} + \epsilon_6\epsilon_{36}\epsilon_1\epsilon_{01} \\
& + \epsilon_6\epsilon_{36}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} + \epsilon_6\epsilon_{36}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} + \epsilon_6\epsilon_{36}\epsilon_4\epsilon_{14} + \epsilon_4\epsilon_{14}\epsilon_{20}\epsilon_{02} + \epsilon_4\epsilon_{14}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} + \epsilon_4\epsilon_{14}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11} + \epsilon_5\epsilon_{25}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} \\
& + \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01} + \epsilon_5\epsilon_{25}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} + \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14} - \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14}\epsilon_{30}\epsilon_{03} - \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14}\epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69} - \epsilon_6\epsilon_{36}\epsilon_4\epsilon_{14}\epsilon_{20}\epsilon_{02} - \epsilon_6\epsilon_{36}\epsilon_4\epsilon_{14}\epsilon_8\epsilon_{02}\epsilon_{25}\epsilon_{58} \\
& - \epsilon_6\epsilon_{36}\epsilon_4\epsilon_{14}\epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8.11} - \epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01} - \epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25}\epsilon_7\epsilon_{01}\epsilon_{14}\epsilon_{47} - \epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7.10} - \epsilon_6\epsilon_{36}\epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14}
\end{aligned}$$

## 4.2.4 Scenario 20

### 4.2.4.1 State Diagram for Connection Establishment

By substituting  $\gamma_{41} = \gamma_{51} = \gamma_{61} = \gamma_{71} = \gamma_{73} = \gamma_{81} = \gamma_{83} = \gamma_{92} = \gamma_{93} = \gamma_{10.2} = \gamma_{10.3} = \gamma_{10.4} = \gamma_{11.2} = \gamma_{11.3} = \gamma_{11.4} = 0$  and  $\gamma_{42} = \gamma_{52} = \gamma_{62} = \gamma_{72} = \gamma_{82} = \gamma_{91} = \gamma_{10.1} = \gamma_{11.1} = 1$  to the generalized state diagram in Figure 3.3, we obtain the following state diagram of the mobile station Figure 4.5, which corresponds to scenario number 20 in the Table 4.1.

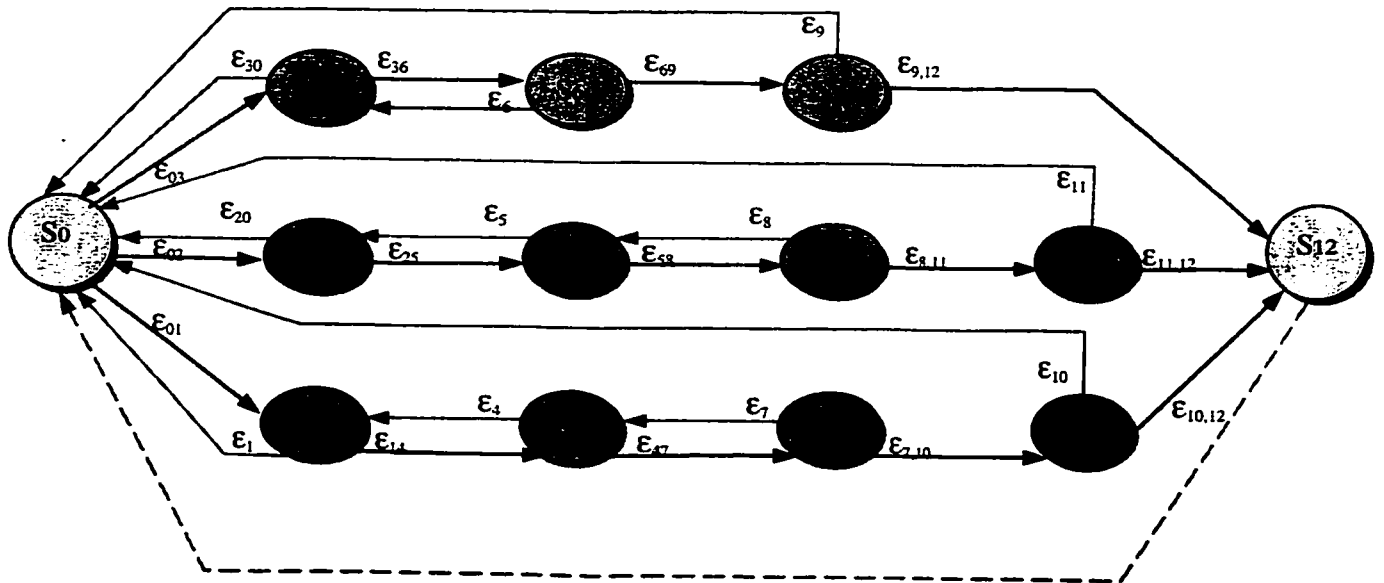


Figure 4.5 State Diagram for Connection Establishment of a reconfigurable Mobile Station (Scenario 20)

**Table 4.5 The transitions in the state diagram (Scenario 20)**

From State	S <sub>0</sub>	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	S <sub>4</sub>	S <sub>5</sub>	S <sub>6</sub>	S <sub>7</sub>	S <sub>8</sub>	S <sub>9</sub>	S <sub>10</sub>	S <sub>11</sub>	S <sub>12</sub>	To
Cellular_DL_Request	X													S <sub>1</sub>
WLAN_DL_Request	X													S <sub>2</sub>
SameSystem_Setup	X													S <sub>3</sub>
Cellular_DL_Authen_Confirm		X												S <sub>4</sub>
WLAN_DL_Authen_Confirm			X											S <sub>5</sub>
SameSys_HO_Authen_Confirm				X										S <sub>6</sub>
Cellular SW_DL_Ready					X									S <sub>7</sub>
WLAN SW_DL_Ready						X								S <sub>8</sub>
SameSys_HO_Completed							X							S <sub>9</sub>
CellSW_DL_Completed								X						S <sub>10</sub>
WLAN SW_DL_Completed									X					S <sub>11</sub>
SameSys_Connected										X				S <sub>12</sub>
Cellular_Connected											X			S <sub>12</sub>
WLAN_Connected												X		S <sub>12</sub>
Process_Fails & Timeout (Auto)		X	X	X						X	X	X	X	S <sub>0</sub>
Cellular_DL_Authen_Failed					X									S <sub>1</sub>
WLAN_DL_Authen_Failed						X								S <sub>2</sub>
SameSys_HO_Authen_Failed							X							S <sub>3</sub>
Cellular SW_DL_Unavailable								X						S <sub>4</sub>
WLAN SW_DL_Unavailable									X					S <sub>5</sub>

Where: X denotes the two states are connected and transition is possible for example.

#### 4.2.4.2 Roaming Acquisition Time Calculation of Scenario 20

##### 1) Transition Function

There are 11 loops in the diagram, which are corresponding to the general flow graph C<sub>1</sub>, C<sub>3</sub>, C<sub>4</sub>,

C<sub>7</sub>, C<sub>10</sub>, C<sub>11</sub>, C<sub>12</sub>, C<sub>17</sub>, C<sub>20</sub>, C<sub>21</sub>, C<sub>22</sub>

$$\begin{aligned}
 C_1 &= \epsilon_{30}\epsilon_{03}Z^{t_0+t_3} & C_3 &= \epsilon_9\epsilon_{03}\epsilon_{36}\epsilon_{69}Z^{t_0+t_3+t_6+t_9} \\
 C_4 &= \epsilon_6\epsilon_{36}Z^{t_3+t_6} & C_7 &= \epsilon_{20}\epsilon_{02}Z^{t_0+t_2} \\
 C_{10} &= \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}Z^{t_0+t_2+t_5+t_8+t_{11}} & C_{11} &= \epsilon_5\epsilon_{25}Z^{t_2+t_5} \\
 C_{12} &= \epsilon_8\epsilon_{58}Z^{t_5+t_8} & C_{17} &= \epsilon_1\epsilon_{01}Z^{t_0+t_1} \\
 C_{20} &= \epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}Z^{t_0+t_1+t_4+t_7+t_{10}} & C_{21} &= \epsilon_4\epsilon_{14}Z^{t_1+t_4} \\
 C_{22} &= \epsilon_7\epsilon_{47}Z^{t_4+t_7}
 \end{aligned}$$

There are 30 groups of two non-touching loops :

C<sub>1</sub>C<sub>11</sub>, C<sub>1</sub>C<sub>12</sub>, C<sub>1</sub>C<sub>21</sub>, C<sub>1</sub>C<sub>22</sub>, C<sub>3</sub>C<sub>11</sub>, C<sub>3</sub>C<sub>12</sub>, C<sub>3</sub>C<sub>21</sub>, C<sub>3</sub>C<sub>22</sub>, C<sub>4</sub>C<sub>7</sub>, C<sub>4</sub>C<sub>10</sub>, C<sub>4</sub>C<sub>11</sub>, C<sub>4</sub>C<sub>12</sub>, C<sub>4</sub>C<sub>17</sub>, C<sub>4</sub>C<sub>20</sub>, C<sub>4</sub>C<sub>21</sub>, C<sub>4</sub>C<sub>22</sub>,  
 C<sub>7</sub>C<sub>12</sub>, C<sub>7</sub>C<sub>21</sub>, C<sub>7</sub>C<sub>22</sub>, C<sub>11</sub>C<sub>17</sub>, C<sub>11</sub>C<sub>20</sub>, C<sub>11</sub>C<sub>21</sub>, C<sub>11</sub>C<sub>22</sub>, C<sub>10</sub>C<sub>21</sub>, C<sub>10</sub>C<sub>22</sub>, C<sub>12</sub>C<sub>17</sub>, C<sub>12</sub>C<sub>20</sub>, C<sub>12</sub>C<sub>21</sub>, C<sub>12</sub>C<sub>22</sub>, C<sub>17</sub>C<sub>22</sub>

There are 26 groups of three non-touching loops :

$$C_1C_{11}C_{21}, C_1C_{11}C_{22}, C_1C_{12}C_{21}, C_1C_{12}C_{22}, C_3C_{11}C_{21}, C_3C_{11}C_{22}, C_3C_{12}C_{21}, C_3C_{12}C_{22},$$

$$C_4C_7C_{12}, C_4C_7C_{21}, C_4C_7C_{22}, C_4C_{10}C_{21}, C_4C_{10}C_{22}, C_4C_{11}C_{17}, C_4C_{11}C_{20}, C_4C_{11}C_{21}, C_4C_{11}C_{22},$$

$$C_4C_{12}C_{17}, C_4C_{12}C_{20}, C_4C_{12}C_{21}, C_4C_{12}C_{22}, C_4C_{17}C_{22}, C_7C_{12}C_{21}, C_7C_{12}C_{22}, C_{11}C_{17}C_{22}, C_{12}C_{17}C_{22}$$

There are 3 groups of four non-touching loops :

$$C_4C_7C_{12}C_{21}, C_4C_{11}C_{17}C_{22}, C_4C_{12}C_{17}C_{22}$$

Thus,

$$\Delta(z) = 1 - (\text{sum of all different loop gains}) + (\text{sum of the gain products of two nontouching loops})$$

$$- (\text{sum of the gain products of three nontouching loops})$$

$$+ (\text{sum of the gain products of four nontouching loops})$$

This will bring us a very complex, cumbersome transition function for this state diagram. We consider a special case only, in which case the transition probability distributions of path1, 2, 3 are  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = \epsilon_{01}/\epsilon_{02}/0$ , i.e, the transition is made to  $S_1$  in path1 or  $S_2$  in path2 with probability  $\epsilon_{01}$  or  $\epsilon_{02}$  respectively; the transition will not be made to path3. Then we will get the acquisition time of the worst case.

There are 8 loops in the state diagram :  $C_7, C_{10}, C_{11}, C_{12}, C_{17}, C_{20}, C_{21}, C_{22}$

$$C_7 = \epsilon_{20}\epsilon_{02}Z^{t_0+t_2}$$

$$C_{11} = \epsilon_5\epsilon_{25}Z^{t_2+t_5}$$

$$C_{17} = \epsilon_1\epsilon_{01}Z^{t_0+t_1}$$

$$C_{21} = \epsilon_4\epsilon_{14}Z^{t_1+t_4}$$

$$C_{10} = \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}Z^{t_0+t_2+t_5+t_8+t_{11}}$$

$$C_{12} = \epsilon_8\epsilon_{58}Z^{t_5+t_8}$$

$$C_{20} = \epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}Z^{t_0+t_1+t_4+t_7+t_{10}}$$

$$C_{22} = \epsilon_7\epsilon_{47}Z^{t_4+t_7}$$

There are 14 groups of two non-touching loops :

$$C_7C_{12}, C_7C_{21}, C_7C_{22}, C_{11}C_{17}, C_{11}C_{20}, C_{11}C_{21}, C_{11}C_{22}, C_{10}C_{21}, C_{10}C_{22}, C_{12}C_{17}, C_{12}C_{20}, C_{12}C_{21}, C_{12}C_{22}, C_{17}C_{22}$$

There are 4 groups of three non-touching loops :

$$C_7C_{12}C_{21}, C_7C_{12}C_{22}, C_{11}C_{17}C_{22}, C_{12}C_{17}C_{22}$$

Thus,

$$\Delta(z) = 1 - C_7 - C_{10} - C_{11} - C_{12} - C_{17} - C_{20} - C_{21} - C_{22} + C_7C_{12} + C_7C_{21} + C_7C_{22} + C_{10}C_{21} + C_{10}C_{22} + C_{11}C_{17} + C_{11}C_{20} + C_{11}C_{21} + C_{11}C_{22}$$

$$+ C_{12}C_{17} + C_{12}C_{20} + C_{12}C_{21} + C_{12}C_{22} + C_{17}C_{22} - C_7C_{12}C_{21} - C_7C_{12}C_{22} - C_{11}C_{17}C_{22} - C_{12}C_{17}C_{22}$$

$$\begin{aligned}
&= 1 - \varepsilon_{20}\varepsilon_{02}Z^{\tau_0+\tau_2} - \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}} - \varepsilon_{5}\varepsilon_{25}Z^{\tau_2+\tau_5} - \varepsilon_{8}\varepsilon_{58}Z^{\tau_5+\tau_8} - \varepsilon_{1}\varepsilon_{01}Z^{\tau_0+\tau_1} - \varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}} \\
&- \varepsilon_{4}\varepsilon_{14}Z^{\tau_1+\tau_4} - \varepsilon_{7}\varepsilon_{47}Z^{\tau_4+\tau_7} + \varepsilon_{20}\varepsilon_{02}\varepsilon_{8}\varepsilon_{58}Z^{\tau_5+\tau_8+\tau_0+\tau_2} + \varepsilon_{20}\varepsilon_{02}\varepsilon_{4}\varepsilon_{14}Z^{\tau_1+\tau_4+\tau_0+\tau_2} + \varepsilon_{20}\varepsilon_{02}\varepsilon_{7}\varepsilon_{47}Z^{\tau_4+\tau_7+\tau_0+\tau_2} + \varepsilon_{1}\varepsilon_{01}\varepsilon_{7}\varepsilon_{47}Z^{\tau_0+\tau_1+\tau_4+\tau_7} \\
&+ \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{4}\varepsilon_{14}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}+\tau_1+\tau_4} + \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{7}\varepsilon_{47}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}+\tau_4+\tau_7} + \varepsilon_{5}\varepsilon_{25}\varepsilon_{1}\varepsilon_{01}Z^{\tau_2+\tau_5+\tau_0+\tau_1} \\
&+ \varepsilon_{5}\varepsilon_{25}\varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}Z^{\tau_2+\tau_5+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}} + \varepsilon_{5}\varepsilon_{25}\varepsilon_{4}\varepsilon_{14}Z^{\tau_2+\tau_5+\tau_1+\tau_4} + \varepsilon_{5}\varepsilon_{25}\varepsilon_{7}\varepsilon_{47}Z^{\tau_2+\tau_5+\tau_4+\tau_7} + \varepsilon_{8}\varepsilon_{58}\varepsilon_{1}\varepsilon_{01}Z^{\tau_5+\tau_8+\tau_0+\tau_1} \\
&+ \varepsilon_{8}\varepsilon_{58}\varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}Z^{\tau_5+\tau_8+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}} + \varepsilon_{8}\varepsilon_{58}\varepsilon_{4}\varepsilon_{14}Z^{\tau_5+\tau_8+\tau_1+\tau_4} + \varepsilon_{8}\varepsilon_{58}\varepsilon_{7}\varepsilon_{47}Z^{\tau_5+\tau_8+\tau_4+\tau_7} - \varepsilon_{8}\varepsilon_{58}\varepsilon_{20}\varepsilon_{02}\varepsilon_{4}\varepsilon_{14}Z^{\tau_1+\tau_4+\tau_0+\tau_2+\tau_5+\tau_8} \\
&- \varepsilon_{8}\varepsilon_{58}\varepsilon_{20}\varepsilon_{02}\varepsilon_{7}\varepsilon_{47}Z^{\tau_4+\tau_7+\tau_0+\tau_2+\tau_5+\tau_8} - \varepsilon_{5}\varepsilon_{25}\varepsilon_{1}\varepsilon_{01}\varepsilon_{7}\varepsilon_{47}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_2+\tau_5} - \varepsilon_{8}\varepsilon_{58}\varepsilon_{1}\varepsilon_{01}\varepsilon_{7}\varepsilon_{47}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_5+\tau_8}
\end{aligned}$$

There are 2 forward paths :

Forward path1:  $F_1 = \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}}$ ,  $\Delta_1 = 1 - C_{11} - C_{12} = 1 - \varepsilon_{5}\varepsilon_{25}Z^{\tau_2+\tau_5} - \varepsilon_{8}\varepsilon_{58}Z^{\tau_5+\tau_8}$

Forward path2:  $F_2 = \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}}$ ,  $\Delta_2 = 1 - C_{21} - C_{22} = 1 - \varepsilon_{4}\varepsilon_{14}Z^{\tau_1+\tau_4} - \varepsilon_{7}\varepsilon_{47}Z^{\tau_4+\tau_7}$

$$\begin{aligned}
F(z) &= F_1 * \Delta_1 + F_2 * \Delta_2 = \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}} - \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}\varepsilon_{5}\varepsilon_{25}Z^{\tau_2+\tau_5+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}} \\
&- \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}\varepsilon_{8}\varepsilon_{58}Z^{\tau_5+\tau_8+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}} + \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}} - \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}\varepsilon_{4}\varepsilon_{14}Z^{\tau_1+\tau_4+\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}} \\
&- \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}\varepsilon_{7}\varepsilon_{47}Z^{\tau_4+\tau_7+\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}}
\end{aligned}$$

Then, according to the definition given in equation (4.2), we get the transition function of this state diagram in special case  $\varepsilon_{01}/\varepsilon_{02}/\varepsilon_{03} = \varepsilon_{01}/\varepsilon_{02}/0$ , i.e

$$\begin{aligned}
H(z) &= \frac{F_1 * \Delta_1 + F_2 * \Delta_2}{\Delta(z)} = \frac{F(z)}{\Delta(z)} \\
\frac{dH(z)}{dz} &= \frac{F'(z)}{\Delta(z)} - \frac{F(z) * \Delta'(z)}{\Delta^2(z)}
\end{aligned}$$

Where:

$$\begin{aligned}
F'(z) &= \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}(\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}\varepsilon_{5}\varepsilon_{25}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_{10}) \\
&* Z^{\tau_2+\tau_5+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}\varepsilon_{10.12}\varepsilon_{8}\varepsilon_{58}(\tau_0 + \tau_1 + \tau_4 + \tau_5 + \tau_7 + \tau_8 + \tau_{10})Z^{\tau_5+\tau_8+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}-1} \\
&+ \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}(\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1} - \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}\varepsilon_{4}\varepsilon_{14}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_1+\tau_4+\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1} \\
&- \varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{11.12}\varepsilon_{7}\varepsilon_{47}(\tau_0 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_8 + \tau_{11})Z^{\tau_4+\tau_7+\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1}
\end{aligned}$$

$$\begin{aligned}
\Delta'(z) &= -\varepsilon_{20}\varepsilon_{02}(\tau_0 + \tau_2)Z^{\tau_0+\tau_2-1} - \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}(\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}-1} - \varepsilon_{5}\varepsilon_{25}(\tau_2 + \tau_5)Z^{\tau_2+\tau_5-1} - \varepsilon_{8}\varepsilon_{58}(\tau_5 + \tau_8)Z^{\tau_5+\tau_8-1} \\
&- \varepsilon_{1}\varepsilon_{01}(\tau_0 + \tau_1)Z^{\tau_0+\tau_1-1} - \varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}(\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \varepsilon_{4}\varepsilon_{14}(\tau_1 + \tau_4)Z^{\tau_1+\tau_4-1} - \varepsilon_{7}\varepsilon_{47}(\tau_4 + \tau_7)Z^{\tau_4+\tau_7-1} \\
&+ \varepsilon_{20}\varepsilon_{02}\varepsilon_{8}\varepsilon_{58}(\tau_0 + \tau_2 + \tau_5 + \tau_8)Z^{\tau_0+\tau_2+\tau_5+\tau_8-1} + \varepsilon_{20}\varepsilon_{02}\varepsilon_{4}\varepsilon_{14}(\tau_0 + \tau_1 + \tau_2 + \tau_4)Z^{\tau_0+\tau_2+\tau_1+\tau_4-1} + \varepsilon_{20}\varepsilon_{02}\varepsilon_{7}\varepsilon_{47}(\tau_0 + \tau_2 + \tau_4 + \tau_7)Z^{\tau_0+\tau_2+\tau_4+\tau_7-1} \\
&+ \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{4}\varepsilon_{14}(\tau_1 + \tau_4 + \tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}+\tau_1+\tau_4-1} + \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{7}\varepsilon_{47}(\tau_0 + \tau_1 + \tau_4 + \tau_7)Z^{\tau_0+\tau_1+\tau_4+\tau_7-1} \\
&+ \varepsilon_{11}\varepsilon_{02}\varepsilon_{25}\varepsilon_{58}\varepsilon_{8.11}\varepsilon_{7}\varepsilon_{47}(\tau_4 + \tau_7 + \tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}+\tau_4+\tau_7-1} + \varepsilon_{5}\varepsilon_{25}\varepsilon_{1}\varepsilon_{01}(\tau_0 + \tau_1 + \tau_2 + \tau_5)Z^{\tau_0+\tau_1+\tau_2+\tau_5-1} \\
&+ \varepsilon_{5}\varepsilon_{25}\varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}(\tau_2 + \tau_5 + \tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})Z^{\tau_2+\tau_5+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}-1} + \varepsilon_{5}\varepsilon_{25}\varepsilon_{4}\varepsilon_{14}(\tau_1 + \tau_2 + \tau_4 + \tau_5)Z^{\tau_1+\tau_4+\tau_2+\tau_5-1} \\
&+ \varepsilon_{5}\varepsilon_{25}\varepsilon_{7}\varepsilon_{47}(\tau_2 + \tau_4 + \tau_5 + \tau_7)Z^{\tau_2+\tau_5+\tau_4+\tau_7-1} + \varepsilon_{8}\varepsilon_{58}\varepsilon_{1}\varepsilon_{01}(\tau_0 + \tau_1 + \tau_5 + \tau_8)Z^{\tau_0+\tau_1+\tau_5+\tau_8-1} + \varepsilon_{8}\varepsilon_{58}\varepsilon_{7}\varepsilon_{47}(\tau_4 + \tau_5 + \tau_7 + \tau_8)Z^{\tau_4+\tau_5+\tau_7+\tau_8-1} \\
&+ \varepsilon_{8}\varepsilon_{58}\varepsilon_{10}\varepsilon_{01}\varepsilon_{14}\varepsilon_{47}\varepsilon_{7.10}(\tau_5 + \tau_8 + \tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})Z^{\tau_5+\tau_8+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}-1} + \varepsilon_{8}\varepsilon_{58}\varepsilon_{4}\varepsilon_{14}(\tau_1 + \tau_4 + \tau_5 + \tau_8)Z^{\tau_1+\tau_4+\tau_5+\tau_8-1} \\
&- \varepsilon_{8}\varepsilon_{58}\varepsilon_{20}\varepsilon_{02}\varepsilon_{4}\varepsilon_{14}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_8)Z^{\tau_0+\tau_2+\tau_1+\tau_4+\tau_5+\tau_8-1} - \varepsilon_{8}\varepsilon_{58}\varepsilon_{20}\varepsilon_{02}\varepsilon_{7}\varepsilon_{47}(\tau_0 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_8)Z^{\tau_0+\tau_2+\tau_4+\tau_7+\tau_5+\tau_8-1} \\
&- \varepsilon_{5}\varepsilon_{25}\varepsilon_{1}\varepsilon_{01}\varepsilon_{7}\varepsilon_{47}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_7)Z^{\tau_0+\tau_1+\tau_2+\tau_4+\tau_5+\tau_7-1} - \varepsilon_{8}\varepsilon_{58}\varepsilon_{1}\varepsilon_{01}\varepsilon_{7}\varepsilon_{47}(\tau_0 + \tau_1 + \tau_8 + \tau_4 + \tau_5 + \tau_7)Z^{\tau_0+\tau_1+\tau_4+\tau_5+\tau_7+\tau_8-1}
\end{aligned}$$

## 2) Roaming Acquisition time of scenario 20 in case $\varepsilon_{01}/\varepsilon_{02}/\varepsilon_{03} = \varepsilon_{01}/\varepsilon_{02}/0$

According to the definition given in equation (4.1) that the acquisition time from  $S_0$  to  $S_{12}$  can be found by setting  $z = 1$  in  $dH(z)/dz$ , then we get the roaming acquisition time in special case

$$\varepsilon_{01}/\varepsilon_{02}/\varepsilon_{03} = \varepsilon_{01}/\varepsilon_{02}/0$$

$$T_{sum} = \left. \frac{dH(z)}{dz} \right|_{z=1} = N_1/M_1 + N_2/M_1^2 \quad (4.9)$$

where :

$$N_1 = F(z) \Big|_{z=1} = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}(\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}) - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_5\epsilon_{25}(\tau_0+\tau_1+\tau_2+\tau_4+\tau_5+\tau_7+\tau_{10}) \\ - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_8\epsilon_{58}(\tau_0+\tau_1+\tau_4+\tau_5+\tau_7+\tau_8+\tau_{10}) + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}) \\ - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_4\epsilon_{14}(\tau_0+\tau_1+\tau_2+\tau_4+\tau_5+\tau_8+\tau_{11}) - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_7\epsilon_{47}(\tau_0+\tau_2+\tau_4+\tau_5+\tau_7+\tau_8+\tau_{11})$$

$$N_2 = -F(z)*\Delta'(z) \Big|_{z=1} = -(\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_5\epsilon_{25} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_8\epsilon_{58} + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12} \\ - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_4\epsilon_{14} - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_7\epsilon_{47}) * [-\epsilon_{20}\epsilon_{02}(\tau_0+\tau_2) - \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}(\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}) - \epsilon_5\epsilon_{25}(\tau_2+\tau_5) \\ - \epsilon_8\epsilon_{58}(\tau_5+\tau_8) - \epsilon_1\epsilon_{01}(\tau_0+\tau_1) - \epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}(\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}) - \epsilon_4\epsilon_{14}(\tau_1+\tau_4) - \epsilon_7\epsilon_{47}(\tau_4+\tau_7) + \epsilon_{20}\epsilon_{02}\epsilon_8\epsilon_{58}(\tau_0+\tau_2+\tau_5+\tau_8) \\ + \epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}(\tau_0+\tau_1+\tau_2+\tau_4) + \epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47}(\tau_0+\tau_2+\tau_4+\tau_7) + \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_4\epsilon_{14}(\tau_1+\tau_4+\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}) + \epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}(\tau_0+\tau_1+\tau_4+\tau_7) \\ + \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_7\epsilon_{47}(\tau_4+\tau_7+\tau_0+\tau_2+\tau_5+\tau_8+\tau_{11}) + \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01}(\tau_0+\tau_1+\tau_2+\tau_5) + \epsilon_5\epsilon_{25}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}(\tau_2+\tau_5+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}) \\ + \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14}(\tau_1+\tau_2+\tau_4+\tau_5) + \epsilon_5\epsilon_{25}\epsilon_7\epsilon_{47}(\tau_2+\tau_4+\tau_5+\tau_7) + \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}(\tau_0+\tau_1+\tau_5+\tau_8) + \epsilon_8\epsilon_{58}\epsilon_7\epsilon_{47}(\tau_4+\tau_5+\tau_7+\tau_8) \\ + \epsilon_8\epsilon_{58}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}(\tau_5+\tau_8+\tau_0+\tau_1+\tau_4+\tau_7+\tau_{10}) + \epsilon_8\epsilon_{58}\epsilon_4\epsilon_{14}(\tau_1+\tau_4+\tau_5+\tau_8) - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}(\tau_0+\tau_1+\tau_2+\tau_4+\tau_5+\tau_8) \\ - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47}(\tau_0+\tau_2+\tau_4+\tau_5+\tau_7+\tau_8) - \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}(\tau_0+\tau_1+\tau_2+\tau_4+\tau_5+\tau_7) - \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}(\tau_0+\tau_1+\tau_8+\tau_4+\tau_5+\tau_7)]$$

$$M_1 = \Delta(z) \Big|_{z=1}$$

$$= 1 - \epsilon_{20}\epsilon_{02} - \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11} - \epsilon_5\epsilon_{25} - \epsilon_8\epsilon_{58} - \epsilon_1\epsilon_{01} - \epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_4\epsilon_{14}\epsilon_7\epsilon_{47} + \epsilon_{20}\epsilon_{02}\epsilon_8\epsilon_{58} + \epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14} + \epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47} \\ + \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_4\epsilon_{14} + \epsilon_{11}\epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_7\epsilon_{47} + \epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47} + \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01} + \epsilon_5\epsilon_{25}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10} + \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14} + \epsilon_5\epsilon_{25}\epsilon_7\epsilon_{47} + \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01} \\ + \epsilon_8\epsilon_{58}\epsilon_{10}\epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10} + \epsilon_8\epsilon_{58}\epsilon_4\epsilon_{14} + \epsilon_8\epsilon_{58}\epsilon_7\epsilon_{47} - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14} - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47} - \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47} - \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}$$

## 4.2.5 Scenario 26

### 4.2.5.1 State Diagram for Connection Establishment

By substituting  $\gamma_{41} = \gamma_{51} = \gamma_{61} = \gamma_{71} = \gamma_{73} = \gamma_{81} = \gamma_{83} = \gamma_{91} = \gamma_{93} = \gamma_{10,1} = \gamma_{10,3} = \gamma_{10,4} = \gamma_{11,1} = \gamma_{11,3} = \gamma_{11,4} = 0$  and  $\gamma_{42} = \gamma_{52} = \gamma_{62} = \gamma_{72} = \gamma_{82} = \gamma_{92} = \gamma_{10,2} = \gamma_{11,2} = 1$  to the generalized state diagram Figure 3.3, we obtain the following state diagram of the mobile station Figure 4.6, which corresponds to scenario number 26 in the Table 4.1. Table 4.6 presents a summary of the most important messages and their effects on the state diagram in Figure 4.6.

In this design scheme, from each state  $S_j$  on a path  $i$ , the MS will move to the next state if the transmission is successful; otherwise, the MS will return to its previous state. This design has shorter processing time than scheme 1 when transmission fails in one state and needs to continue, e.g, in the case of same kind Base Station (BS) system exists. However, it has longer processing time when the MS needs to return to the start point, because the MS has to return to the previous state one by one.



Therefore, this scheme is suitable for a MS moving slowly and it is not in the edge between two different systems, which implies that the BS types do not change frequently to as MS roams. The main disadvantage is long processing time when the process on the path  $i$  has to be terminated during a procedure.

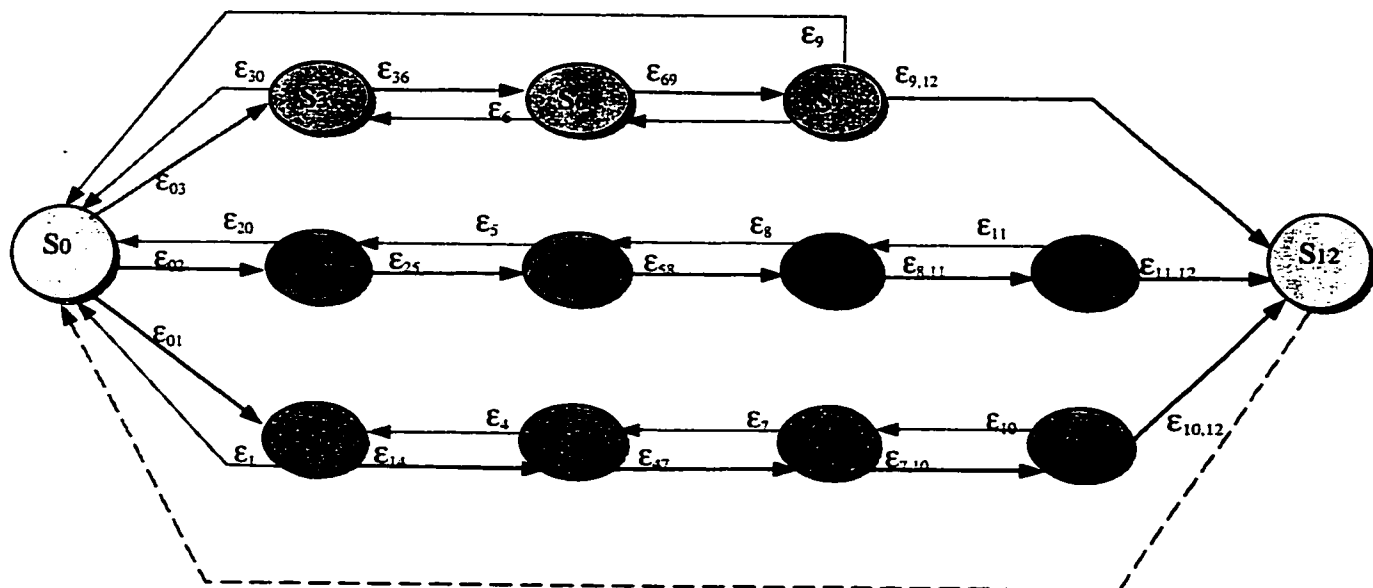


Figure 4.6 State Diagram for Connection Control of a reconfigurable Mobile Station (Scenario 26)

Table 4.6 The transitions in the state diagram (Scenario 26)

From State	S <sub>0</sub>	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	S <sub>4</sub>	S <sub>5</sub>	S <sub>6</sub>	S <sub>7</sub>	S <sub>8</sub>	S <sub>9</sub>	S <sub>10</sub>	S <sub>11</sub>	S <sub>12</sub>	T <sub>0</sub>
Cellular_DL_Request	X													S <sub>1</sub>
WLAN_DL_Request	X													S <sub>2</sub>
SameSystem_Setup	X													S <sub>3</sub>
Cellular_DL_Authen_Confirm		X												S <sub>4</sub>
WLAN_DL_Authen_Confirm			X											S <sub>5</sub>
SameSys_HO_Authen_Confirm				X										S <sub>6</sub>
Cellular SW_DL_Ready					X									S <sub>7</sub>
WLAN SW_DL_Ready						X								S <sub>8</sub>
SameSys_HO_Completed							X							S <sub>9</sub>
Cellular SW_DL_Completed								X						S <sub>10</sub>
WLAN SW_DL_Completed									X					S <sub>11</sub>
SameSys_Connected										X				S <sub>12</sub>
Cellular_Connected											X			S <sub>12</sub>
WLAN_Connected												X		S <sub>12</sub>
Process_Fails & Timeout (Auto)		X	X	X									X	S <sub>0</sub>
Cellular_DL_Authen_Failed					X									S <sub>1</sub>
WLAN_DL_Authen_Failed						X								S <sub>2</sub>
SameSys_HO_Authen_Failed							X							S <sub>3</sub>

Cellular SW_DL_Unavailable								X							S <sub>4</sub>
WLAN SW_DL_Unavailable								X							S <sub>5</sub>
SameSys_HO_Unavailable									X						S <sub>6</sub>
New System Update_Failed										X					S <sub>7</sub>
New System Update_Failed											X				S <sub>8</sub>

Where: X denotes the two states are connected and transition is possible for example.

#### 4.2.5.2 Roaming Acquisition Time Calculation

##### 1) Transition Function

There are 11 loops in the diagram, which are corresponding to the general flow graph C<sub>1</sub>, C<sub>4</sub>, C<sub>5</sub>,

C<sub>7</sub>, C<sub>11</sub>, C<sub>12</sub>, C<sub>13</sub>, C<sub>17</sub>, C<sub>21</sub>, C<sub>22</sub>, C<sub>23</sub>

$$C_1 = \epsilon_{30}\epsilon_{03}Z^{t_0+t_3}$$

$$C_5 = \epsilon_9\epsilon_{69}Z^{t_6+t_9}$$

$$C_{11} = \epsilon_5\epsilon_{25}Z^{t_2+t_5}$$

$$C_{13} = \epsilon_{11}\epsilon_{8,11}Z^{t_8+t_{11}}$$

$$C_{21} = \epsilon_4\epsilon_{14}Z^{t_1+t_4}$$

$$C_{23} = \epsilon_{10}\epsilon_{7,10}Z^{t_7+t_{10}}$$

$$C_4 = \epsilon_6\epsilon_{36}Z^{t_3+t_6}$$

$$C_7 = \epsilon_{20}\epsilon_{02}Z^{t_0+t_2}$$

$$C_{12} = \epsilon_8\epsilon_{58}Z^{t_5+t_8}$$

$$C_{17} = \epsilon_1\epsilon_{01}Z^{t_0+t_1}$$

$$C_{22} = \epsilon_7\epsilon_{47}Z^{t_4+t_7}$$

There are 44 groups of two non-touching loops :

C<sub>1</sub>C<sub>5</sub>, C<sub>1</sub>C<sub>11</sub>, C<sub>1</sub>C<sub>12</sub>, C<sub>1</sub>C<sub>13</sub>, C<sub>1</sub>C<sub>21</sub>, C<sub>1</sub>C<sub>22</sub>, C<sub>1</sub>C<sub>23</sub>, C<sub>4</sub>C<sub>7</sub>, C<sub>4</sub>C<sub>11</sub>, C<sub>4</sub>C<sub>12</sub>, C<sub>4</sub>C<sub>13</sub>, C<sub>4</sub>C<sub>17</sub>, C<sub>4</sub>C<sub>21</sub>, C<sub>4</sub>C<sub>22</sub>, C<sub>4</sub>C<sub>23</sub>, C<sub>5</sub>C<sub>7</sub>,  
C<sub>5</sub>C<sub>11</sub>, C<sub>5</sub>C<sub>12</sub>, C<sub>5</sub>C<sub>13</sub>, C<sub>5</sub>C<sub>17</sub>, C<sub>5</sub>C<sub>21</sub>, C<sub>5</sub>C<sub>22</sub>, C<sub>5</sub>C<sub>23</sub>, C<sub>7</sub>C<sub>12</sub>, C<sub>7</sub>C<sub>13</sub>, C<sub>7</sub>C<sub>21</sub>, C<sub>7</sub>C<sub>22</sub>, C<sub>7</sub>C<sub>23</sub>, C<sub>11</sub>C<sub>13</sub>, C<sub>11</sub>C<sub>17</sub>, C<sub>11</sub>C<sub>21</sub>,  
C<sub>11</sub>C<sub>22</sub>, C<sub>11</sub>C<sub>23</sub>, C<sub>12</sub>C<sub>17</sub>, C<sub>12</sub>C<sub>21</sub>, C<sub>12</sub>C<sub>22</sub>, C<sub>12</sub>C<sub>23</sub>, C<sub>13</sub>C<sub>17</sub>, C<sub>13</sub>C<sub>21</sub>, C<sub>13</sub>C<sub>22</sub>, C<sub>13</sub>C<sub>23</sub>, C<sub>17</sub>C<sub>22</sub>, C<sub>17</sub>C<sub>23</sub>, C<sub>21</sub>C<sub>23</sub>

Moreover, there are 79 groups of three non-touching loops, 62 groups of four non-touching loops, 16 groups of five non-touching loops and 1 group of five non-touching loops.

Thus,

$$\Delta(z) = 1 - (\text{sum of all different loop gains}) + (\text{sum of the gain products of two nontouching loops}) \\
- (\text{sum of the gain products of three nontouching loops}) \\
+ (\text{sum of the gain products of four nontouching loops}) \\
- (\text{sum of the gain products of five nontouching loops}) \\
+ (\text{sum of the gain products of six nontouching loops})$$

This will bring us a very complex, cumbersome transition function for this state diagram scenario. We consider a special case only, in which case the transition probability distributions of path1, 2, 3 are  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = \epsilon_{01}/\epsilon_{02}/0$ , i.e, the transition is made to S<sub>1</sub> in path1 or S<sub>2</sub> in path2 with

probability  $\epsilon_{01}$  or  $\epsilon_{02}$  respectively; the transition will not be made to path3. Then we will get the roaming acquisition time of the worst case.

There are 8 loops in the state diagram :  $C_7, C_{11}, C_{12}, C_{13}, C_{17}, C_{21}, C_{22}, C_{23}$

$$\begin{aligned} C_7 &= \epsilon_{20}\epsilon_{02}Z^{\tau_0+\tau_2} & C_{11} &= \epsilon_5\epsilon_{25}Z^{\tau_2+\tau_5} \\ C_{12} &= \epsilon_8\epsilon_{58}Z^{\tau_5+\tau_8} & C_{13} &= \epsilon_{11}\epsilon_{8,11}Z^{\tau_8+\tau_{11}} \\ C_{17} &= \epsilon_1\epsilon_{01}Z^{\tau_0+\tau_1} & C_{21} &= \epsilon_4\epsilon_{14}Z^{\tau_1+\tau_4} \\ C_{22} &= \epsilon_7\epsilon_{47}Z^{\tau_4+\tau_7} & C_{23} &= \epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}} \end{aligned}$$

There are 21 groups of two non-touching loops :

$$\begin{aligned} &C_7C_{12}, C_7C_{13}, C_7C_{21}, C_7C_{22}, C_7C_{23}, C_{11}C_{13}, C_{11}C_{17}, C_{11}C_{21}, C_{11}C_{22}, C_{11}C_{23}, C_{12}C_{17}, C_{12}C_{21}, C_{12}C_{22}, C_{12}C_{23}, \\ &C_{13}C_{17}, C_{13}C_{21}, C_{13}C_{22}, C_{13}C_{23}, C_{17}C_{22}, C_{17}C_{23}, C_{21}C_{23} \end{aligned}$$

There are 20 groups of three non-touching loops :

$$\begin{aligned} &C_7C_{12}C_{21}, C_7C_{12}C_{22}, C_7C_{12}C_{23}, C_7C_{13}C_{21}, C_7C_{13}C_{22}, C_7C_{13}C_{23}, C_7C_{21}C_{23}, C_{11}C_{13}C_{17}, C_{11}C_{13}C_{21}, C_{11}C_{13}C_{22}, C_{11}C_{13}C_{23}, \\ &C_{11}C_{17}C_{22}, C_{11}C_{17}C_{23}, C_{11}C_{21}C_{23}, C_{12}C_{17}C_{22}, C_{12}C_{17}C_{23}, C_{12}C_{21}C_{23}, C_{13}C_{17}C_{22}, C_{13}C_{17}C_{23}, C_{13}C_{21}C_{23} \end{aligned}$$

There are 5 groups of three non-touching loops

$$C_7C_{12}C_{21}C_{23}, C_7C_{13}C_{21}C_{23}, C_{11}C_{13}C_{17}C_{22}, C_{11}C_{13}C_{17}C_{23}, C_{11}C_{13}C_{21}C_{23}$$

Thus,

$$\begin{aligned} \Delta(z) &= 1 - C_7 - C_{11} - C_{12} - C_{13} - C_{17} - C_{21} - C_{22} - C_{23} + C_7 \cdot (C_{12} + C_{13} + C_{21} + C_{22} + C_{23}) + C_{11} \cdot (C_{13} + C_{17} + C_{21} + C_{22} + C_{23}) \\ &+ (C_{12} + C_{13}) \cdot (C_{17} + C_{21} + C_{22} + C_{23}) + C_{17} \cdot (C_{22} + C_{23}) + C_{21}C_{23} - C_7C_{12} \cdot (C_{21} + C_{22} + C_{23}) - C_7C_{13} \cdot (C_{21} + C_{22} + C_{23}) - C_7C_{21}C_{23} \\ &- C_{11}C_{13} \cdot (C_{17} + C_{21} + C_{22} + C_{23}) - C_{11}C_{17} \cdot (C_{22} + C_{23}) - C_{11}C_{21}C_{23} - C_{12}C_{17} \cdot (C_{22} + C_{23}) - C_{12}C_{21}C_{23} - C_{13}C_{17} \cdot (C_{22} + C_{23}) - C_{13}C_{21}C_{23} \\ &+ C_7C_{12}C_{21}C_{23} + C_7C_{13}C_{21}C_{23} + C_{11}C_{13}C_{17}C_{22} + C_{11}C_{13}C_{17}C_{23} + C_{11}C_{13}C_{21}C_{23} \\ &= 1 - \epsilon_{20}\epsilon_{02}Z^{\tau_0+\tau_2} - \epsilon_5\epsilon_{25}Z^{\tau_2+\tau_5} - \epsilon_8\epsilon_{58}Z^{\tau_5+\tau_8} - \epsilon_{11}\epsilon_{8,11}Z^{\tau_8+\tau_{11}} - \epsilon_1\epsilon_{01}Z^{\tau_0+\tau_1} - \epsilon_4\epsilon_{14}Z^{\tau_1+\tau_4} - \epsilon_7\epsilon_{47}Z^{\tau_4+\tau_7} - \epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}} + \epsilon_{20}\epsilon_{02}\epsilon_8\epsilon_{58}Z^{\tau_0+\tau_2+\tau_5+\tau_8} \\ &+ \epsilon_{20}\epsilon_{02}\epsilon_{11}\epsilon_{8,11}Z^{\tau_0+\tau_2+\tau_8+\tau_{11}} + \epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}Z^{\tau_0+\tau_2+\tau_1+\tau_4} + \epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47}Z^{\tau_0+\tau_2+\tau_4+\tau_7} + \epsilon_{20}\epsilon_{02}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_2+\tau_7+\tau_{10}} + \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}Z^{\tau_2+\tau_5+\tau_8+\tau_{11}} \\ &+ \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01}Z^{\tau_0+\tau_1+\tau_2+\tau_5} + \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14}Z^{\tau_1+\tau_4+\tau_2+\tau_5} + \epsilon_5\epsilon_{25}\epsilon_7\epsilon_{47}Z^{\tau_2+\tau_5+\tau_4+\tau_7} + \epsilon_5\epsilon_{25}\epsilon_{10}\epsilon_{7,10}Z^{\tau_2+\tau_5+\tau_7+\tau_{10}} + \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}Z^{\tau_0+\tau_1+\tau_5+\tau_8} \\ &+ \epsilon_8\epsilon_{58}\epsilon_4\epsilon_{14}Z^{\tau_1+\tau_4+\tau_5+\tau_8} + \epsilon_8\epsilon_{58}\epsilon_7\epsilon_{47}Z^{\tau_4+\tau_5+\tau_7+\tau_8} + \epsilon_8\epsilon_{58}\epsilon_{10}\epsilon_{7,10}Z^{\tau_5+\tau_7+\tau_8+\tau_{10}} + \epsilon_{11}\epsilon_{8,11}\epsilon_{01}Z^{\tau_0+\tau_1+\tau_{11}+\tau_8} + \epsilon_{11}\epsilon_{8,11}\epsilon_4\epsilon_{14}Z^{\tau_1+\tau_4+\tau_{11}+\tau_8} \\ &+ \epsilon_{11}\epsilon_{8,11}\epsilon_7\epsilon_{47}Z^{\tau_4+\tau_7+\tau_{11}+\tau_8} + \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_8+\tau_{11}+\tau_{10}} + \epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}Z^{\tau_0+\tau_1+\tau_4+\tau_7} + \epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_1+\tau_7+\tau_{10}} + \epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_1+\tau_4+\tau_7+\tau_{10}} \\ &- \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}Z^{\tau_0+\tau_2+\tau_1+\tau_4+\tau_5+\tau_8} - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47}Z^{\tau_0+\tau_2+\tau_4+\tau_7+\tau_5+\tau_8} - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_2+\tau_5+\tau_8+\tau_7+\tau_{10}} \\ &- \epsilon_{11}\epsilon_{8,11}\epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}Z^{\tau_0+\tau_2+\tau_1+\tau_4+\tau_8+\tau_{11}} - \epsilon_{11}\epsilon_{8,11}\epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47}Z^{\tau_0+\tau_2+\tau_4+\tau_7+\tau_8+\tau_{11}} - \epsilon_{11}\epsilon_{8,11}\epsilon_{20}\epsilon_{02}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_2+\tau_7+\tau_8+\tau_{10}+\tau_8+\tau_{11}} \\ &- \epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_2+\tau_1+\tau_4+\tau_7+\tau_{10}} - \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}Z^{\tau_2+\tau_5+\tau_8+\tau_{11}+\tau_8} - \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_4\epsilon_{14}Z^{\tau_2+\tau_5+\tau_1+\tau_4+\tau_{11}+\tau_8} \\ &- \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_7\epsilon_{47}Z^{\tau_2+\tau_5+\tau_4+\tau_7+\tau_8} - \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}Z^{\tau_2+\tau_5+\tau_{11}+\tau_7+\tau_8+\tau_{10}} - \epsilon_5\epsilon_{25}\epsilon_{10}\epsilon_{7,10}\epsilon_7\epsilon_{47}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_2+\tau_5} \\ &- \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_1+\tau_7+\tau_{10}+\tau_2+\tau_5} - \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_1+\tau_4+\tau_7+\tau_{10}+\tau_2+\tau_5} - \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_5+\tau_8} \\ &- \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_1+\tau_7+\tau_{10}+\tau_5+\tau_8} - \epsilon_8\epsilon_{58}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_1+\tau_4+\tau_7+\tau_{10}+\tau_5+\tau_8} - \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}\epsilon_7\epsilon_{47}Z^{\tau_0+\tau_1+\tau_4+\tau_7+\tau_8+\tau_{11}} \\ &- \epsilon_{11}\epsilon_{8,11}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_1+\tau_7+\tau_{10}+\tau_8+\tau_{11}} - \epsilon_{11}\epsilon_{8,11}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_1+\tau_4+\tau_7+\tau_{10}+\tau_8+\tau_{11}} + \epsilon_{20}\epsilon_{02}\epsilon_8\epsilon_{58}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_2+\tau_1+\tau_4+\tau_7+\tau_{10}+\tau_5+\tau_8} \\ &+ \epsilon_{20}\epsilon_{02}\epsilon_{11}\epsilon_{8,11}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_0+\tau_2+\tau_1+\tau_4+\tau_7+\tau_{10}+\tau_8+\tau_{11}} + \epsilon_7\epsilon_{47}\epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_1\epsilon_{01}Z^{\tau_2+\tau_5+\tau_0+\tau_1+\tau_{11}+\tau_8+\tau_4+\tau_7} \\ &+ \epsilon_{10}\epsilon_{7,10}\epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_1\epsilon_{01}Z^{\tau_2+\tau_5+\tau_0+\tau_1+\tau_{11}+\tau_8+\tau_7+\tau_{10}} + \epsilon_4\epsilon_{14}\epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}Z^{\tau_1+\tau_4+\tau_2+\tau_5+\tau_{11}+\tau_7+\tau_8+\tau_{10}} \end{aligned}$$

There are 2 forward paths :

Forward path1:  $F_1 = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}Z^{10+\tau_1+\tau_4+\tau_7+\tau_{10}}$ ,

$$\Delta_1 = 1 - C_{11} - C_{12} - C_{13} + C_{11}C_{13} = 1 - \epsilon_5\epsilon_{25}Z^{\tau_2+\tau_5} - \epsilon_8\epsilon_{58}Z^{\tau_5+\tau_8} - \epsilon_{11}\epsilon_{8,11}Z^{\tau_8+\tau_{11}} + \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}Z^{\tau_2+\tau_5+\tau_8+\tau_{11}}$$

Forward path2:  $F_2 = \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}Z^{10+\tau_2+\tau_5+\tau_8+\tau_{11}}$ ,

$$\Delta_2 = 1 - C_{21} - C_{22} - C_{23} + C_{21}C_{23} = 1 - \epsilon_4\epsilon_{14}Z^{\tau_1+\tau_4} - \epsilon_7\epsilon_{47}Z^{\tau_4+\tau_7} - \epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}} + \epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_1+\tau_4+\tau_7+\tau_{10}}$$

$$F(z) = F_1 * \Delta_1 + F_2 * \Delta_2 = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}Z^{10+\tau_1+\tau_4+\tau_7+\tau_{10}} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_5\epsilon_{25}Z^{\tau_2+\tau_5+10+\tau_1+\tau_4+\tau_7+\tau_{10}} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_8\epsilon_{58}Z^{\tau_5+\tau_8+10+\tau_1+\tau_4+\tau_7+\tau_{10}} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_{11}\epsilon_{8,11}Z^{10+\tau_1+\tau_4+\tau_7+\tau_{10}+\tau_8+\tau_{11}} + \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}Z^{\tau_2+\tau_5+\tau_8+\tau_{11}+10+\tau_1+\tau_4+\tau_7+\tau_{10}} + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}Z^{10+\tau_2+\tau_5+\tau_8+\tau_{11}} - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_4\epsilon_{14}Z^{\tau_1+\tau_4+10+\tau_2+\tau_5+\tau_8+\tau_{11}} - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_7\epsilon_{47}Z^{\tau_4+\tau_7+10+\tau_2+\tau_5+\tau_8+\tau_{11}} - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_{10}\epsilon_{7,10}Z^{\tau_7+\tau_{10}+10+\tau_2+\tau_5+\tau_8+\tau_{11}} + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}Z^{\tau_1+\tau_4+\tau_7+\tau_{10}+10+\tau_2+\tau_5+\tau_8+\tau_{11}}$$

Then, according to the definition given in equation (4.2), we get the transition function of this

state diagram in special case  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = \epsilon_{01}/\epsilon_{02}/0$ :

$$H(z) = \frac{F_1 * \Delta_1 + F_2 * \Delta_2 + F_3 * \Delta_3}{\Delta(z)} = \frac{F(z)}{\Delta(z)}$$

$$\frac{dH(z)}{dz} = \frac{F'(z)}{\Delta(z)} - \frac{F(z) * \Delta'(z)}{\Delta^2(z)}$$

Where:

$$F'(z) = \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}(\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_{10})Z^{10+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_5\epsilon_{25}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_{10})Z^{\tau_2+\tau_5+10+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_8\epsilon_{58}(\tau_0 + \tau_1 + \tau_4 + \tau_5 + \tau_7 + \tau_8 + \tau_{10})Z^{\tau_5+\tau_8+10+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_{11}\epsilon_{8,11}(\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_8 + \tau_{10} + \tau_{11})Z^{10+\tau_1+\tau_4+\tau_7+\tau_{10}+\tau_8+\tau_{11}-1} + \epsilon_{01}\epsilon_{14}\epsilon_{47}\epsilon_{7,10}\epsilon_{10,12}\epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_8 + \tau_{10} + \tau_{11})Z^{\tau_2+\tau_5+\tau_8+\tau_{11}+10+\tau_1+\tau_4+\tau_7+\tau_{10}-1} + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}(\tau_0 + \tau_2 + \tau_5 + \tau_8 + \tau_{11})Z^{10+\tau_2+\tau_5+\tau_8+\tau_{11}-1} - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_4\epsilon_{14}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_1+\tau_4+10+\tau_2+\tau_5+\tau_8+\tau_{11}-1} - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_7\epsilon_{47}(\tau_0 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_8 + \tau_{11})Z^{\tau_4+\tau_7+10+\tau_2+\tau_5+\tau_8+\tau_{11}-1} - \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_{10}\epsilon_{7,10}(\tau_0 + \tau_2 + \tau_5 + \tau_7 + \tau_8 + \tau_{10} + \tau_{11})Z^{\tau_7+\tau_{10}+10+\tau_2+\tau_5+\tau_8+\tau_{11}-1} + \epsilon_{02}\epsilon_{25}\epsilon_{58}\epsilon_{8,11}\epsilon_{11,12}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_8 + \tau_{10} + \tau_{11})Z^{\tau_1+\tau_4+\tau_7+\tau_{10}+10+\tau_2+\tau_5+\tau_8+\tau_{11}-1}$$

$$\Delta'(z) = -\epsilon_{20}\epsilon_{02}(\tau_0 + \tau_2)Z^{10+\tau_2-1} - \epsilon_5\epsilon_{25}(\tau_2 + \tau_5)Z^{\tau_2+\tau_5-1} - \epsilon_8\epsilon_{58}(\tau_5 + \tau_8)Z^{\tau_5+\tau_8-1} - \epsilon_{11}\epsilon_{8,11}(\tau_8 + \tau_{11})Z^{\tau_8+\tau_{11}-1} - \epsilon_1\epsilon_{01}(\tau_0 + \tau_1)Z^{10+\tau_1-1} - \epsilon_4\epsilon_{14}(\tau_1 + \tau_4)Z^{\tau_1+\tau_4-1} - \epsilon_7\epsilon_{47}(\tau_4 + \tau_7)Z^{\tau_4+\tau_7-1} - \epsilon_{10}\epsilon_{7,10}(\tau_7 + \tau_{10})Z^{\tau_7+\tau_{10}-1} + \epsilon_{20}\epsilon_{02}\epsilon_8\epsilon_{58}(\tau_0 + \tau_2 + \tau_5 + \tau_8)Z^{10+\tau_2+\tau_5+\tau_8-1} + \epsilon_{20}\epsilon_{02}\epsilon_{11}\epsilon_{8,11}(\tau_0 + \tau_2 + \tau_8 + \tau_{11})Z^{10+\tau_2+\tau_8+\tau_{11}-1} + \epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}(\tau_0 + \tau_1 + \tau_2 + \tau_4)Z^{10+\tau_2+\tau_1+\tau_4-1} + \epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47}(\tau_0 + \tau_2 + \tau_4 + \tau_7)Z^{10+\tau_2+\tau_4+\tau_7-1} + \epsilon_{20}\epsilon_{02}\epsilon_{10}\epsilon_{7,10}(\tau_0 + \tau_2 + \tau_7 + \tau_{10})Z^{10+\tau_2+\tau_7+\tau_{10}-1} + \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}(\tau_2 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_2+\tau_5+\tau_8+\tau_{11}-1} + \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01}(\tau_0 + \tau_1 + \tau_2 + \tau_5)Z^{10+\tau_1+\tau_2+\tau_5-1} + \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14}(\tau_1 + \tau_2 + \tau_4 + \tau_5)Z^{\tau_1+\tau_2+\tau_4+\tau_5-1} + \epsilon_5\epsilon_{25}\epsilon_7\epsilon_{47}(\tau_2 + \tau_4 + \tau_5 + \tau_7)Z^{\tau_2+\tau_4+\tau_5+\tau_7-1} + \epsilon_5\epsilon_{25}\epsilon_{10}\epsilon_{7,10}(\tau_2 + \tau_5 + \tau_7 + \tau_{10})Z^{\tau_2+\tau_5+\tau_7+\tau_{10}-1} + \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}(\tau_0 + \tau_1 + \tau_5 + \tau_8)Z^{10+\tau_1+\tau_5+\tau_8-1} + \epsilon_8\epsilon_{58}\epsilon_4\epsilon_{14}(\tau_1 + \tau_4 + \tau_5 + \tau_8)Z^{\tau_1+\tau_4+\tau_5+\tau_8-1} + \epsilon_8\epsilon_{58}\epsilon_7\epsilon_{47}(\tau_4 + \tau_5 + \tau_7 + \tau_8)Z^{\tau_4+\tau_5+\tau_7+\tau_8-1} + \epsilon_8\epsilon_{58}\epsilon_{10}\epsilon_{7,10}(\tau_5 + \tau_7 + \tau_8 + \tau_{10})Z^{\tau_5+\tau_7+\tau_8+\tau_{10}-1} + \epsilon_{11}\epsilon_{8,11}\epsilon_1\epsilon_{01}(\tau_0 + \tau_1 + \tau_8 + \tau_{11})Z^{10+\tau_1+\tau_8+\tau_{11}-1} + \epsilon_{11}\epsilon_{8,11}\epsilon_4\epsilon_{14}(\tau_1 + \tau_4 + \tau_8 + \tau_{11})Z^{\tau_1+\tau_4+\tau_8+\tau_{11}-1} + \epsilon_{11}\epsilon_{8,11}\epsilon_7\epsilon_{47}(\tau_4 + \tau_7 + \tau_8 + \tau_{11})Z^{\tau_4+\tau_7+\tau_8+\tau_{11}-1} + \epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}(\tau_7 + \tau_8 + \tau_{10} + \tau_{11})Z^{\tau_7+\tau_8+\tau_{10}+\tau_{11}-1} + \epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}(\tau_0 + \tau_1 + \tau_4 + \tau_7)Z^{10+\tau_1+\tau_4+\tau_7-1} + \epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7,10}(\tau_0 + \tau_1 + \tau_7 + \tau_{10})Z^{10+\tau_1+\tau_7+\tau_{10}-1} + \epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}(\tau_1 + \tau_4 + \tau_7 + \tau_{10})Z^{\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_8)Z^{10+\tau_2+\tau_1+\tau_4+\tau_5+\tau_8-1} - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47}(\tau_0 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_8)Z^{10+\tau_2+\tau_4+\tau_5+\tau_7+\tau_8-1} - \epsilon_8\epsilon_{58}\epsilon_{20}\epsilon_{02}\epsilon_{10}\epsilon_{7,10}(\tau_0 + \tau_2 + \tau_5 + \tau_7 + \tau_8 + \tau_{10})Z^{10+\tau_2+\tau_5+\tau_7+\tau_8+\tau_{10}-1} - \epsilon_{11}\epsilon_{8,11}\epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_8 + \tau_{11})Z^{10+\tau_2+\tau_1+\tau_4+\tau_8+\tau_{11}-1} - \epsilon_{11}\epsilon_{8,11}\epsilon_{20}\epsilon_{02}\epsilon_7\epsilon_{47}(\tau_0 + \tau_2 + \tau_4 + \tau_7 + \tau_8 + \tau_{11})Z^{10+\tau_2+\tau_4+\tau_7+\tau_8+\tau_{11}-1} - \epsilon_{20}\epsilon_{02}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_7 + \tau_{10})Z^{10+\tau_2+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_1\epsilon_{01}(\tau_0 + \tau_1 + \tau_2 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_2+\tau_5+\tau_8+\tau_{11}+10+\tau_1+\tau_4+\tau_7+\tau_{10}-1} - \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_4\epsilon_{14}(\tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_8 + \tau_{11})Z^{\tau_2+\tau_5+\tau_4+\tau_5+\tau_8+\tau_{11}-1} - \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_7\epsilon_{47}(\tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_8 + \tau_{11})Z^{\tau_2+\tau_5+\tau_4+\tau_5+\tau_7+\tau_8+\tau_{11}-1} - \epsilon_5\epsilon_{25}\epsilon_{11}\epsilon_{8,11}\epsilon_{10}\epsilon_{7,10}(\tau_2 + \tau_5 + \tau_7 + \tau_8 + \tau_{10} + \tau_{11})Z^{\tau_2+\tau_5+\tau_7+\tau_8+\tau_{10}+\tau_{11}-1} - \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}(\tau_0 + \tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_7)Z^{10+\tau_1+\tau_2+\tau_4+\tau_5+\tau_7-1} - \epsilon_5\epsilon_{25}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7,10}(\tau_0 + \tau_1 + \tau_2 + \tau_5 + \tau_7 + \tau_{10})Z^{10+\tau_1+\tau_2+\tau_5+\tau_7+\tau_{10}-1} - \epsilon_5\epsilon_{25}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}(\tau_1 + \tau_2 + \tau_4 + \tau_5 + \tau_7 + \tau_{10})Z^{\tau_1+\tau_2+\tau_4+\tau_5+\tau_7+\tau_{10}-1} - \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}(\tau_0 + \tau_1 + \tau_4 + \tau_5 + \tau_7 + \tau_8)Z^{10+\tau_1+\tau_4+\tau_5+\tau_7+\tau_8-1} - \epsilon_8\epsilon_{58}\epsilon_1\epsilon_{01}\epsilon_{10}\epsilon_{7,10}(\tau_0 + \tau_1 + \tau_5 + \tau_7 + \tau_8 + \tau_{10})Z^{10+\tau_1+\tau_5+\tau_7+\tau_8+\tau_{10}-1} - \epsilon_8\epsilon_{58}\epsilon_4\epsilon_{14}\epsilon_{10}\epsilon_{7,10}(\tau_1 + \tau_4 + \tau_5 + \tau_7 + \tau_8 + \tau_{10})Z^{\tau_1+\tau_4+\tau_5+\tau_7+\tau_8+\tau_{10}-1} - \epsilon_{11}\epsilon_{8,11}\epsilon_1\epsilon_{01}\epsilon_7\epsilon_{47}(\tau_0 + \tau_1 + \tau_4 + \tau_7 + \tau_8 + \tau_{11})Z^{10+\tau_1+\tau_4+\tau_7+\tau_8+\tau_{11}-1}$$



## Chapter 5 Test Results

### 5.1 Possible Cases

As we have discussed in the previous section, the mobile station operates on the universal base station and its channels when it is in the state  $S_0, S_1, S_2, S_4, S_5, S_7, S_8$ , and operates on the classical base station and its channels when it is in the state  $S_3, S_6, S_9, S_{12}$  in path 3, state  $S_{10}, S_{11}, S_{12}$  in path 1 & path 2. Also, in normal case, the data rate or bit rate of the universal pilot channel and data channel may be different from that of the classical channel, and the data rate or bit rate in different mobile systems are also different. Therefore, one should consider those factors for precise time estimation.

During the mobile station connection establishment signaling period, we assume that the signaling bit rates in the classical base station channels of different mobile systems are the same, take 50Kb/s for example, our results are general though could apply to any signaling rate. The propagation delay time in the link is not taken into account in this project, and the estimation method will be no different from the current mobile communication system.

We condition the various acquisition time on the starting point and the final point, i.e., the acquisition time for updating a new system is related to the starting and target system. For instance, if the user wants to use the CDMA IS-95 network now, then the acquisition time to authenticate, associate and download this system software code are different from other cases where mobile station is currently in GSM or wireless LAN (because of the different number of bits required).

Next, we will present the six possible cases and build up the tables listing the size of code for listening, authentication, association, downloaded software, connection establishment

signaling and the minimum time in each state (they are approximations). The values of code size, bit rate and time satisfy the following equation:

The minimum time  $T_i = \text{Size of Code in Number bits} / \text{Channel Bit Rate}$

Then, the total time  $\tau_i$  spent in each state  $S_i$  can be easily found by  $\tau_i = T_i/P_i$  –equation (3.2), which will be used for evaluation input values in the following.

We assume that:

- The signaling bit rates of different cellular systems are the same as  $R_{\text{cell}} = 50\text{Kb/s}$  and the signaling bit rates of wireless LAN is  $R_{\text{bWLAN}} = 50\text{Kb/s}$  during the mobile station connection establishing signaling period, without losing any generality of our results, this is one example.
- The total time spent in start state  $\tau_0 = 50\text{ms}$ , and 1 packet = 1Kbits.

**Case 1:** When the mobile station starts from GSM and moves to other mobile systems, the required size of code, the number of packets, and the minimum time spent in each state will be different. Their relative values are shown in Table 5.1(a) and Table 5.1(b), since one packet contains 1Kbits, then one packet transmission time  $T_p = 10\text{ms}$  if the transmission bit rate  $R_b = 100\text{Kb/s}$ .

**Table 5.1(a)** The required number of kilo-bits and packets in each state for the transition from GSM to the other wireless systems.

$T_0$ Size of code in each state $S_i$ (Kb)/(Packets)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$S_1/S_2/S_3$	40	100	100	100	100	100	100	20
$S_4/S_5/S_6$	50	200	200	150	150	120	200	50
$S_7/S_8$	200	1,500	2,000	500	500	1,000	1,000	---
$S_9/S_{10}/S_{11}$	150	200	200	150	150	100	300	150
Total Bit/ Packets	440K /440	2,000K /2,000	2,500K /2,500	900K /900	900K /900	1,320K /1,320	1,600K /1,600	220K /220

We assume that the signaling bit rates of different cellular mobile systems are same as  $R_{bcell} = 50\text{Kb/s}$  and the signaling bit rates of wireless LAN is  $R_{bWLAN} = 50\text{Kb/s}$  during the mobile station connection establishment signaling period, again without losing generality and applicability of our techniques. If the bit rate in universal channels is  $R_b = 100\text{Kb/s}$ , we can derive the following Table 5.1(b) from Table 5.1(a).

**Table 5.1(b)** The minimum time spent in each state for the transition from GSM to one of the other wireless systems. ( $R_b = 100\text{Kb/s}$ )

$T_o$ Minimum time in each state $S_i$ (ms)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$T_1/T_2/T_3$	400	1,000	1,000	1,000	1,000	1,000	1,000	400
$T_4/T_5/T_6$	500	2,000	2,000	1,500	1,500	1,200	2,000	1,000
$T_7/T_8$	2,000	15,000	20,000	5,000	5,000	10,000	10,000	---
$T_9/T_{10}/T_{11}$	3,000	4,000	4,000	3,000	3,000	2,000	6,000	3,000

If the universal channel bit rate  $R_b = 50\text{Kb/s}$  or  $R_b = 200\text{Kb/s}$ , we can derive the following Table 5.1(c) and Table 5.1(d) from Table 5.1(a).

**Table 5.1(c)** The minimum time spent in each state for the transition from GSM to one of the following system. ( $R_b = 50\text{Kb/s}$ )

$T_o$ Minimum time in each state $S_i$ (ms)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$T_1/T_2/T_3$	800	2,000	2,000	2,000	2,000	2,000	2,000	400
$T_4/T_5/T_6$	1000	4,000	4,000	3,000	3,000	2,400	4,000	1,000
$T_7/T_8$	4,000	30,000	40,000	10,000	10,000	20,000	20,000	---
$T_9/T_{10}/T_{11}$	3,000	4,000	4,000	3,000	3,000	2,000	6,000	3,000

**Table 5.1(d)** The minimum time spent in each state for the transition from GSM to one of the following system. ( $R_b = 200\text{Kb/s}$ )

$T_o$ Minimum time in each state $S_i$ (ms)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$T_1/T_2/T_3$	200	500	500	500	500	500	500	400
$T_4/T_5/T_6$	250	1,000	1,000	750	750	600	1000	1,000
$T_7/T_8$	1,000	7,500	10,000	2,500	2,500	5,000	5,000	---
$T_9/T_{10}/T_{11}$	3,000	4,000	4,000	3,000	3,000	2,000	6,000	3,000



**Case 2:** When the mobile station starts from TDMA system IS-54 or IS-136 and moves to the other wireless systems, then the required size of code, the number of packets, and the minimum time spent in each state will be different. Their relative values are shown in Table 5.2 (a) and Table 5.2(b), since one packet contains 1Kbits, one packet transmission time  $T_p = 10\text{ms}$  if the transmission bit rate  $R_b = 100 \text{ Kb/s}$ .

**Table 5.2(a)** The required number of kilo-bits and packets in each state for the transition from TDMA IS-54 to the other wireless systems.

<i>To</i> Size of code in each state $S_i$ (Kb)/(Packets)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$S_1/S_2/S_3$	100	40	100	100	100	100	100	20
$S_4/S_5/S_6$	200	50	200	150	150	120	200	50
$S_7/S_8$	1,500	200	2,000	500	500	1,000	1,000	---
$S_9/S_{10}/S_{11}$	150	200	200	150	150	100	300	150
Total Bit/ Packets	1,950K /1,950	490K /490	2,500K /2,500	900K /900	900K /900	1,320K /1,320	1,600K /1,600	220K /220

We assume that the signaling bit rates of different cellular systems are same as  $R_{\text{bcell}} = 50\text{Kb/s}$  and the signaling bit rates of wireless LAN is  $R_{\text{bWLAN}} = 50\text{Kb/s}$  during the mobile station connection establishment signaling period. If the bit rate in universal channels is  $R_b = 100\text{Kb/s}$ , we can derive the following Table 5.2(b) from Table 5.2(a).

**Table 5.2(b)** The minimum time spent in each state for the transition from TDMA IS-54 to the other wireless systems. ( $R_b = 100\text{Kb/s}$ )

<i>To</i> Minimum time in each state $S_i$ (ms)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$T_1/T_2/T_3$	1,000	400	1,000	1,000	1,000	1,000	1,000	400
$T_4/T_5/T_6$	2,000	500	2,000	1,500	1,500	1,200	2,000	1,000
$T_7/T_8$	15,000	2,000	20,000	5,000	5,000	10,000	10,000	---
$T_9/T_{10}/T_{11}$	3,000	4,000	4,000	3,000	3,000	2,000	6,000	3,000

**Case 3:** When the mobile station starts from CDMA system IS-95 or 3G and moves to the other wireless systems, then the required size of code, the number of packets, and the minimum time spent in each state will be different. Their relative values are shown in Table 5.3(a) and Table 5.3(b), since one packet contains 1Kbits, one packet transmission time  $T_p = 10\text{ms}$  if the transmission bit rate  $R_b = 100\text{Kb/s}$ .

**Table 5.3 (a)** The required number of kilo-bits and packets in each state for the transition from CDMA system to the other wireless systems.

<i>To</i> Size of code in each state $S_i$ (Kb)/(Packets)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$S_1/S_2/S_3$	150	150	50	80	80	120	100	50
$S_4/S_5/S_6$	200	200	50	100	100	120	200	50
$S_7/S_8$	2,000	2,000	200	800	800	1,000	800	---
$S_9/S_{10}/S_{11}$	150	200	200	150	150	100	300	200
Total Bit/ Packets	2,500K /2,500	2,550K /2,550	500K /500	1,130K /1,130	1,130K /1,130	1,320K /1,320	1,400K /1,400	300K /300

We assume that the signaling bit rates of different cellular systems are same as  $R_{\text{bcell}} = 50\text{Kb/s}$  and the signaling bit rates of wireless LAN is  $R_{\text{bWLAN}} = 50\text{Kb/s}$  during the mobile station connection establishment signaling period. If the bit rate in universal channels is  $R_b = 100\text{Kb/s}$ , we can derive Table 5.3(b) from Table 5.3(a).

**Table 5.3(b)** The minimum time spent in each state for the transition from CDMA system to the other wireless systems. ( $R_b = 100\text{Kb/s}$ )

<i>To</i> Minimum time in each state $S_i$ (ms)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$T_1/T_2/T_3$	1,500	1,500	500	800	800	1,200	1,000	1,000
$T_4/T_5/T_6$	2,000	2,000	500	1,000	1,000	1,200	2,000	1,000
$T_7/T_8$	20,000	20,000	2,000	8,000	8,000	10,000	8,000	---
$T_9/T_{10}/T_{11}$	3,000	4,000	4,000	3,000	3,000	2,000	6,000	4,000

**Case 4:** When the mobile station starts from DECT cordless system and moves to other wireless systems, the required size of code, the number of packets, and the minimum time spent in each state will be different. Their relative values are shown in Table 5.4(a) and Table 5.4(b), since one packet contains 1Kbits, one packet transmission time  $T_p = 10\text{ms}$  if the transmission bit rate  $R_b = 100\text{Kb/s}$ .

**Table 5.4(a)** The required number of kilo-bits and packets in each state for the transition from DECT to the other wireless systems.

<i>To</i> Size of code in each state $S_i$ (Kb)/(Packets)	Cellular System					Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz		
$S_1/S_2/S_3$	100	100	100	100	100	150	20
$S_4/S_5/S_6$	200	200	200	150	150	200	30
$S_7/S_8$	1,500	1,500	2,000	500	500	1,000	---
$S_9/S_{10}/S_{11}$	150	200	200	150	150	300	150
Total Bit/ Packets	1,950K /1,950	2,000K /2,000	2,500K /2,500	900K /900	900K /900	1,650K /1,650	200K /200

We assume that the signaling bit rates of different cellular systems are same as  $R_{b\text{cell}} = 50\text{Kb/s}$  and the signaling bit rates of wireless LAN is  $R_{b\text{WLAN}} = 50\text{Kb/s}$  during the mobile station connection establishment signaling period. If the bit rate in universal channels is  $R_b = 100\text{Kb/s}$ , we can derive the following Table 5.4(a) from Table 5.4(b).

**Table 5.4(b)** The minimum time spent in each state for the transition from DECT to the other wireless systems. ( $R_b = 100\text{Kb/s}$ )

<i>To</i> Minimum time in each state $S_i$ (ms)	Cellular System					Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz		
$T_1/T_2/T_3$	1,000	1,000	1,000	1,000	1,000	1,500	400
$T_4/T_5/T_6$	2,000	2,000	2,000	1,500	1,500	2,000	600
$T_7/T_8$	15,000	15,000	20,000	5,000	5,000	10,000	---
$T_9/T_{10}/T_{11}$	3,000	4,000	4,000	3,000	3,000	6,000	3,000

**Case 5:** When the mobile station starts from AMPS or CDPD and moves to other wireless systems, the required size of code, the number of packets, and the minimum time spent in each state will be different. Their relative values are shown in Table 5.5(a) and Table 5.5(b), since one packet contains 1Kbits, one packet transmission time  $T_p = 10\text{ms}$  if the transmission bit rate  $R_b = 100\text{Kb/s}$ .

**Table 5.5(a)** The required kilo-bits and packets in each state for the transition from AMPS/CDPD to the other wireless systems.

<i>To</i> Size of code in each state $S_i$ (Kb)/(Packets)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$S_1/S_2/S_3$	100	100	100	20	20	100	100	50
$S_4/S_5/S_6$	200	150	200	500	500	120	200	50
$S_7/S_8$	1,500	1,500	2,000	300	300	1,000	1,000	---
$S_9/S_{10}/S_{11}$	150	200	200	150	150	100	300	200
Total Bit/ Packets	1,950K /1,950	1,950K /1,950	2,500K /2,500	970K /970	970K /970	1,320K /1,320	1,600K /1,600	300K /300

We assume that the signaling bit rates of different cellular systems are same as  $R_{b\text{cell}} = 50\text{Kb/s}$  and the signaling bit rates of wireless LAN is  $R_{b\text{WLAN}} = 50\text{Kb/s}$  during the mobile station connection establishment signaling period. If the bit rate in universal channels is  $R_b = 100\text{Kb/s}$ , we can derive the following Table 5.5(b) from Table 5.5(a).

**Table 5.5(b)** The minimum time spent in each state for the transition from AMPS/CDPD to the other wireless systems. ( $R_b = 100\text{Kb/s}$ )

<i>To</i> Minimum time in each state $S_i$ (ms)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$T_1/T_2/T_3$	1,000	1,000	1,000	200	200	1,000	1,000	1,000
$T_4/T_5/T_6$	2,000	1,500	2,000	5,000	5,000	1,200	2,000	1,000
$T_7/T_8$	15,000	15,000	20,000	3,000	3,000	10,000	10,000	---
$T_9/T_{10}/T_{11}$	3,000	4,000	4,000	3,000	3,000	2,000	6,000	4,000

**Case 6:** When the mobile station starts from wireless local area network (WLAN) and moves to other wireless systems, the required size of code, the number of packets, and the minimum time spent in each state will be different. Their relative values are shown in Table 5.6(a) and Table 5.6(b), since one packet contains 1Kbits, one packet transmission time  $T_p = 10\text{ms}$  if the transmission bit rate  $R_b = 100\text{Kb/s}$ .

**Table 5.6(a)** The required number of kilo-bits and packets in each state for the transition from WLAN to the other wireless systems.

<i>To</i> Size of code in each state $S_i$ (Kb)/(Packets)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$S_1/S_2/S_3$	100	100	100	100	100	100	100	50
$S_4/S_5/S_6$	200	200	200	50	50	120	200	50
$S_7/S_8$	2,500	2,500	2,000	800	800	1,000	500	---
$S_9/S_{10}/S_{11}$	150	200	200	150	150	100	300	200
Total Bit/ Packets	2,950K /2,950	3,000K /3,000	2,500K /2,500	1,100K /1,100	1,100K /1,100	1,320K /1,320	1,100K /1,100	300K /300

We assume that the signaling bit rates of different cellular systems are same as  $R_{\text{bcell}} = 50\text{Kb/s}$  and the signaling bit rates of wireless LAN is  $R_{\text{bWLAN}} = 50\text{Kb/s}$  during the mobile station connection establishment signaling period. If the bit rate in universal channels is  $R_b = 100\text{Kb/s}$ , we can derive the following Table 5.6(b) from Table 5.6(a).

**Table 5.6(b)** The minimum time spent in each state for the transition from WLAN to the other wireless systems. ( $R_b = 100\text{Kb/s}$ )

<i>To</i> Minimum time in each state $S_i$ (ms)	Cellular System					Cordless	Wireless LAN 2.4GHz, 5GHz	Same System
	GSM 900,1800MHz	TDMA IS-54,IS-136	CDMA IS-95, 3G	AMPS 800 MHz	CDPD 800MHz	DECT 1800 MHz		
$T_1/T_2/T_3$	1,000	1,000	1,000	1,000	1,000	1,000	1,000	1,000
$T_4/T_5/T_6$	2,000	2,000	2,000	500	500	1,200	2,000	1,000
$T_7/T_8$	25,000	25,000	20,000	8,000	8,000	10,000	5,000	---
$T_9/T_{10}/T_{11}$	3,000	4,000	4,000	3,000	3,000	2,000	6,000	4,000

Besides the above assumptions, we further assume that:

- 1) The resource blocking probabilities of the universal base station and the classical base station in each state are the same, let  $P_{s_u} = P_{s_c} = P_s$  so called system resource blocking probability.
- 2) The mobile station (MS) resource blocking probability in each state is the same, denoted as  $P_m$ .
- 3) The packet successful transmission probability in each state is the same, denoted as  $P_i$ .

Then, we can find the relationship between the roaming connection establishment acquisition time **Tsum** (called roaming acquisition time for convenience) and *packet successful transmission probability over radio channel  $P_i$*  (Section 5.2), *system resource blocking probability  $P_s$*  (Section 5.3), *mobile station resource blocking probability  $P_m$*  (Section 5.4), and *signaling bit rate over the universal base station channel  $R_b$*  (Section 5.5) for different cases and design scenarios. The roaming acquisition time Tsum in design scenario number 1, 6, 19, 20, 26 can be found by equation given by (4.6), (4.7), (4.8), (4.9), and (4.10) respectively.

In the following sections, we will compute the roaming time performance for the designed scenario number 1 in case 1, 2, 3, 4, 5, 6 listed above (Section 5.6). For other designed scenarios, we take case 1 for evaluation only, because the mobile station operates similarly in case 1, 2, 3, 4, 5, 6.

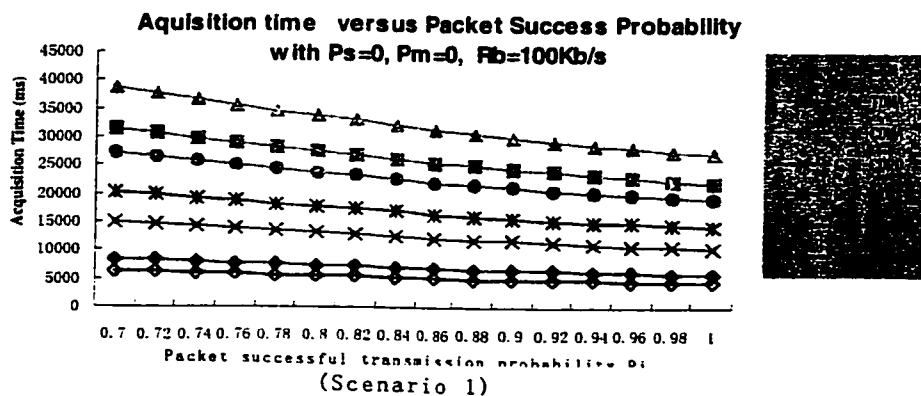
It is also noted that the relationship between the average roaming acquisition time and the initial path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  is evaluated under the worst case assumption that:

- The cellular system download path 1 has the largest software (SW) code size system for downloading. For example, CDMA system SW code in case 1, 2, 4, 5, TDMA IS-54 system SW code size in case 3, 6.
- The wireless LAN system download path 2 has the largest software (SW) code size system for downloading.

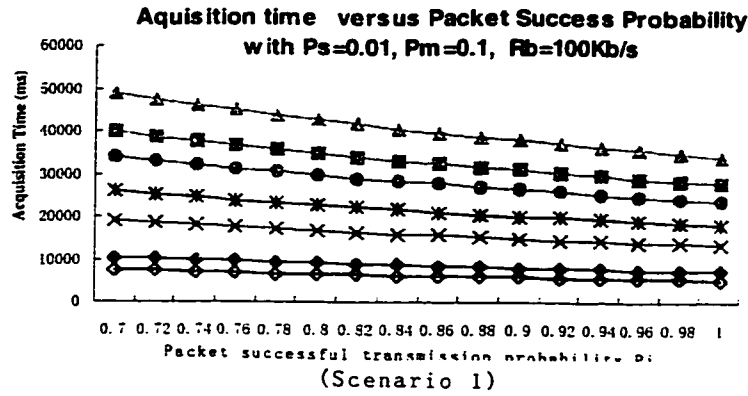
## 5.2 Roaming Acquisition Time Versus Packet Successful Transmission Probability

Taking the minimum time value  $T_i$  in Table 5.1 (b) for evaluation, the total time  $\tau_i$  spent in each state can be found by  $\tau_i = T_i/P_i$  –equation (3.2).

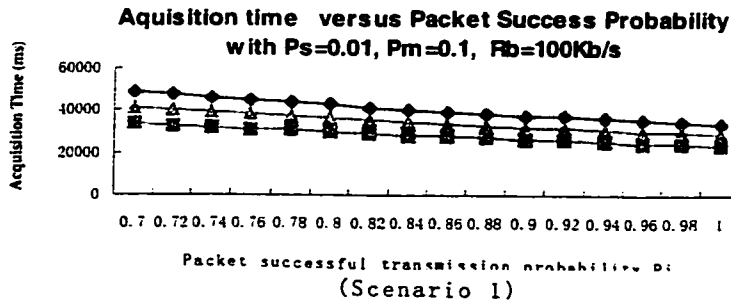
### 5.2.1 Scenario Number 1:



**Figure 5.1(a)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 1, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0$ , and MS resource blocking probability  $P_m=0$ .

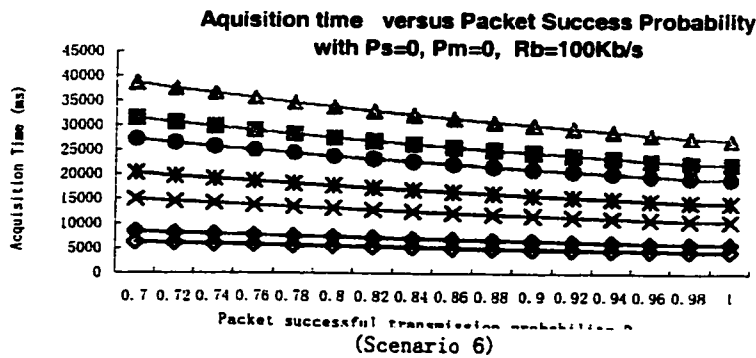


**Figure 5.1(b)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 1, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ .



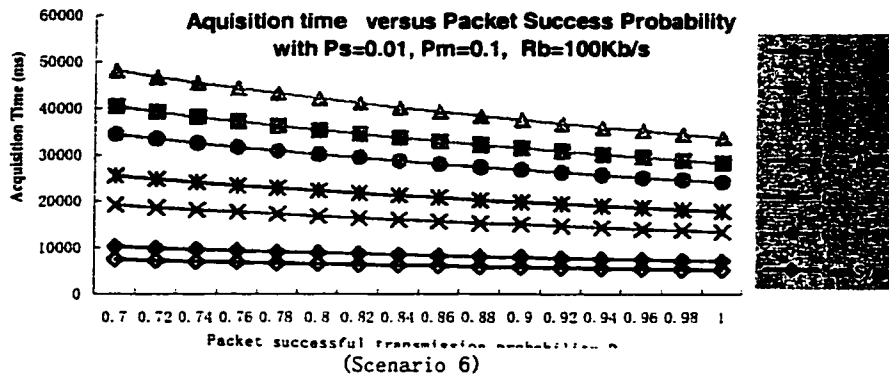
**Figure 5.1(c)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 1, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/1/0$ ,  $0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.2.2 Scenario Number 6:

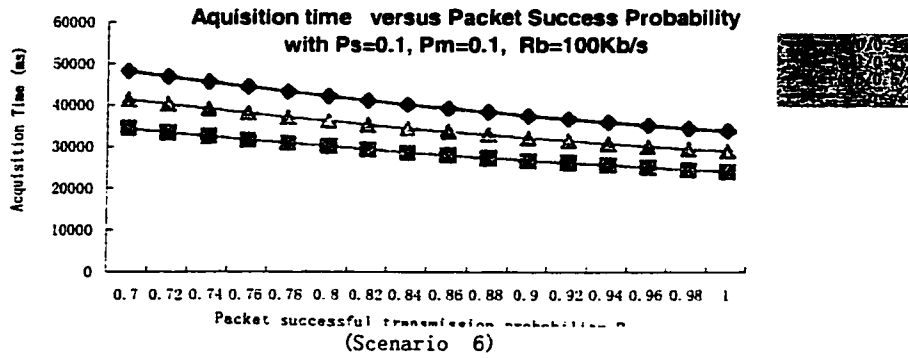


**Figure 5.2(a)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 6, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0$ , and MS resource blocking probability  $P_m=0$ .



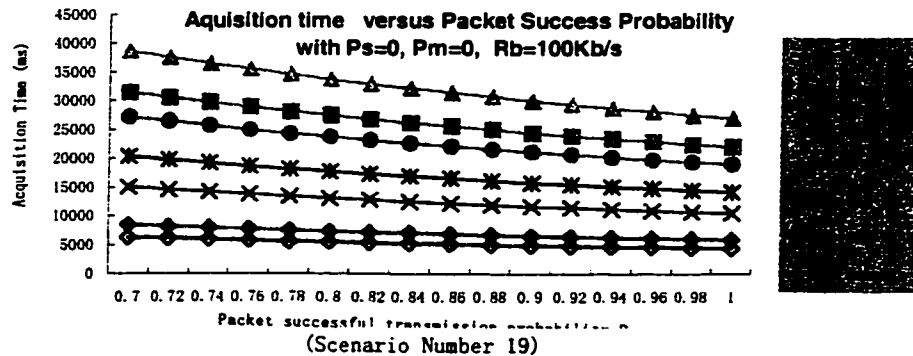


**Figure 5.2(b)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 6, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ .

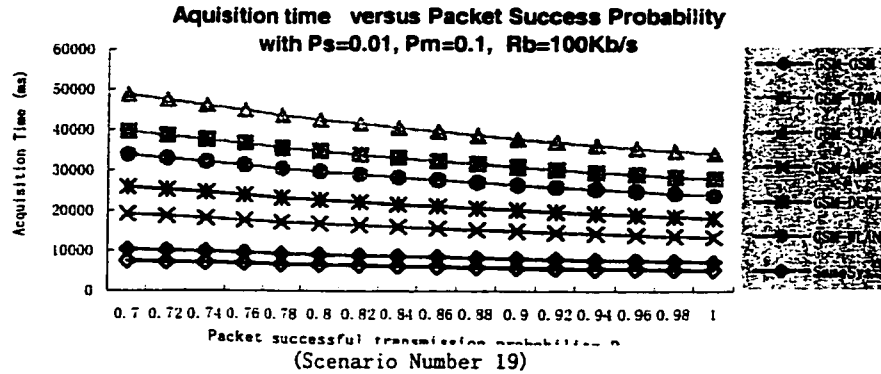


**Figure 5.2(c)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 6, with initial path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0$  respectively, universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ .

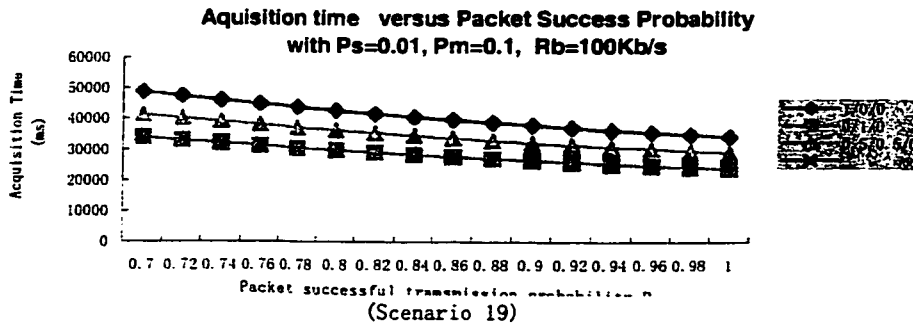
### 5.2.3 Scenario Number 19:



**Figure 5.3(a)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 19, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0$ , and MS resource blocking probability  $P_m = 0$ .

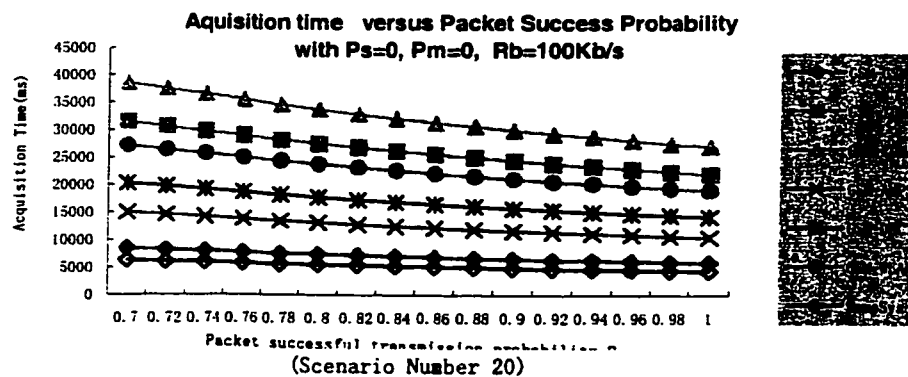


**Figure 5.3(b)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 19, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ .

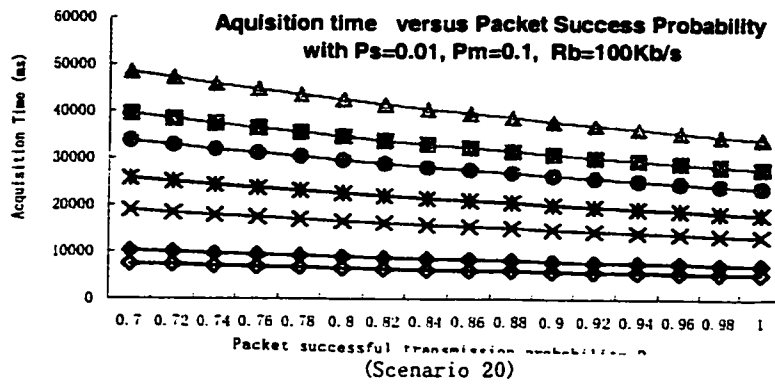


**Figure 5.3(c)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 19, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ .

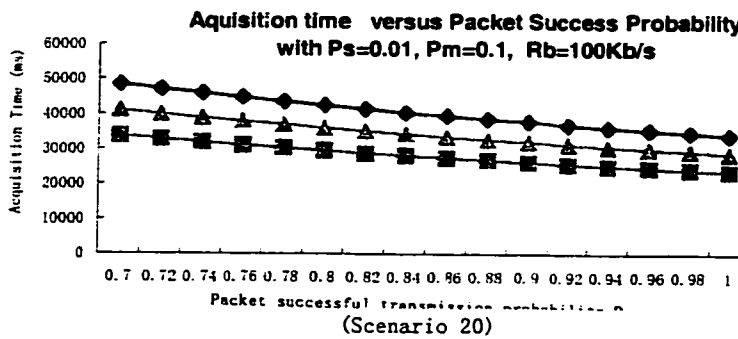
#### 5.2.4 Scenario Number 20:



**Figure 5.4(a)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 20, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0$ , and MS resource blocking probability  $P_m=0$ .

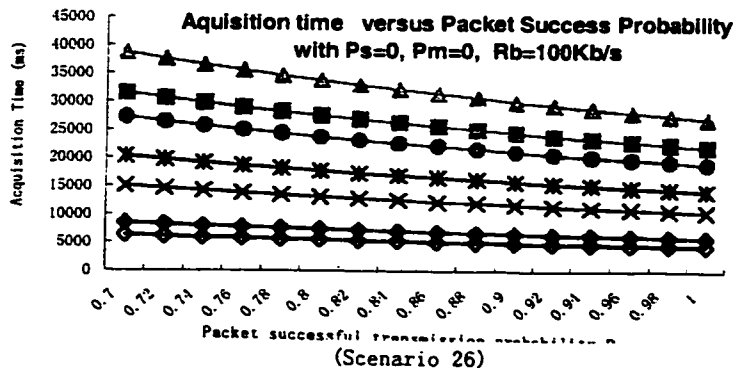


**Figure 5.4(b)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 20, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ .

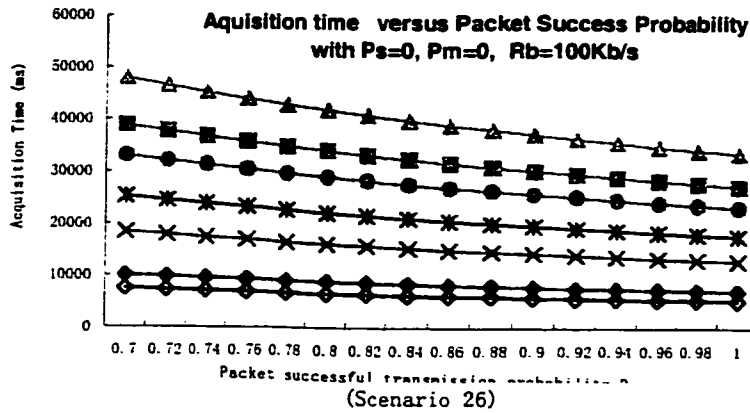


**Figure 5.4(c)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 20, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ .

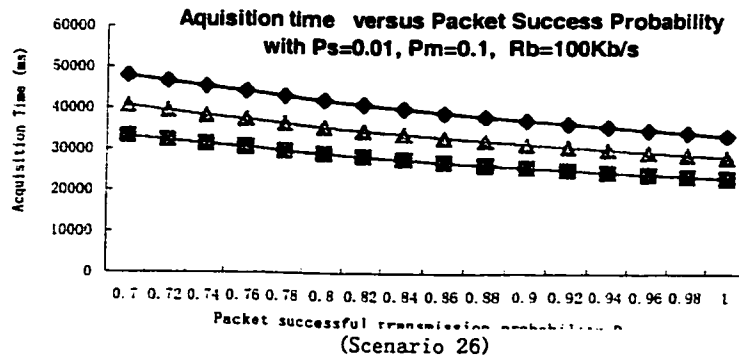
### 5.2.5 Scenario Number 26:



**Figure 5.5(a)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 26, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0$ , and MS resource blocking probability  $P_m=0$ .

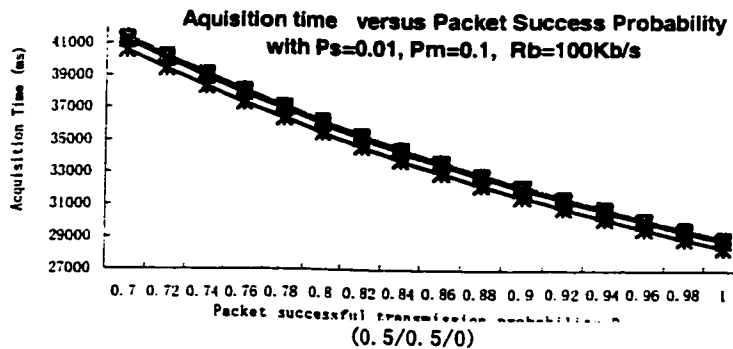


**Figure 5.5(b)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 26, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ .



**Figure 5.5(c)** Acquisition Time versus Packet successful transmission probability  $P_i$  for designed scenario number 26, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0$  respectively, universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ .

### 5.2.6 Comparison:



**Figure 5.6** Comparison of Acquisition Time versus Packet successful transmission probability  $P_i$  in different designed scenario number 1, 6, 19, 20, 26, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 0.5/0.5/0$ , universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ .

### **5.2.7 Performance Analysis:**

**By** observing Figure 5.1 (a), (b), (c), Figure 5.2 (a), (b), (c), Figure 5.3 (a), (b), (c), Figure 5.4 (a), (b), (c), Figure 5.5 (a), (b), (c), we can see that:

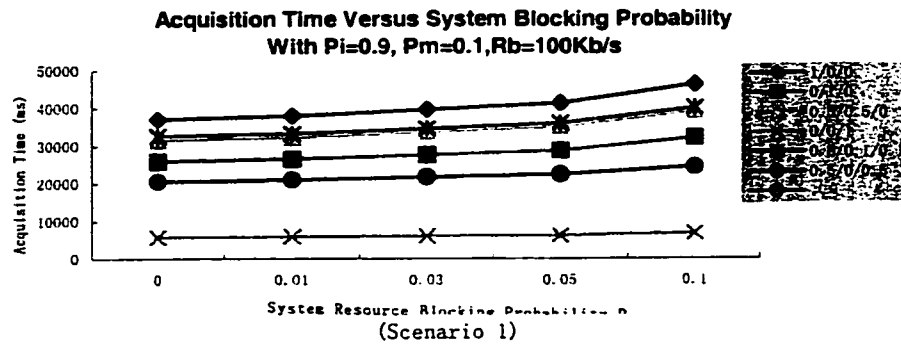
- The roaming acquisition time decreases as the packet transmission successful probability increases.
- The roaming acquisition time for connection establishment in a new system is different from the target system when the MS starts from GSM system. For the MS reaches to a target system, the larger software code size required, the longer processing time under the same conditions. It is shown that the MS needs the longest roaming acquisition time while it roams from a GSM system to a CDMA system, and the MS needs the shortest roaming acquisition time while it handoffs in the same GSM system.
- The average roaming acquisition time for connection establishment in a new system is also different from the initial path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  when the MS starts from GSM system. The higher probability spent in a large code size system download path, the longer acquisition time is required.
- The packet transmission successful probability contributes slight effect on the roaming acquisition time comparing to the target system effect.

As seen from Figure 5.6, the average roaming acquisition time has slight difference in different designed scenarios, and scenario 26 has the shortest acquisition time among them.

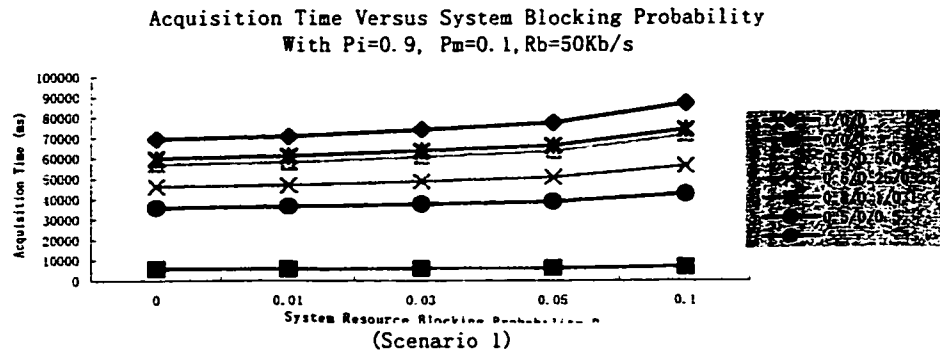
It is predictable that these results can be applied to the general scenario, since the tested scenarios are chosen randomly.

## 5.3 Roaming Acquisition Time Versus System Resource Blocking Probability

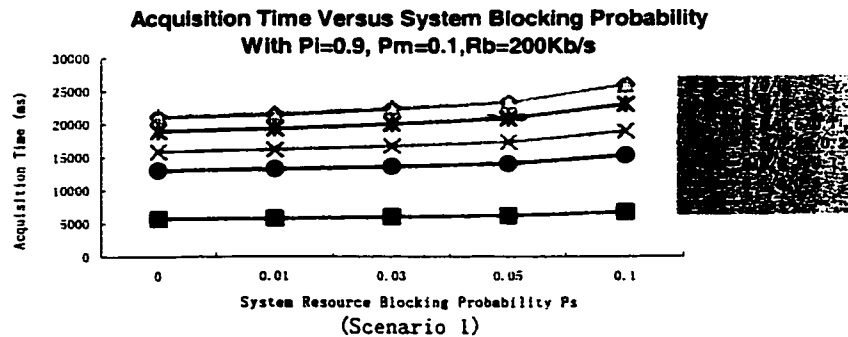
### 5.3.1 Scenario Number 1:



**Figure 5.7(a)** Acquisition Time versus System Resource Blocking Probability  $P_s$  for designed scenario number 1, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0, 0/0/1, 0.8/0.1/0.1,$  and  $0.5/0/0.5$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

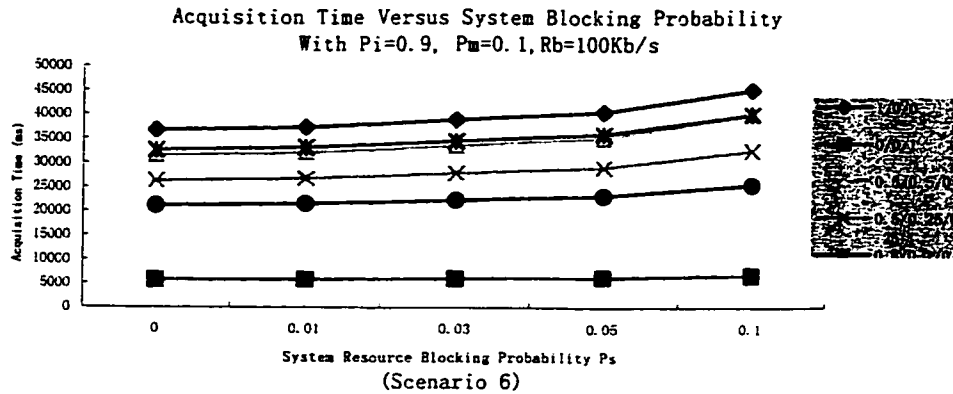


**Figure 5.7(b)** Acquisition Time versus System Resource Blocking Probability  $P_s$  for designed scenario number 1, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0, 0/0/1, 0.8/0.1/0.1,$  and  $0.5/0/0.5$  respectively, universal channel bit rate  $R_b=50\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .



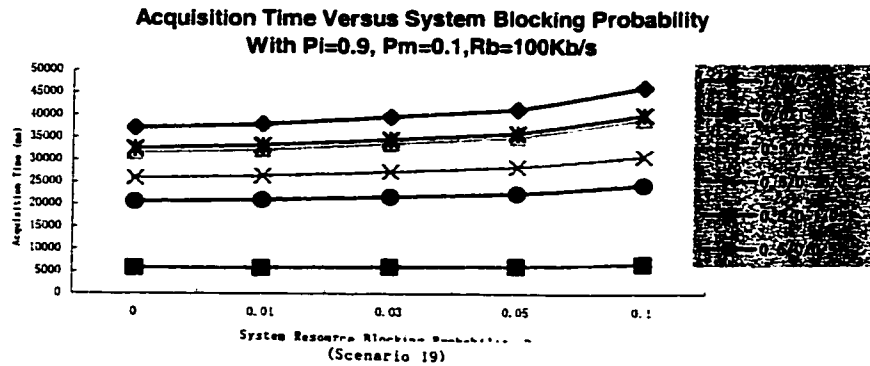
**Figure 5.7(c)** Acquisition Time versus System Resource Blocking Probability  $P_s$  for designed scenario number 1, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0, 0/0/1, 0.8/0.1/0.1,$  and  $0.5/0/0.5$  respectively, universal channel bit rate  $R_b=200\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.3.2 Scenario Number 6:



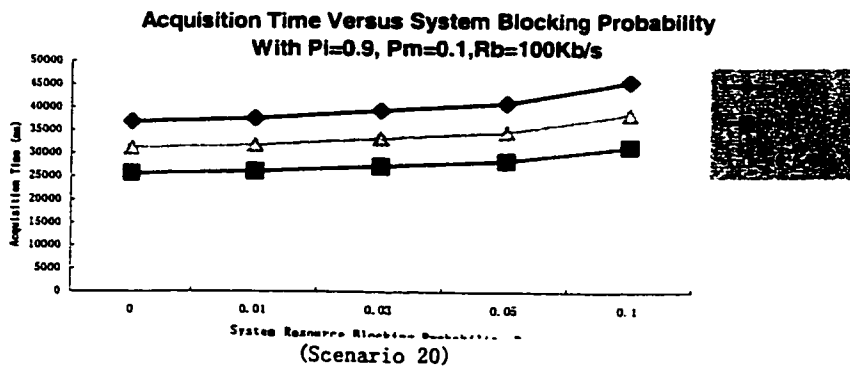
**Figure 5.8** Acquisition Time versus System Resource Blocking Probability  $P_s$  for designed scenario number 6, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/1/0$ ,  $0.5/0.5/0$ ,  $0/0/1$ ,  $0.8/0.1/0.1$ , and  $0.5/0/0.5$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.3.3 Scenario Number 19:



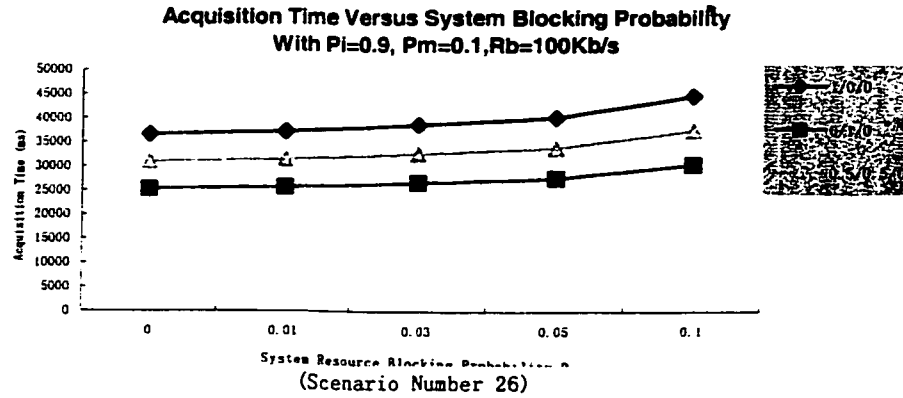
**Figure 5.9** Acquisition Time versus System Resource Blocking Probability  $P_s$  for designed scenario number 19, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/1/0$ ,  $0.5/0.5/0$ ,  $0/0/1$ ,  $0.8/0.1/0.1$ , and  $0.5/0/0.5$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.3.4 Scenario Number 20:



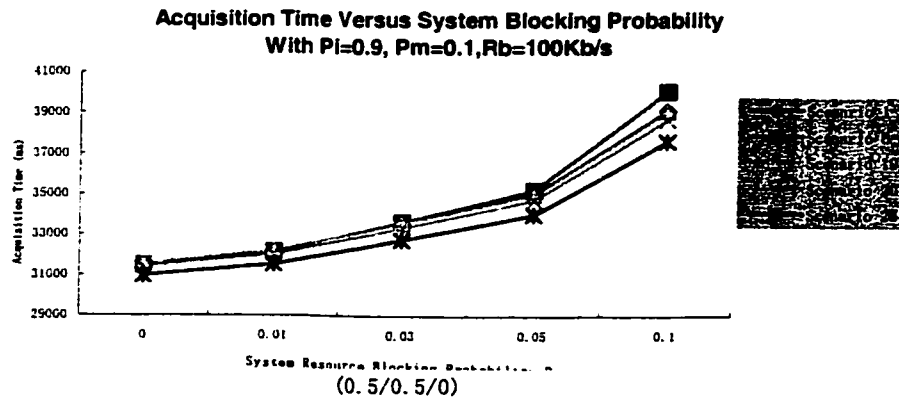
**Figure 5.10** Acquisition Time versus System Resource Blocking Probability  $P_s$  for designed scenario number 20, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

**5.3.5 Scenario Number 26:**



**Figure 5.11** Acquisition Time versus System Resource Blocking Probability  $P_s$  for designed scenario number 26, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0/1/0, 0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

**5.3.6 Comparison**



**Figure 5.12** Comparison of the Acquisition Time versus System Resource Blocking Probability  $P_s$  in different designed scenarios number 1, 6, 19, 20, 26, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 0.5/0.5/0$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .



### 5.3.7 Performance Analysis:

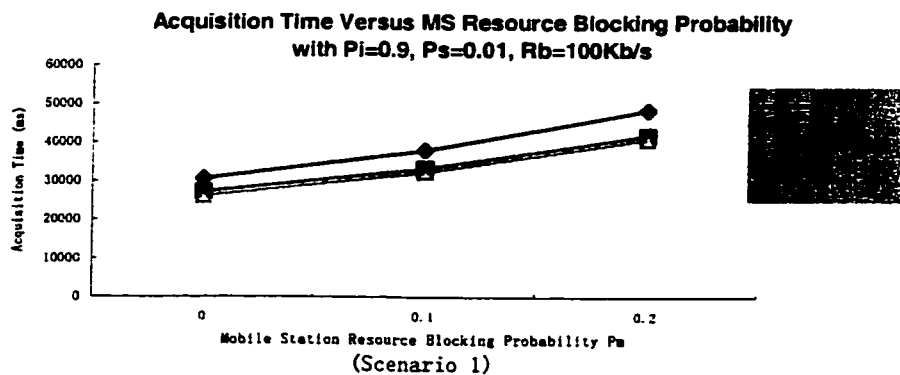
By observing Figure 5.7 (a), (b), (c), Figure 5.8, Figure 5.9, Figure 5.10, Figure 5.11, we can see that:

- The roaming acquisition time increases as the system resource blocking probability increases.
- The average roaming acquisition time for connection establishment in a new system is also different from the path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  when the MS starts from GSM system. The higher probability spent in a large code size system download path, the longer acquisition time is required.

As seen from Figure 5.12, the average roaming acquisition time has slight difference in different designed scenarios, and scenario 26 has the shortest acquisition time among them. It is predictable that these results can be applied to the general scenario.

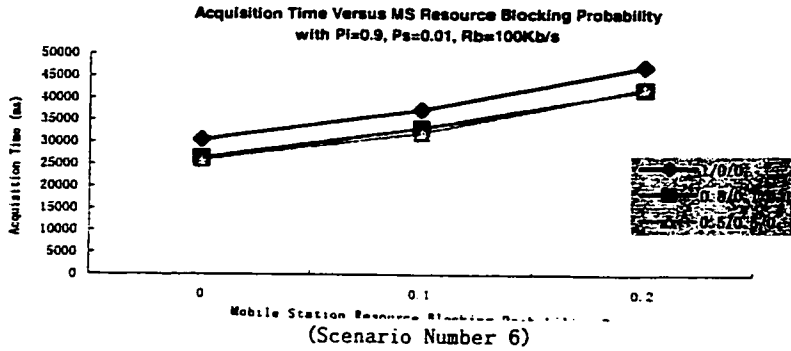
## 5.4 Roaming Acquisition Time Versus Mobile Station Resource Blocking Probability

### 5.4.1 Scenario Number 1:



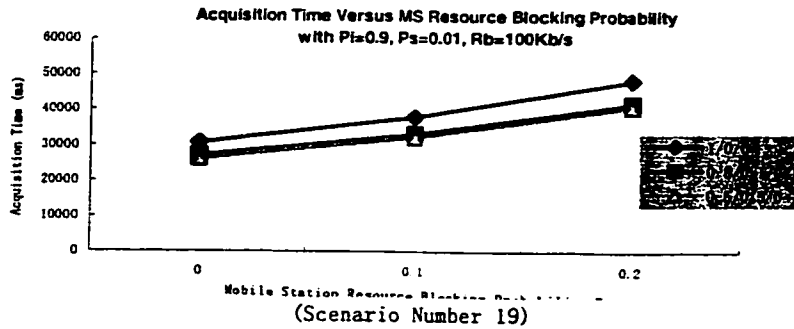
**Figure 5.13** Acquisition Time versus MS Resource Blocking Probability  $P_m$  for designed scenario number 1, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0, 0.8/0.1/0.1, 0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and system resource blocking probability  $P_s=0.01$ .

### 5.4.2 Scenario Number 6:



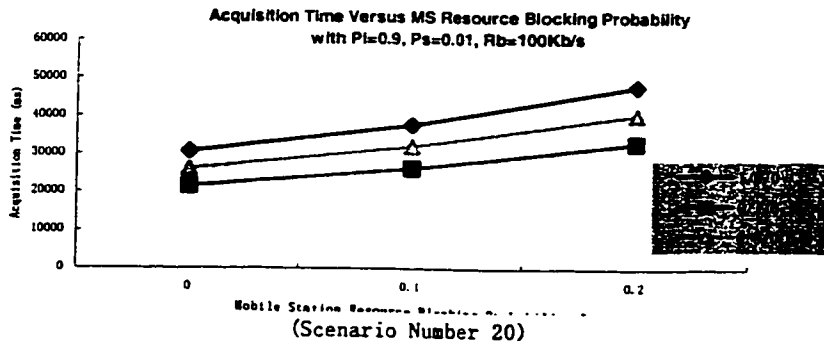
**Figure 5.14** Acquisition Time versus MS Resource Blocking Probability  $P_m$  for designed scenario number 6, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0.8/0.1/0.1$ ,  $0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and system resource blocking probability  $P_s=0.01$ .

### 5.4.3 Scenario Number 19:



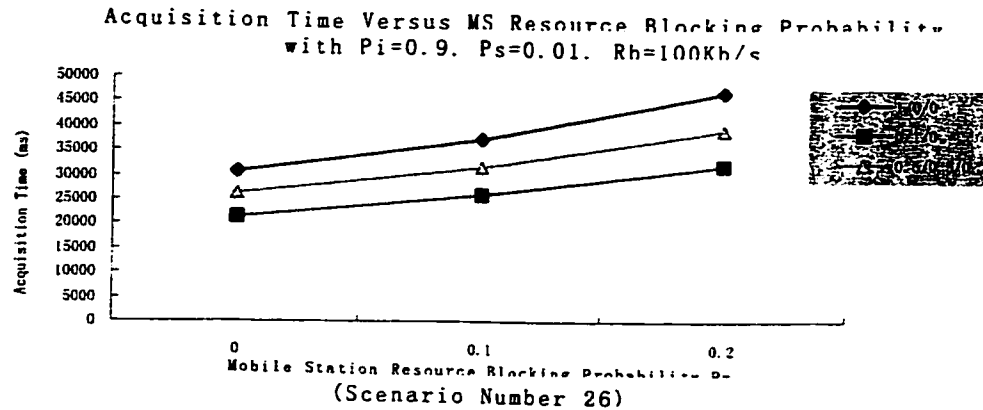
**Figure 5.15** Acquisition Time versus MS Resource Blocking Probability  $P_m$  for designed scenario number 19, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0.8/0.1/0.1$ ,  $0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and system resource blocking probability  $P_s=0.01$ .

### 5.4.4 Scenario Number 20:



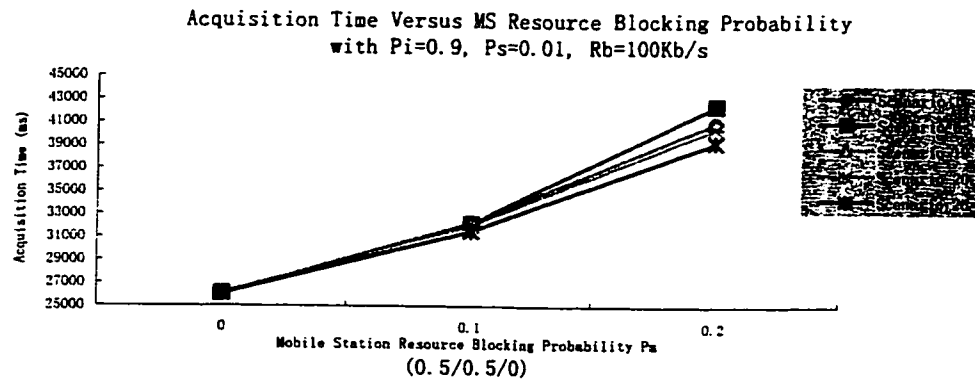
**Figure 5.16** Acquisition Time versus MS Resource Blocking Probability  $P_m$  for designed scenario number 20, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/1/0$ ,  $0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and system resource blocking probability  $P_s=0.01$ .

### 5.4.5 Scenario Number 26:



**Figure 5.17** Acquisition Time versus MS Resource Blocking Probability  $P_m$  for designed scenario number 26, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/1/0$ ,  $0.5/0.5/0$  respectively, universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and system resource blocking probability  $P_s=0.01$ .

### 5.4.6 Comparison



**Figure 5.18** Comparison of the Acquisition Time versus MS Resource Blocking Probability  $P_m$  in different designed scenarios number 1, 6, 19, 20, 26, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 0.5/0.5/0$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , packet successful transmission probability  $P_i=0.9$ , and system resource blocking probability  $P_s=0.01$ .

### 5.4.7 Performance Analysis:

By observing Figure 5.13, Figure 5.14, Figure 5.15, Figure 5.16, Figure 5.17, we can see that:

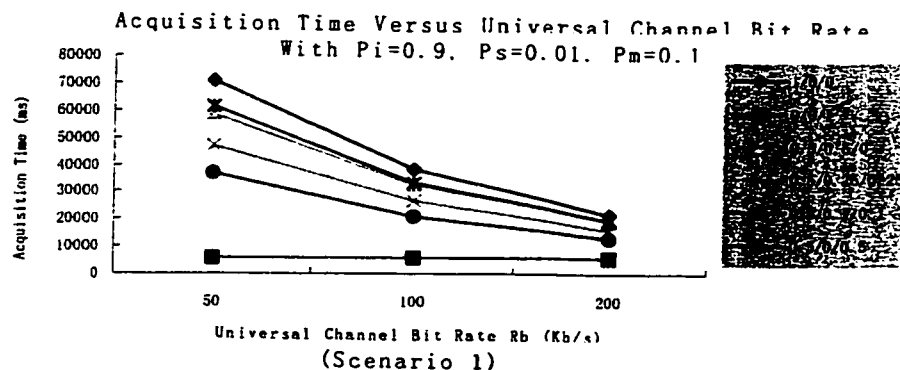
- The roaming acquisition time increases as the mobile station resource blocking probability increases.
- The average roaming acquisition time for connection establishment in a new system is also different from the path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  when the MS starts from GSM system. The higher probability spent in a large code size system download path, the longer acquisition time is required.

As seen from Figure 5.18, the average roaming acquisition time has slight difference in different designed scenarios, and scenario 26 also has the shortest acquisition time among them.

It is predictable that these results can be applied to the general scenario.

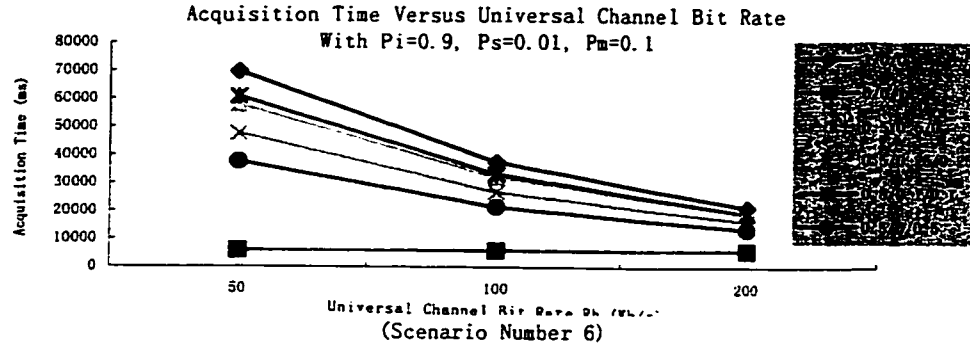
## 5.5 Roaming Acquisition Time Versus Universal Channel Bit Rate

### 5.5.1 Scenario Number 1:



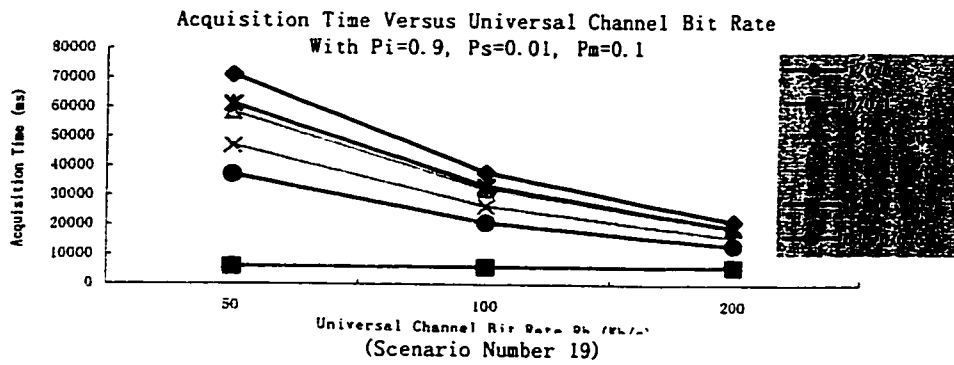
**Figure 5.19** Acquisition Time versus Universal Channel Bit Rate  $R_b$  for designed scenario number 1, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/0/1$ ,  $0.5/0.5/0$ ,  $0.5/0.25/0.25$ ,  $0.8/0.1/0.1$ , and  $0.5/0/0.5$  respectively, system resource blocking probability  $P_s=0.01$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.5.2 Scenario Number 6



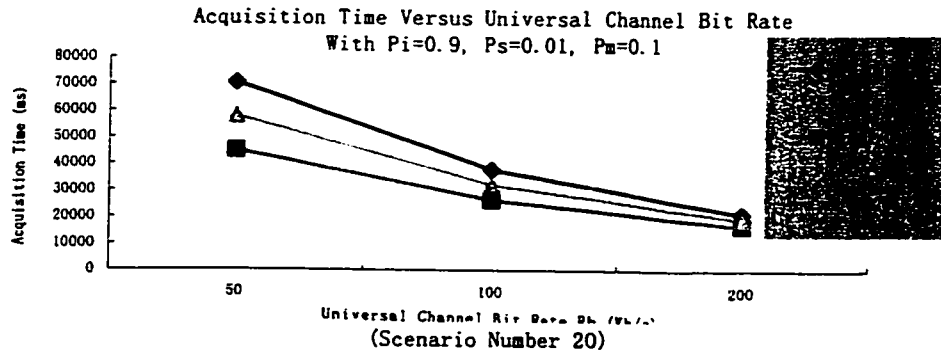
**Figure 5.20** Acquisition Time versus Universal Channel Bit Rate  $R_b$  for designed scenario number 6, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/0/1$ ,  $0.5/0.5/0$ ,  $0.5/0.25/0.25$ ,  $0.8/0.1/0.1$ , and  $0.5/0/0.5$  respectively, system resource blocking probability  $P_s=0.01$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.5.3 Scenario Number 19



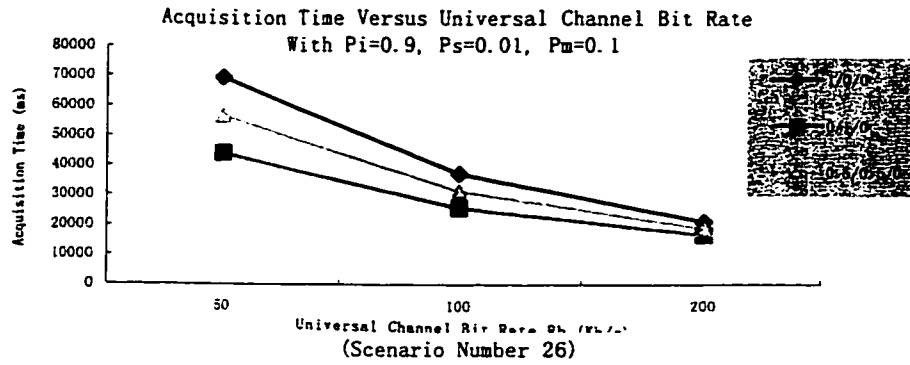
**Figure 5.21** Acquisition Time versus Universal Channel Bit Rate  $R_b$  for designed scenario number 19, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/0/1$ ,  $0.5/0.5/0$ ,  $0.5/0.25/0.25$ ,  $0.8/0.1/0.1$ , and  $0.5/0/0.5$  respectively, system resource blocking probability  $P_s=0.01$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.5.4 Scenario Number 20



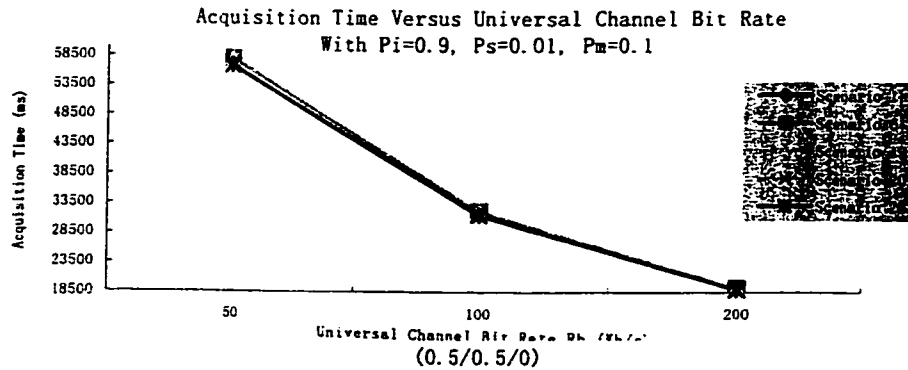
**Figure 5.22** Acquisition Time versus Universal Channel Bit Rate  $R_b$  for designed scenario number 20, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/1/0$ , and  $0.5/0.5/0$  respectively, system resource blocking probability  $P_s=0.01$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.5.5 Scenario Number 26



**Figure 5.23** Acquisition Time versus Universal Channel Bit Rate  $R_b$  for designed scenario number 26, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 1/0/0$ ,  $0/1/0$ , and  $0.5/0.5/0$  respectively, system resource blocking probability  $P_s=0.01$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.5.6 Comparison



**Figure 5.24** Comparison of the Acquisition Time versus Universal Channel Bit Rate  $R_b$  in different designed scenarios number 1, 6, 19, 20, 26, with path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03} = 0.5/0.5/0$ , system resource blocking probability  $P_s=0.01$ , packet successful transmission probability  $P_i=0.9$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.5.7 Performance Analysis:

By observing Figure 5.19, Figure 5.20, Figure 5.21, Figure 5.22, Figure 5.23, we can see that:

- The roaming acquisition time decreases as the universal channel bit rate increases if the mobile station needs to download new system software (i.e. if  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  is not equal to  $0/0/1$ ). The roaming acquisition time is not affected by the universal channel bit rate if the mobile station keeps in the same system path 3 (i.e. if  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  is equal to  $0/0/1$ ).

- When the universal channel bit rate is higher, e.g.  $R_b=200$  Kb/s, the roaming acquisition time is affected by the path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  slighter. When the universal channel bit rate is lower, e.g.  $R_b=50$  Kb/s, the roaming acquisition time is affected by the path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  more seriously.
- The average roaming acquisition time for connection establishment in a new system is also different from the path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  when the MS starts from GSM system. The higher probability spent in a large code size system download path, the longer acquisition time is required.

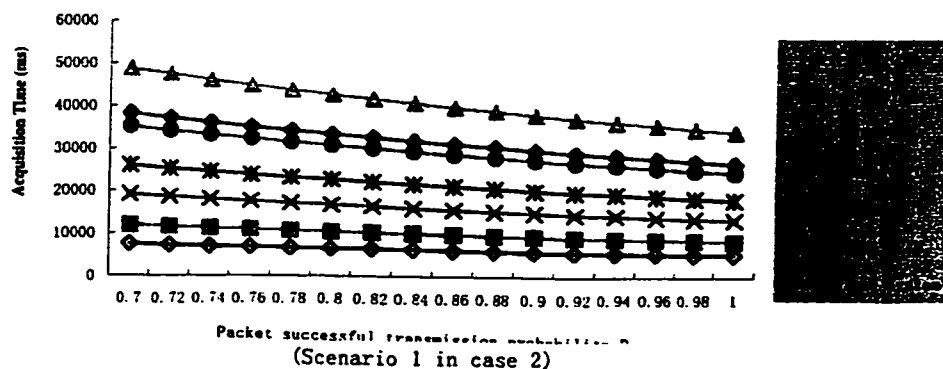
As seen from Figure 5.24, the average roaming acquisition time has slight difference in different designed scenarios, and scenario 26 also has the shortest acquisition time among them. It is predictable that these results can be applied to the general scenario.

## 5.6 Other Tests on Roaming Acquisition Time in Scenario Number 1

Roaming Acquisition Time Versus Packet Successful Transition Probability test for Scenario Number 1 by taking Case 2, 3, 4, 5, 6 for evaluation.

### 5.6.1 Case 2:

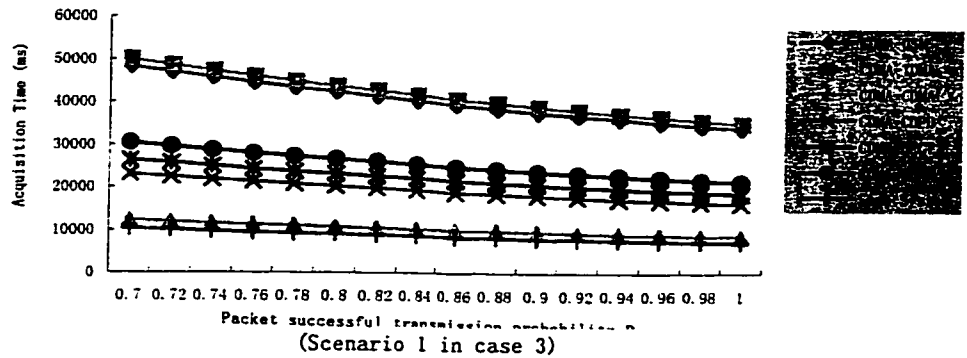
When the mobile station starts from TDMA system IS-54 or IS-136 and moves to the other wireless systems, we take Table 5.2 (b) for evaluation.



**Figure 5.25** Acquisition Time versus Packet successful transmission probability  $P_i$  for evaluating case 2, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ .

**5.6.2 Case 3:**

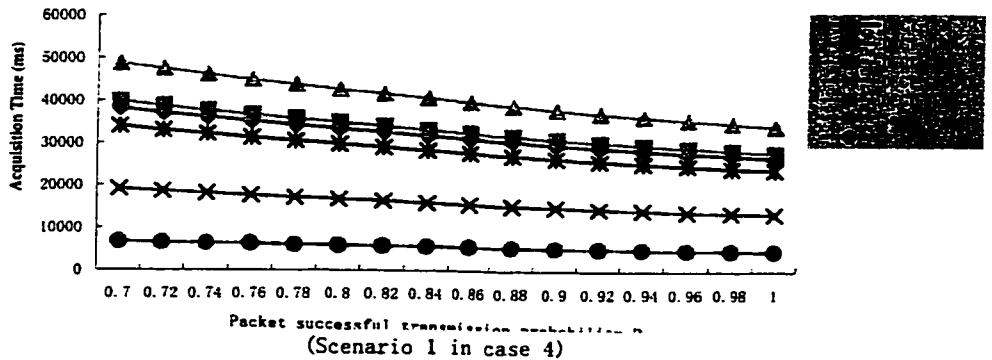
When the mobile station starts from CDMA IS-95 and moves to the other wireless systems, we take Table 5.3 (b) for evaluation.



**Figure 5.26** Acquisition Time versus Packet successful transmission probability  $P_i$  for evaluating case 3, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ .

**5.6.3 Case 4:**

When the mobile station starts from DECT and moves to the other wireless systems, we take Table 5.4 (b) for evaluation.

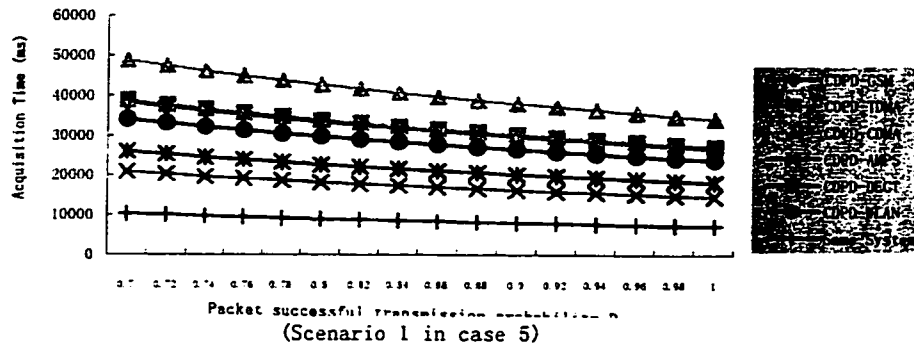


**Figure 5.27** Acquisition Time versus Packet successful transmission probability  $P_i$  for evaluating case 4, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ .



### 5.6.4 Case 5:

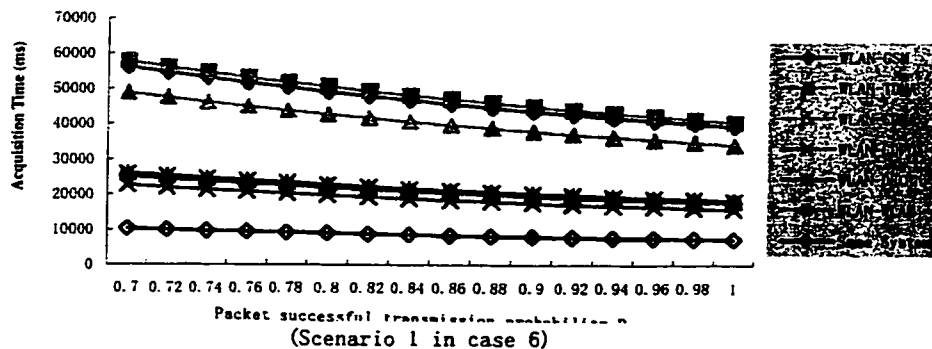
When the mobile station starts from CDPD or AMPS and moves to the other wireless systems, we take Table 5.5 (b) for evaluation.



**Figure 5.28** Acquisition Time versus Packet successful transmission probability  $P_i$  for evaluating case 5, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.6.5 Case 6:

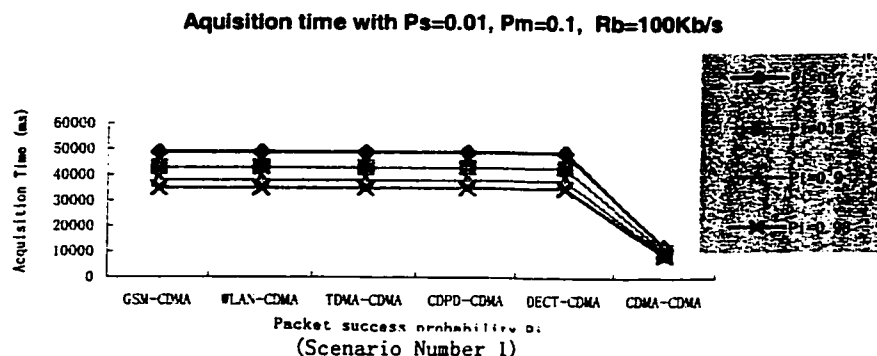
When the mobile station starts from wireless LAN and moves to the other wireless systems, we take Table 5.6 (b) for evaluation.



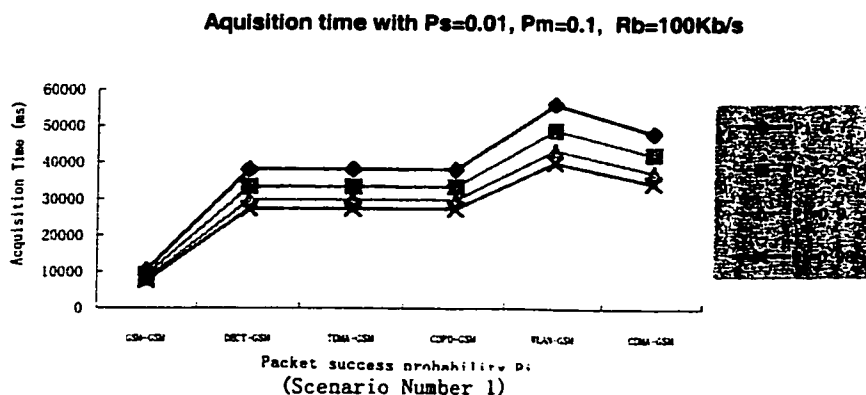
**Figure 5.29** Acquisition Time versus Packet successful transmission probability  $P_i$  for evaluating case 6, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{02}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100\text{Kb/s}$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ .

### 5.6.6 Comparison:

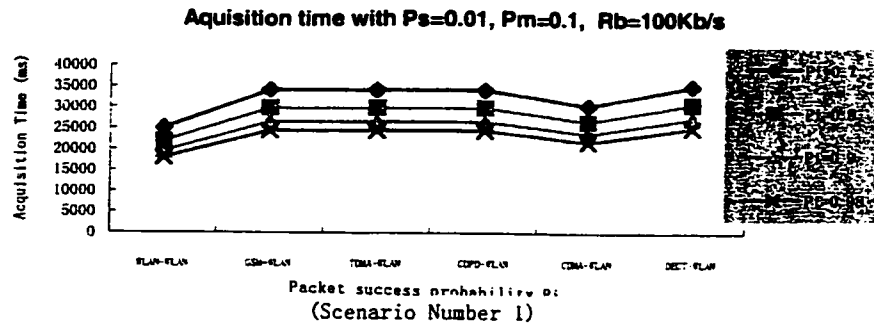
When the mobile station starts from different wireless systems and moves to the same wireless system, the acquisition time may be different. We take CDMA, GSM, wireless LAN as the target system for evaluation, testing in designed Scenario Number 1.



**Figure 5.30(a)** Roaming Acquisition Time from other systems to CDMA in scenario 1, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100Kb/s$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ , packet successful transmission probability  $P_i = 0.7, 0.8, 0.9, 0.98$  respectively.



**Figure 5.30(b)** Roaming Acquisition Time from other systems to GSM in scenario 1, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b=100Kb/s$ , system resource blocking probability  $P_s=0.01$ , and MS resource blocking probability  $P_m=0.1$ , packet successful transmission probability  $P_i = 0.7, 0.8, 0.9, 0.98$  respectively.



**Figure 5.30(c)** Roaming Acquisition Time from other systems to wireless LAN in scenario 1, with path transition probability  $\epsilon_{01}$  or  $\epsilon_{03} = 1$ , universal channel bit rate  $R_b = 100\text{Kb/s}$ , system resource blocking probability  $P_s = 0.01$ , and MS resource blocking probability  $P_m = 0.1$ , packet successful transmission probability  $P_i = 0.7, 0.8, 0.9, 0.98$  respectively.

### 5.6.7 Performance Analysis:

By observing Figure 5.25, Figure 5.26, Figure 5.27, Figure 5.28, Figure 5.29, we can see that:

- The roaming acquisition time decreases as the packet transmission successful probability increases. This is true for 6 possible cases.
- The roaming acquisition time for connection establishment in a new system may be different when the mobile station starts roaming from the same system to the different target system. For the MS reaches to a target system, the larger software code size required, the longer processing time under the same conditions.

As seen from Figure 5.30 (a), (b), (c), the roaming acquisition time for connection establishment in a new system may be different when the mobile station starts roaming from the different system to the same target system. For the MS reaches to a target system, the larger software code size required, the longer processing time under the same conditions. It is predictable that these results can be applied to the general scenarios, since the tested scenarios are chosen randomly.

## Chapter 6 Conclusion and Contribution

In this thesis, derived from the software defined radio technique, we proposed a reconfigurable multi-mode mobile station (MS) possible transition from one kind of wireless system standard to another. The reconfigurability of the MS is obtained by downloading the system software code over-the-air. Thus, a generalized state diagram of the multi-mode MS was presented for this purpose. Moreover, a detail description of the roaming operation and transition probabilities in this state diagram was presented. Furthermore, we focused on the evaluation of the roaming connection establishment acquisition time performance. The evaluation of the above roaming times include time for sensing the universal pilot channel, classic base station pilot channel, association time, and connection establishment signaling.

In acquisition time performance test, we investigated the effects of packet successful transmission probability over wireless channel  $P_i$ , system resource blocking probability  $P_s$ , mobile station resource blocking probability  $P_m$ , and signaling bit rate over the universal base station channel  $R_b$ , on the roaming connection establishment acquisition time performance for different cases and designed scenarios. By summarizing the performance analysis presented in Section 5.2.7, Section 5.3.7, Section 5.4.7, Section 5.5.7, and Section 5.6.7, and since the tested scenarios are chosen randomly, we can conclude that:

- 1) The roaming acquisition time decreases as the packet transmission successful probability increases.
- 2) The roaming acquisition time increases as the system resource blocking probability increases.
- 3) The roaming acquisition time increases as the MS resource blocking probability increases.

- 4) The roaming acquisition time decreases as the universal channel bit rate increases if the mobile station needs to download new system software (i.e. if  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  is not equal to 0/0/1). The roaming acquisition time is not affected by the universal channel bit rate if the mobile station keeps in the same system path 3 (i.e. if  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  is equal to 0/0/1).
- 5) The packet transmission successful probability contributes slight effect on the roaming acquisition time comparing to the target system effect.
- 6) When the universal channel bit rate is higher, e.g.  $R_b=200$  Kb/s, the roaming acquisition time is affected by the initial path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  slighter. When the universal channel bit rate is lower, e.g.  $R_b=50$  Kb/s, the roaming acquisition time is affected by the initial path transition probability distribution  $\epsilon_{01}/\epsilon_{02}/\epsilon_{03}$  more seriously.
- 7) The roaming acquisition time for connection establishment in a new system may be different when the mobile station starts roaming from the different system to the same target system. Vice versa, the roaming acquisition time may be different when the mobile station starts roaming from the same system to the different target system. For the MS reaches to a target system, the larger software code size required, the longer processing time under the same conditions.
- 8) The average roaming acquisition time has only slight difference among different designed scenarios.

In this thesis, we have developed a generalized state diagram of a SDR reconfigurable, multi-mode MS and presented a detailed description of its roaming and download operation. These contributions would provide a good reference to the future design of SDR mobile terminal. The

time evaluations in this thesis are important for prior design of SDR in global roaming situations and would be asset for the design of universal BS, such as for the choice of channel bandwidth.

Also, we derived a generalized test case table and acquisition time formula in order to compute the roaming connection establishment acquisition time for the MS in areas defined as having a mixture of universal cellular base station, universal wireless LAN base station, and classical base stations. It should be noted that our test case table and acquisition time formula could also be applied to some other situations' acquisition time estimation, such as roaming registration acquisition time. This can be done by changing the code size in the possible case table and by modifying the values of transition probabilities in the state diagram. For example, to compute the registration acquisition time, one could set the values of  $\epsilon_{9,12}$ ,  $\epsilon_{10,12}$ ,  $\epsilon_{11,12}$  to 1 and reduce the code size, i.e., minimum time for signaling spent in the state  $S_9$ ,  $S_{10}$ ,  $S_{11}$  in the input test table.

However, some complex situations roaming connection acquisition time evaluation, such as in the case of roaming to a different system happens during call processing period, the MS roams to a different system during SW downloading, have not been discussed in this thesis. Since these issues requires more complicated mathematic and network planning analysis, or these maybe cause call dropping, we just suggested the MS should move slowly while it is downloading new system software code and considered that the connection establishment occurs in the center but not at the edge of a wireless system.

## **Chapter 7 Suggestion for Further Research**

Software defined radio represents an idea target for R & D. In this thesis, we addressed some software download issues and time performance analysis. Several suggestions are presented here for further research:

- At present, the development of an software radio system remains very utopian because of several problems, overall technological ones, such as the amount of signal processing is too much for most processors.
- We propose that each re-configurable mobile station could have a default mode whose data is stored in a ROM by the manufacture and have two download modes whose data are saved as file1 and file2 stored in the memory such details are left for further research. Another problem arisen is how to increase the size of memory but not increase the power consumption—low power consumption component implementation issue.
- The details about how the universal base station reaches the database and details of its authentication method need to be considered for further research.
- The downloaded software code should be platform independent and could re-configure the MS to different wireless system standard, what kind of language should be adopted need to be investigated for further research, even though some literatures suggested that JAVA would be the suitable candidate.

Software radio is an emerging technology, an increasing literature addresses the SDR terminal architecture and the other related issues (wideband ADC, RF filtering, DSP, multi-band antenna). I believe that a breakthrough point to this research area would be the hardware implementation.

## **Appendix I: Bibliography**

- [1] Gunnar Heine, "GSM Networks: Protocols, Terminology, and Implementation," Artech House Publisher, Boston, 1999
- [2] Theodore S. Rappaport, "Wireless Communications Principles and Practice," Prentice Hall PTR, New Jersey, 1996
- [3] Jochen Schiller, "Mobile Communications," Addition Wesley, 2000
- [4] Cameron Kelly Coursey, "Understanding Digital PCS: The TDMA Standard," Artech House Publisher, Boston, 1999
- [5] Jerry D. Gibson, "The Communication Handbook," CRC Handbook Published in Cooperation with IEEE Press
- [6] Man Young Rhee, "CDMA Cellular Mobile Communications Network & Security," Prentice Hall PTR, New Jersey, 1998
- [7] Bernhard H. Walke, "Mobile Radio Networks: Networking and Protocols," John Wiley & Sons, 1999
- [8] Vijay K. Garg, Kenneth Smolik, Joseph E. Wilkes, "Applications of CDMA in Wireless/Personal Communication," 1996
- [9] TIA TR45.5 Subcommittee, "An overview of the Application of Code Division Multiple Access (CDMA) to Digital Cellular Systems and Personal Cellular Networks", 1992
- [10] Roger L. Peterson, Rodger E. Ziemer, David E. Borth, "Introduction to Spread Spectrum Communications," Prentice Hall
- [11] Muthuthamby Sreetharan, Rajiv Kumar, "Cellular Digital Packet Data," Artech House Publisher, Boston, 1996



- [12] Enrico Buracchini, CSELT, "The Software Radio Concept," *IEEE Communication Magazine*, pp.138-143, September 2000
- [13] C Noblet, A.H. Aghvami, "Accessing the Over-the-Air Software Download for Re-configurable Terminal," *IEE*, Savoy Place, London, UK, pp 1-6, 1998
- [14] Shigeaki Ogose, "Application of Software Radio to the Third Generation Mobile Telecommunications," Kagawa, Japan, *IEEE* pp.1212-1216, 1999
- [15] Pentti Leppanen, Jaakko Reinila, Asko Nykanen, Visa Tapio, Matti Isohookana, Juha Pyhtila, Timo Kokkonen, Jari Sillanpaa, "Software Radio—An Alternative for the Future in Wireless Personal and Multimedia Communications," University of Oulu, Telecommunication Laboratory, Finland
- [16] J. Mitola, "The Software Radio Architecture," *IEEE Communication Magazine*, vol. 33, no.5, May 1995
- [17] J. Wepman, "A/D Converters and Their Applications in Radio Receivers," *IEEE communication Magazine*, May 1995
- [18] Special Issues on Software Radio, *IEEE Personal Communication*, August 1999
- [19] Bernd Friedrichs, Reza Karimi, "Flexible Multi-Standard Terminals for 2<sup>nd</sup> and 3<sup>rd</sup> Generation Mobile Systems,"
- [20] Alberto Leon-Garcia, "Probability and Random Process for Electrical Engineering," Addition-Wesley Publishing Company
- [21] Richard C. Dorf, Roberth H. Bishop, "Modern Control System," 7<sup>th</sup> Edition, Addition-Wesley Publishing Company
- [22] <http://www.ti.com/wireless>
- [23] <http://www.etsi.org>

## **Appendix II: Acronyms**

**1G: First Generation Communication**

**2G: Second Generation Communication**

**3G: Third Generation Communication**

**Abis-interface: Interface between BTS and BSC.**

**A-interface: Interface between MSC and BSC.**

**Air-interface: Interface between MS and BTS.**

**Active set: consists of the BSs involved in the soft handoff with given MS.**

**A/D: Analogue to Digital Converter**

**AMPS: Advanced Mobile Phone System**

**ARQ: Automatic Repeat Request**

**AuC: Authentication Centre**

**B-interface: Interface between MSC and VLR.**

**BCCH: Broadcast Control Channel**

**BSC: Base Station Controller**

**BSS: Base Station Subsystem**

**BTS: Base Transceiver Station**

**Candidate Set: consists of BSs that fulfil the criteria to be included in the active set but have not yet been included in active set.**

**CC: Call Control**

**CC: Connection Confirm**

**CCCH: Common Control Channel**

**CCH: Control Channel**

**CDMA: Code Division Multiple Access**

**CDPD: Cellular Digital Packet Data**

**CellularSW\_DL: Cellular system Software Download**

**CI: Cell Identity**

**CKSN: Ciphering Key Sequence Number**

**CM: Call Management**

**Cnf: Confirmation**

**CR: Connection Request**

**CSMA: Carrier Sense Multiple Access**

**D-AMPS: Digital-AMPS**

**DCCH: Dedicated Control Channel**

**DCH: Data Channel**

**DCS: Digital Cellular System**

**DECT: Digital Enhanced Cordless Telecommunication**

**Discard Set: is the set of BSs that belongs to the current active set but are going to be dropped from the active set since they no longer fulfil the criteria for the active set.**

**DL: Download**

**DLC: Data Link Control**

**DPCCH: Dedicated Physical Control Channel**

**DSP: Digital Signal Processing**

**ETSI: European Telecommunication Standard Institute**

**FACCH: Fast Associated Dedicated Control Channel**

**FCCH: Frequency Correction Channel**

**FDD: Frequency Division Duplex**

**FDMA: Frequency Division Multiple Access**

**FPGA: Field Programmable Gate Array**

**GPRS: General Packet Radio Service**

**GSM: Global System for Mobile Communications**

**HLR: Home Location Register**

**HO: Handover/Handoff**

**HW: Hardware**

**ID: Identifier**

**IEEE: Institute of Electrical and Electronics Engineers**

**IMEI: International Mobile Equipment Identity**

**IMSI: International Mobile Subscriber Identity**

**IN: Intelligent Network**

**ISDN: Integrated Service Digital Network**

**ISO: International Organization for Standardization**

**ISUP: ISDN User Part**

**ITU: International Telecommunication Union**

**LA: Location Area**

**LAC: Location Area Code**

**LAI: Location Area Identification**

**LAN: Local Area Network**

**LAPC: Link Access Procedure for the C-plane**

**LAPD: Link Access Procedure for the D-channel**

**LAPDm: LAPD for Mobile**

**LC: Link Controller**

**LLC: Logic Link Control**

**LOS: Light-Of-Sight**

**MAC: Medium Access Control**

**MM: Mobility Management**

**MNC: Mobile Network Code**

**MOC: Mobile Originated Call**

**M-QoS: Mobile QoS**

**MS: Mobile Station**

**MSC: Mobile Switching Centre**

**MSIN: Mobile Subscriber Identification Number**

**MTC: Mobile Terminated Call**

**MTSO: Mobile Telephone Switching Office**

**NA-TDMA: North American-TDMA**

**Neighbor Set: contains the BSs that are likely candidates for soft handoff.**

**NMT: Nordic Mobile Telephone**

**NSS: Network and Switching Subsystem**

**OSI: Open System Interconnection**

**PC: Personal Computer**

**PCH: Paging Channel**

**PCHHT: Pilot/Paging Channel History Table**

**PCS: Personal Communication Service**

**PCS: Personal Cellular System**

**PHY: Physical Layer**

**PIN: Personal Identity Number**

**PLMN: Public Mobile Land Network**

**PS: Power Saving**

**PSTN: Public Switched Telephone Network**

**PTM: Point-to-Multipoint**

**PTP: Point-to-Point**

**QoS: Quality of Service**

**RACH: Random Access Channel**

**RAND: Random Number**

**Remaining Set: contains all BSs excluded from the other sets.**

**Req: Request**

**Res: Response**

**RLC: Radio Link Control**

**RLP: Radio Link Protocol**

**RM: Resource Management**

**RNS: Radio Network Subsystem**

**ROM: Read Only Memory**

**RR: Radio Resource**

**RRC: Radio Resource Control**

**RRM: Radio Resource Management**

**RSS: Radio Subsystem**

**RTS: Request To Send**

**SABM: Set Asynchronous Balance Mode**

**SACCH: Slow Associated Dedicated Control Channel**

**SC: Synchronization Channel**

**SCCP: Signalling Connection Control Part**

**SCF: Service Control Function**

**SCH: Synchronization Channel**

**SDCCH: Stand-alone Dedicated Control Channel**

**SDMA: Space Division Multiple Access**

**SDR: Software Defined Radio/ Software Radio**

**SIM: Subscriber Identity Module**

**SMS: Short Message Service**

**SN: Subscriber Number**

**SNDCP: Sub-Network Dependent Convergence Protocol**

**SS7: Signaling System No. 7**

**SW: Software**

**SWDB: Software Database**

**SYSDB: System Database**

**TCH: Traffic Channel**

**TCH/F: TCH Full Rate**

**TCH/FS: TCH/F Speech**

**TCH/H: TCH Half Rate**

**TCH/HS: TCH/H Speech**

**TD-CDMA: Time Division-CDMA**

**TDD: Time Division Duplex**

**TDMA: Time Division Multiple Access**

**TMN: Traffic Management Network**

**TMSI: Temporary Mobile Subscriber Identity**

**TOS: Type Of Service**

**TRX: Transmission/Reception Unit**

**TS: Time Slot**

**UA: Unnumbered Acknowledgment**

**VLR: Visitor Location Register**

**W-CDMA: Wideband-CDMA**

**W-CTRL: Wireless Control**

**WLAN: Wireless LAN**

**WLL: Wireless Local Loop**

**WMT: Wireless Mobile Terminal**