

SENSITIVITY STUDIES OF  
GENERALIZED GYRATOR CIRCUITS

BY

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## ABSTRACT

In this dissertation, the sensitivity of the Generalized Gyrator realized using three different structures has been examined. Also the sensitivity of an arbitrary voltage transfer function realized using the Yanagisawa structure, using the Generalized Gyrator as the active element, with the three different realizations of the Generalized Gyrator has been investigated.

A method of realizing an arbitrary biquadratic voltage transfer function has been described for two specific examples.

CHAPTER I  
THE GENERALIZED GYRATOR AND ITS REALIZATIONS

1.1 Introduction

The gyrator is an element used in active network synthesis for the realization of driving point and transfer functions. One of the main characteristics of a gyrator is the impedance inversion property. The great advantage of this characteristic is that an inductance can be simulated at the input port of a gyrator, when the output port is terminated by a capacitor. This property is used in the realization of several active RC-networks.

In the recent past many types of gyrators have been introduced. The one which includes all these different types of special cases is called the "Generalized Gyrator" (GG).

1.2 Generalized Gyrator (GG)

A generalized gyrator (GG) has been defined (1) by its chain matrix [a] as:

$$[a] = \begin{bmatrix} 0 & \frac{1}{g_2(s)} \\ g_1(s) & 0 \end{bmatrix} \quad (1.1)$$



Where  $g_1(s)$  and  $g_2(s)$  are positive or negative realizable admittance functions. The symbolic representation of the GG is shown in Fig. 1.1. The GG will be termed lossless, if the parameters A and D of [a] are zero or positive. If A and D are not zero, the GG is a lossy one. In this dissertation, we shall be concerned with only lossless GG's.

The GG will be called an "Ideal Generalized Gyrator" (IGG), if  $|a| = \pm 1$ , that is,  $g_1(s) = \pm g_2(s)$ . The IGG is reciprocal if  $|a| = +1$ , while it is non-reciprocal if  $|a| = -1$ .

### 1.3 Positive and Negative Gyrators

If  $g_1(s)$  and  $g_2(s)$  have the same signs, the GG will be termed a "positive gyrator" (PG), where as if they are of opposite signs-it will be termed a "negative gyrator" (NG).

Depending on the signs of  $g_1(s)$  and  $g_2(s)$ , there will be two types for each PG and NG. The [a] of the PG is given by:

$$[a] = \begin{bmatrix} 0 & \pm \frac{1}{g_2(s)} \\ \pm g_1(s) & 0 \end{bmatrix}$$

where the positive signs correspond to PG type I while the negative signs refer to PG type II.

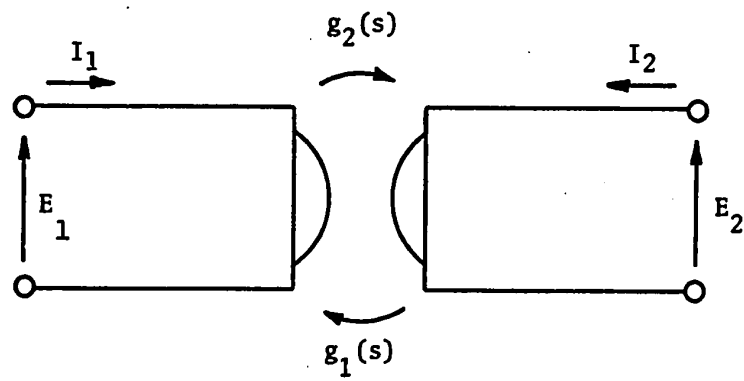


Fig. 1.1: Symbolic Representation of the GG

Similarly the  $[a]$  of the NG is given by:

$$[a] = \begin{bmatrix} 0 & + \frac{1}{g_2(s)} \\ \pm g_1(s) & 0 \end{bmatrix}$$

NG type I will have the  $[a] = \begin{bmatrix} 0 & - \frac{1}{g_2(s)} \\ g_1(s) & 0 \end{bmatrix}$

while NG type II will have the  $[a] = \begin{bmatrix} 0 & + \frac{1}{g_2(s)} \\ - g_1(s) & 0 \end{bmatrix}$

In what follows, the two types of gyrators, namely passive and active gyrators, will be defined.

1. If  $g_1(s) = g_2(s) = G$  in the IPG, we get Tellegen gyrator, which is a passive anti-reciprocal element.
2. If  $g_1(s)$  and  $g_2(s)$  are conductances and have opposite signs in (1.1), we get Kawakami's negative gyrator, which is reciprocal.

#### 1.4 Gyrator Realization

The generalized gyrator has been realized, using active devices, by two methods, namely:

- (i) Realization of GG using CNICs and VNICs.
- (ii) (a)- Realization of GG using VNIC and an IPG or an ING.
- (b)- Realization of GG using INIC and an IPG or an ING.

In what follows, for the sake of completeness, the realization of GG using these methods will be reproduced.

##### 1.41 Realization of GG using CNICs and VNICs and Passive Elements (2)

Fig. 1.2 consists of the four passive-two ports  $N_1$ ,  $N_2$ ,  $P_a$  and  $P_b$  and CNICs with unity conversion ratio.

Analysis yields:

$$[Y] = [Y]_{N_1} + [Y]_{N_2} + [Y]_{P_a} + [Y]_{P_b} \quad (1.2)$$

This is equated to the admittance matrix of the GG:

$$[Y] = \begin{bmatrix} 0 & g_1(s) \\ g_2(s) & 0 \end{bmatrix} = \begin{bmatrix} 0 & g_{1p}(s) - g_{1n}(s) \\ g_{2p}(s) - g_{2n}(s) & 0 \end{bmatrix} \quad (1.3)$$

Where  $g_{1p}(s)$ ,  $g_{1n}(s)$ ,  $g_{2p}(s)$  and  $g_{2n}(s)$  are driving point functions of the two element type networks and are obtained by partial fraction expansion of  $g_1(s)$  and  $g_2(s)$ .

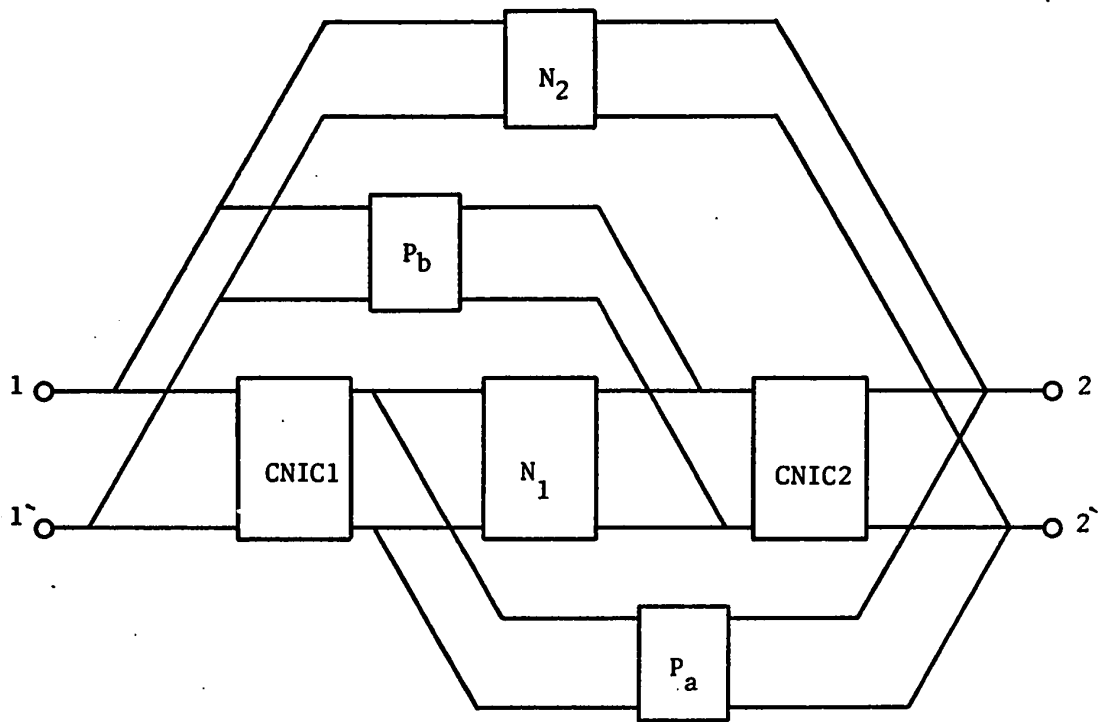


Fig.1.2: Basic Construction for the Realization  
of GG using CNICs and Passive Elements

Several allocations between the individual matrices in (1.2) are possible. One simple choice is to have the networks  $N_1$  and  $N_2$  as  $\pi$  - structures, and  $P_a$  and  $P_b$  as series arms. The structure corresponding to this choice is shown in Fig. 1.3.

The different admittances are:

$$\begin{aligned}
 Y_1 &= \frac{g_{1n}(s) + g_{2n}(s)}{2} & Y_5 &= g_{1p}(s) \\
 Y_2 &= \frac{g_{1p}(s) + g_{2p}(s)}{2} & Y_6 &= g_{1n}(s) \\
 Y_3 &= \frac{g_{1p}(s) + g_{2n}(s)}{2} & Y_7 &= g_{2n}(s) \\
 Y_4 &= \frac{g_{1n}(s) + g_{2p}(s)}{2} & Y_8 &= g_{2p}(s)
 \end{aligned}
 \tag{1.4}$$

Instead of the CNICs, VNICs can be used, in which case, only the ports need to be interchanged. The ideal gyrators result from a simplification of the above structure, where some of the admittances will be absent. For IPG, type I or II  $Y_1$  and  $Y_2$  will be equal to zero, while for ING, type I or II,  $Y_3$  and  $Y_4$  will be absent.

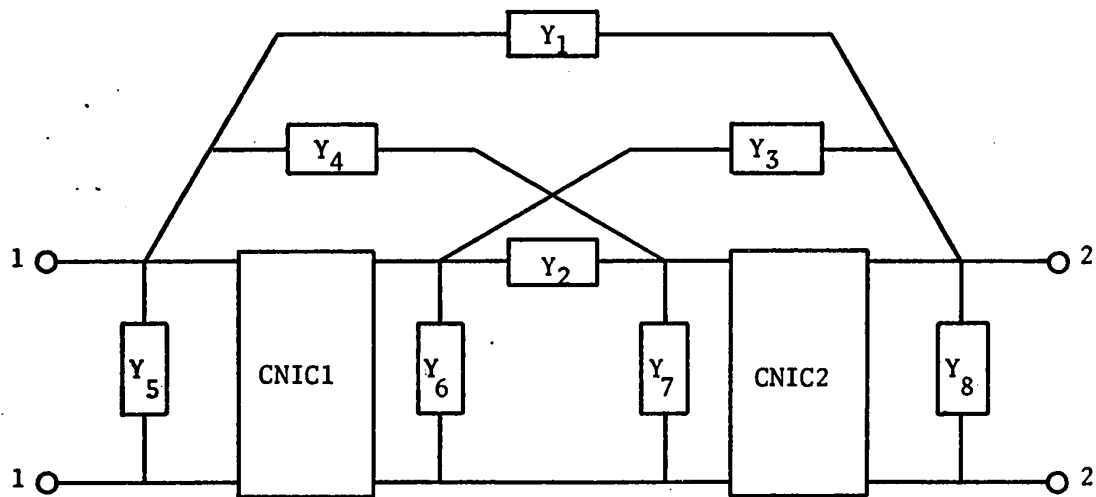


Fig. 1.3: The Structure used in the Realization  
of GG.

### 1.42 Realization of GG using VNIC or INIC and an IPG or an ING(1)

#### (a) Using VNIC:

Fig. 1.4(a) shows the arrangement, for realizing a GG, using generalized VNIC in cascade with IPG or ING. Fig. 1.4(b) shows the idealized version of a generalized VNIC.

From Fig. 1.4(a), the [a] is:

$$\begin{bmatrix} -\frac{g_1(s)}{g_2(s)} & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & B \\ C & 0 \end{bmatrix} = \begin{bmatrix} 0 & -B \frac{g_1(s)}{g_2(s)} \\ C & 0 \end{bmatrix}$$

By choosing  $B = \pm \frac{1}{g_1(s)}$  and  $C = \pm \frac{1}{B}$  the GG results.

The GG may also be realized by following the IPG or ING by the generalized VNIC, in which case the choice of the different parameters are  $B = \pm \frac{1}{g_2(s)}$  and  $C = \pm \frac{1}{B}$ .

#### (b) Using a INIC:

As before, Fig. 1.5(a) and Fig. 1.5(b) show the arrangement, for realizing a GG, using generalized INIC in cascade with IPG or ING and the idealized version of a generalized INIC respectively.



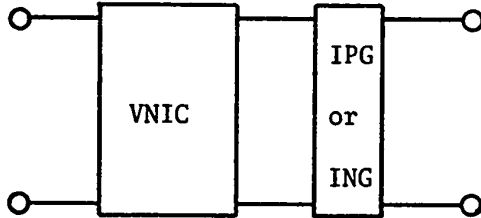


Fig. 1.4(a)

Realization of a GG  
by a Generalized VNIC  
in cascade with an  
IPG or ING

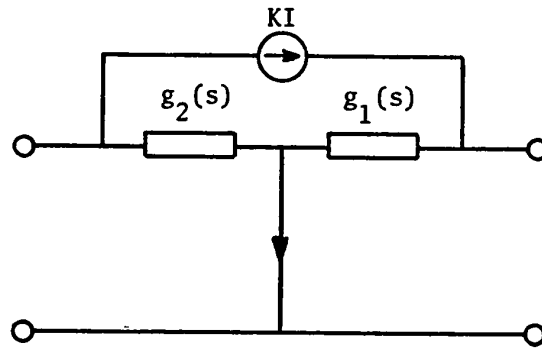


Fig. 1.4(b)

Idealized Version of a  
Generalized VNIC

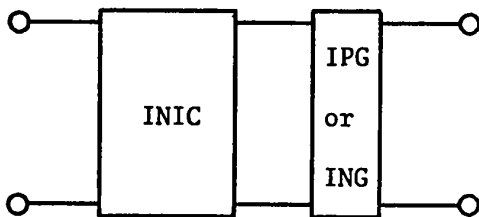


Fig. 1.5(a)

Realization of a GG  
by a Generalized INIC  
in cascade with an  
IPG or ING

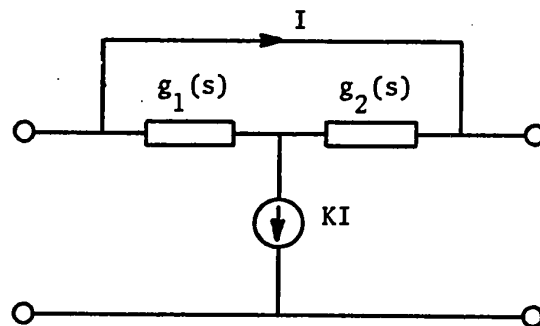


Fig. 1.5(b)

Idealized Version of a  
Generalized INIC

From Fig. 1.5(a), choosing  $B = \pm \frac{1}{g_2(s)}$  and  $C = \pm \frac{1}{B}$

for IPG or ING, the GG results.

It may also be obtained by following the IPG or ING by the generalized INIC, in which case the different parameters ought to be  $B = \pm \frac{1}{g_1(s)}$  and  $C = \pm \frac{1}{B}$ .

The IPG or ING can be realized by many different methods (3), but they are not discussed here, as this dissertation concerns itself only with GG's sensitivities and not their realizations.

### 1.5 Scope of the Dissertation

This dissertation deals with the investigation of the following:-

1. The sensitivities of the two different realizations of the GG.
2. The different sensitivities of a biquadratic voltage transfer function realized using the GG.

CHAPTER II  
SENSITIVITY OF THE GENERALIZED GYRATOR

2.1 Introduction

In passive and active network design, a great deal of attention must be paid to the sensitivity of the network function caused due to the variation of network parameters. The characteristics of any element is subject to change for many reasons, like temperature, aging, manufacturing tolerances .. etc. Such variations cause the poles and zeros to be displaced from their nominal positions and consequently the network gives a different performance from the one for which it is designed.

Although, as mentioned earlier, the GG has been realized using two methods, the sensitivity of the GG has not been discussed before. In this chapter, the sensitivity analysis of the GG with respect to each element used in the realization of the GG will be carried out in detail.

2.2 Sensitivity

The sensitivity of a network function can be considered as a measure of the change in the performance of the network due to a change in the nominal value of one or more of the network elements.

We shall here adopt the following definition of sensitivity:-

The sensitivity function  $S_x^{N(s)}$  of the network function  $N(s,x)$  due to the variation of the parameter  $x$  is defined as:

$$S_x^{N(s)} = \frac{dN(s,x)/N(s,x)}{dx/x}$$

The above definition of the sensitivity will be used throughout this dissertation.

### 2.3 Realization of GG using CNICs with "k" Conversion Ratio

In Chapter I, realization of GG using CNICs or VNICs with unity conversion ratio has been discussed. Here it is assumed that the CNICs or the VNICs used will have a conversion ratio  $k$ .

In Fig. 1.3, let the  $[a]$  of CNIC<sub>1</sub> and CNIC<sub>2</sub> be

$$[a] = \begin{bmatrix} 1 & 0 \\ 0 & -\frac{1}{k_1} \end{bmatrix} \text{ and } [a] = \begin{bmatrix} 1 & 0 \\ 0 & -\frac{1}{k_2} \end{bmatrix}$$

respectively.

Analysis yields:

$$[Y] = [Y]_{N_1} + [Y]_{N_2} + [Y]_{P_a} + [Y]_{P_b} \quad (2.1)$$

$$= \begin{bmatrix} \frac{Y_2 + Y_6}{k_1} & \frac{Y_2}{k_1} \\ k_2 Y_2 & -k_2 (Y_2 + Y_7) \end{bmatrix}_{N_1} + \begin{bmatrix} Y_1 + Y_5 & -Y_1 \\ -Y_1 & Y_1 + Y_8 \end{bmatrix}_{N_2} + \begin{bmatrix} \frac{-Y_3}{k_1} & \frac{Y_3}{k_1} \\ -Y_3 & Y_3 \end{bmatrix}_{P_a} + \begin{bmatrix} Y_4 & -Y_4 \\ k_2 Y_4 & -k_2 Y_4 \end{bmatrix}_{P_b}$$

$$[Y] = \begin{bmatrix} Y_1 + Y_4 + Y_5 - \frac{Y_2 + Y_3 + Y_6}{k_1} & \frac{Y_2 + Y_3}{k_1} - (Y_1 + Y_4) \\ k_2 (Y_2 + Y_4) - (Y_1 + Y_3) & Y_1 + Y_3 + Y_8 - k_2 (Y_2 + Y_4 + Y_7) \end{bmatrix} \quad (2.2)$$

This is equated to the admittance matrix of the generalized gyrator

$$[Y] = \begin{bmatrix} 0 & g_1(s) \\ g_2(s) & 0 \end{bmatrix} = \begin{bmatrix} 0 & g_{1p}(s) - g_{1n}(s) \\ g_{2p}(s) - g_{2n}(s) & 0 \end{bmatrix} \quad (2.3)$$

Where  $g_{1p}(s)$ ,  $g_{1n}(s)$ ,  $g_{2p}(s)$  and  $g_{2n}(s)$  are driving point functions of the two element kind networks and are obtained by partial fraction expansion of  $g_1(s)$  and  $g_2(s)$ . Hence we get

$$\begin{aligned}
 Y_1 + Y_4 + Y_5 - \frac{Y_2 + Y_3 + Y_6}{k_1} &= 0 \\
 Y_1 + Y_3 + Y_8 - k_2(Y_2 + Y_4 + Y_7) &= 0 \\
 \frac{Y_2 + Y_3}{k_1} - (Y_1 + Y_4) &= g_{1p}(s) - g_{1n}(s) \\
 k_2(Y_2 + Y_4) - (Y_1 + Y_3) &= g_{2p}(s) - g_{2n}(s)
 \end{aligned} \tag{2.4}$$

#### 2.4 Sensitivity of [Y] parameters of a GG

Next, let us consider the sensitivity of the [Y] parameters  $Y_{11}$ ,  $Y_{12}$ ,  $Y_{21}$  and  $Y_{22}$  of equation (2.2) with respect to the variation in the elements  $Y_1$  to  $Y_8$ ,  $k_1$  and  $k_2$ .

##### 2.4.1 Sensitivity of $Y_{11}$ with respect to $Y_1$

From equation (2.2)

$$Y_{11} = Y_1 + Y_4 + Y_5 - \frac{Y_2 + Y_3 + Y_6}{k_1} \tag{2.5}$$

Let  $Y_1$  become  $Y_1 (1 + \epsilon_1)$  and as a consequence  $Y_{11}$  will be  $Y_{11} + \alpha_1$ , where  $\epsilon_1$  is a small variation in  $Y_1$  and  $\alpha_1$  is the corresponding change in  $Y_{11}$  substituting (2.6) in (2.5)

we get:

$$Y_{11} + \alpha_1 = Y_1 + Y_4 + Y_5 - \frac{Y_2 + Y_3 + Y_6}{k_1} + Y_1 \epsilon_1 \quad (2.7)$$

from (2.7) and (2.5)  $\alpha_1 = Y_1 \epsilon_1$  and so

$$S_{\epsilon_1}^{\alpha_1} = \frac{d\alpha_1/\alpha_1}{d\epsilon_1/\epsilon_1} = 1$$

In a similar manner, the sensitivity of  $Y_{11}$  with respect to  $Y_2$  to  $Y_8$ ,  $k_1$  and  $k_2$  could be obtained. Also, following the same procedure, the sensitivity of the parameters  $Y_{12}$ ,  $Y_{21}$  and  $Y_{22}$  could be calculated. Table 2.1 shows the sensitivity of the [Y] parameters with respect to each element in Fig. 1.3. It is obvious from Table 2.1 that the sensitivities of the [Y] parameters of the GG realized using CNICs with conversion ratio equal to  $k$  could be one of three cases:

- (i) Identically to zero.
- (ii) Equal unity.
- (iii) Inversely proportional to the change in the element nominal value.

TABLE 2.1

Sensitivity of [Y] parameters with respect to  
Small Variation in  $Y_1$  to  $Y_8$ ,  $k_1$  &  $k_2$

<u>Element</u>	<u>Variation</u>	$\frac{S^\alpha}{S^\alpha}$	$\frac{S^\beta}{S^\beta}$	$\frac{S^\gamma}{S^\gamma}$	$\frac{S^\delta}{S^\delta}$
$Y_1$	$\epsilon_1$	1	1	1	1
$Y_2$	$\epsilon_2$	1	1	1	1
$Y_3$	$\epsilon_3$	1	1	1	1
$Y_4$	$\epsilon_4$	1	1	1	1
$Y_5$	$\epsilon_5$	1	-	-	-
$Y_6$	$\epsilon_6$	1	-	-	-
$Y_7$	$\epsilon_7$	-	-	-	1
$Y_8$	$\epsilon_8$	-	-	-	1
$k_1$	$\epsilon_{k_1}$	$\frac{1}{1 + \epsilon_{k_1}}$	$\frac{1}{1 + \epsilon_{k_1}}$	-	-
$k_2$	$\epsilon_{k_2}$	-	-	1	1

$S^\alpha$  = Sensitivity of variation ( $\alpha$ ) in  $Y_{11}$  w.r.t. element variation.  
 $S^\beta$  = Sensitivity of variation ( $\beta$ ) in  $Y_{12}$  w.r.t. element variation.  
 $S^\gamma$  = Sensitivity of variation ( $\gamma$ ) in  $Y_{21}$  w.r.t. element variation.  
 $S^\delta$  = Sensitivity of variation ( $\delta$ ) in  $Y_{22}$  w.r.t. element variation.



## 2.5 Sensitivity of GG realized using VNIC and IPG in Cascade

As stated before, the GG can be realized using the combination of VNIC cascaded by IPG. In what follows, the sensitivity of a GG realized by this structure will be examined.

Let the ING be given by the T section<sup>(3)</sup> shown in Fig. 2.1 and has

$$[a] = \begin{bmatrix} 0 & Z \\ -\frac{1}{Z} & 0 \end{bmatrix}$$

The [a] of the VNIC, shown in Fig. 1.4(b) is given by:

$$[a] = \begin{bmatrix} \frac{1-k}{k} \frac{g_2}{g_1} & \frac{g_2}{k} \\ \frac{1}{kg_1} & \frac{k+1}{k} \end{bmatrix} \quad (2.8)$$

The [a] of the cascaded network shown in Fig. 1.4(a) will be:

$$[a]_{\text{comb}} = [a]_{\text{VNIC}} [a]_{\text{ING}} \quad (2.9)$$

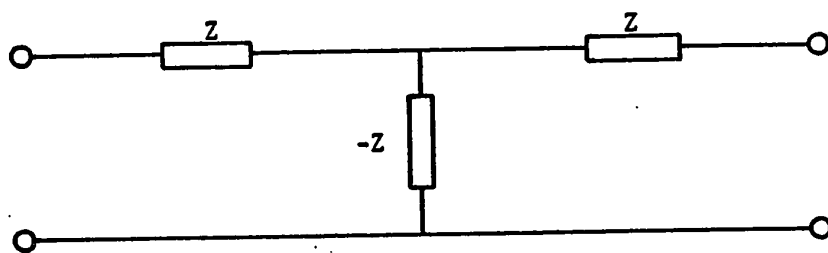


Fig. 2.1 Circuit Realization of the ING

$$= \begin{bmatrix} \frac{g_2(1-k)}{g_1 k} & \frac{g_2}{k} \\ \frac{1}{kg_1} & \frac{k+1}{k} \end{bmatrix} \begin{bmatrix} 0 & z \\ -\frac{1}{z} & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{g_2}{zk} & \frac{zg_2(1-k)}{g_1 k} \\ -\frac{k+1}{kz} & \frac{z}{kg_1} \end{bmatrix}$$

(2.10)

This is equated to the [a] of a GG

$$[a] = \begin{bmatrix} 0 & \frac{1}{g_2(s)} \\ g_1(s) & 0 \end{bmatrix}$$

from which we conclude that k must be large.

In such a case,

$$[a]_{\text{comb}} = \begin{bmatrix} 0 & \frac{zg_2}{g_1} \\ -\frac{1}{z} & 0 \end{bmatrix}$$

(2.11)

### 2.51 Sensitivity of the A,B,C, and D Parameters

The four parameters of the [a] of equation 2.10 are

$$A = - \frac{g_2}{zk} \qquad B = \frac{zg_2(1-k)}{g_1k}$$

$$C = - \frac{k+1}{kz} \qquad D = \frac{z}{kg_1}$$

Following the same procedure outlined in section 2.41 the sensitivity of the [a] of a GG, realized using VNIC succeeded by ING, with respect to a small change in the nominal value of the four elements  $g_1$ ,  $g_2$ ,  $z$  and  $k$  could be calculated. Results are shown in Table 2.2. It is obvious from Table 2.2 that the sensitivities of the [Y] parameters of the GG realized using VNIC and ING with conversion ratio equal to  $k$  could be one of three cases:

- (i) Identically to zero.
- (ii) Equal unity.
- (iii) Inversely proportional to the change in the element nominal value.

TABLE 2.2

Sensitivity of [a] parameters of a GG realized using  
 VNIC and ING with respect to small variation  
 in  $g_1, g_2, z$  &  $k$

<u>Element</u>	<u>Variation</u>	$\frac{S\alpha}{-}$	$\frac{S\beta}{\frac{1}{1+\epsilon_1}}$	$\frac{S\gamma}{-}$	$\frac{S\delta}{\frac{1}{1+\epsilon_1}}$
$g_1$ (s)	$\epsilon_1$	-	$\frac{1}{1+\epsilon_1}$	-	$\frac{1}{1+\epsilon_1}$
$g_2$ (s)	$\epsilon_2$	1	1	-	-
$z$	$\epsilon_3$	$\frac{1}{1+\epsilon_3}$	1	$\frac{1}{1+\epsilon_3}$	1
$k$	$\epsilon_4$	$\frac{1}{1+\epsilon_4}$	$\frac{1}{1+\epsilon_4}$	$\frac{1}{1+\epsilon_4}$	$\frac{1}{1+\epsilon_4}$

$S^\alpha$  = Sensitivity of variation ( $\alpha$ ) in A parameter w.r.t. element variation.

$S^\beta$  = Sensitivity of variation ( $\beta$ ) in B parameter w.r.t. element variation.

$S^\gamma$  = Sensitivity of variation ( $\gamma$ ) in C parameter w.r.t. element variation.

$S^\delta$  = Sensitivity of variation ( $\delta$ ) in D parameter w.r.t. element variation.

## 2.6 Sensitivity of GG realized using INIC and ING in Cascade

The [a] of the generalized INIC shown in Fig. 1.5b is given by:

$$[a] = \begin{bmatrix} 1 & 0 \\ 0 & \frac{g_1 + (k + 1) g_2}{g_2 - (k - 1) g_1} \end{bmatrix} \quad (2.12)$$

If the INIC is followed by the T section shown in Fig. 2.1, acting as ING, the [a] of the cascaded combination will be:

$$[a]_{\text{comb}} = [a]_{\text{INIC}} [a]_{\text{ING}} \quad (2.13)$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & \frac{g_1 + (k + 1) g_2}{g_2 - (k - 1) g_1} \end{bmatrix} \begin{bmatrix} 0 & z \\ -\frac{1}{z} & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & z \\ -\frac{1}{z} & \frac{g_1 + (k + 1) g_2}{g_2 - (k - 1) g_1} \end{bmatrix} \quad (2.14)$$

which is equivalent to [a] of a GG.

The sensitivity of the [a] parameters of (2.14) has been evaluated, and results are shown in Table 2.3. It is obvious from Table 2.3 that the sensitivities of [Y] parameters of the GG realized using INIC and ING could be one of three cases:-

- (i) Identically equal to zero.
- (ii) Equal to unity.
- (iii) Dependent on both the variation and the nominal values of the different elements used in the realization of INIC and will be less than unity.

## 2.7 Summary

In this chapter the sensitivities of the GG realized using three different methods have been examined. It has been shown that for the two realizations:

- (i) using CNICs or VNICs and passive elements
- (ii) using VNIC and ING

the sensitivities of both the structures with respect to the different elements used in the realization could be one of three cases:-

- (i) Identically equal to zero.
- (ii) Equal to unity.
- (iii) Inversely proportional to the variation in the element nominal value.

TABLE 2.3

Sensitivity of the [a] parameters of a GG realized using INIC and ING with respect to small variation in  $g_1$ ,  $g_2$ ,  $z$  &  $k$

<u>Element</u>	<u>Variation</u>	<u>S<sup>α</sup></u>	<u>S<sup>β</sup></u>	<u>S<sup>γ</sup></u>	<u>S<sup>δ</sup></u>
$g_1(s)$	$\epsilon_1$	-	-	$\frac{1}{(k-1)g_1\epsilon_1}$ $1 - \frac{1}{g_2 - (k-1)g_1}$	-
$g_2(s)$	$\epsilon_2$	-	-	$\frac{1}{1 + \frac{g_2\epsilon_2}{g_2 - (k-1)g_1}}$	-
$z$	$\epsilon_3$	-	1	$\frac{1}{1 + \epsilon_3}$	-
$k$	$\epsilon_4$	-	-	$\frac{1}{g_1k}$ $1 - \frac{1}{g_2 + g_1(1-k\epsilon_4)}$	-

S<sup>α</sup> = Sensitivity of variation (α) in A parameter w.r.t. element variation  
 S<sup>β</sup> = Sensitivity of variation (β) in B parameter w.r.t. element variation  
 S<sup>γ</sup> = Sensitivity of variation (γ) in C parameter w.r.t. element variation  
 S<sup>δ</sup> = Sensitivity of variation (δ) in D parameter w.r.t. element variation



In the other realization, where INIC and IPG are used, it has been shown that the sensitivities of the A,B, and D parameters, with respect to the elements used in the realization of INIC and IPG could be either identically equal to zero or unity; while the sensitivity of the C parameter, with respect to the elements used in the realization of INIC, depends on the variation in the element nominal value and the values of all other elements. Also the sensitivity of the C parameter, with respect to the element used in the realization of the IPG is inversely proportional to the variation in the element nominal value.

## CHAPTER III

### SENSITIVITY OF THE YANAGISAWA STRUCTURE USING THE GG AS THE ACTIVE ELEMENT

#### 3.1 Introduction

A method of realizing an arbitrary voltage transfer function, using an ING has been discussed before (5). In this method, the transfer function  $T(s)$  was assumed to be stable and in the form:

$$T(s) = \frac{P(s)}{Q(s)} = \frac{s^p + a_{p-1}s^{p-1} + \dots + a_0}{s^q + b_{q-1}s^{q-1} + \dots + b_0} \quad (3.1)$$

Where  $P(s)$  and  $Q(s)$  are arbitrary polynomials of  $s$ , but with their zeros assumed to be neither at origin nor on the negative real axis. Also it was assumed that the ING, used in the realization has only positive gyrational admittance.

In this chapter the sensitivity of the  $[Y]$  of an arbitrary voltage transfer function, realized using the structure described in Fig. 3.1, with the different realizations of the GG, will be investigated.

#### 3.2 Sensitivity of the $[Y]$ parameters of a Voltage Transfer Function Realized using GG and RC Networks

In Chapter II, the sensitivity of the GG realized using:

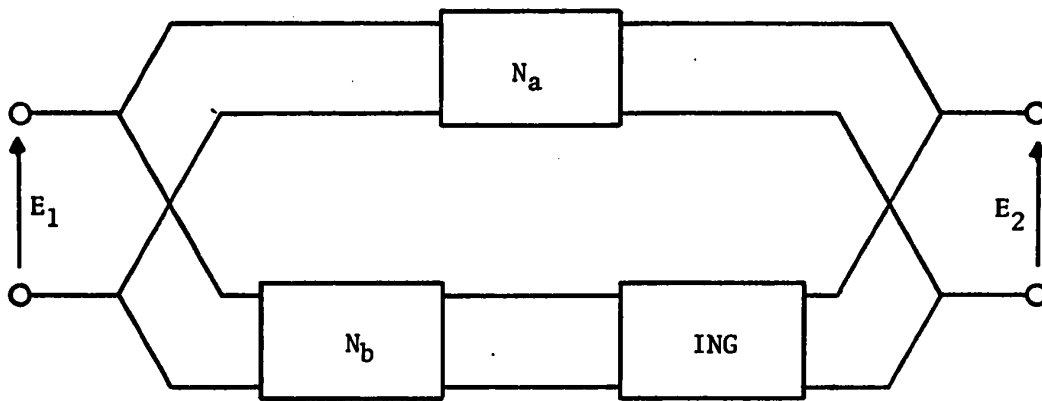


Fig. 3.1: Basic Structure used in Realizing an Arbitrary Voltage Transfer Function.

- (i) CNICs or VNICs with a conversion ratio equal to  $k$ .
- (ii) (a)- VNIC and an IPG or an ING  
       (b)- INIC and an IPG or an ING

has been discussed.

In what follows the sensitivity of the Yanagisawa structure, using the three realizations of the GG, will be investigated.

### 3.21 Sensitivity of the Structure when the GG is Realized using CNICs or VNICs

Here, it is assumed that the two CNICs or the VNICs, used in the realization of the GG, are identical and have an  $[h]$  given by:

$$[h] = \begin{bmatrix} 0 & k_1 \\ k_2 & 0 \end{bmatrix}$$

For the purpose of this study, consider the structure shown in Fig. 3.2. The  $[Y]$  of this structure will be obtained as follows. Let  $[Y]_G = [Y]$  of the gyrator portion contained within the dotted square.

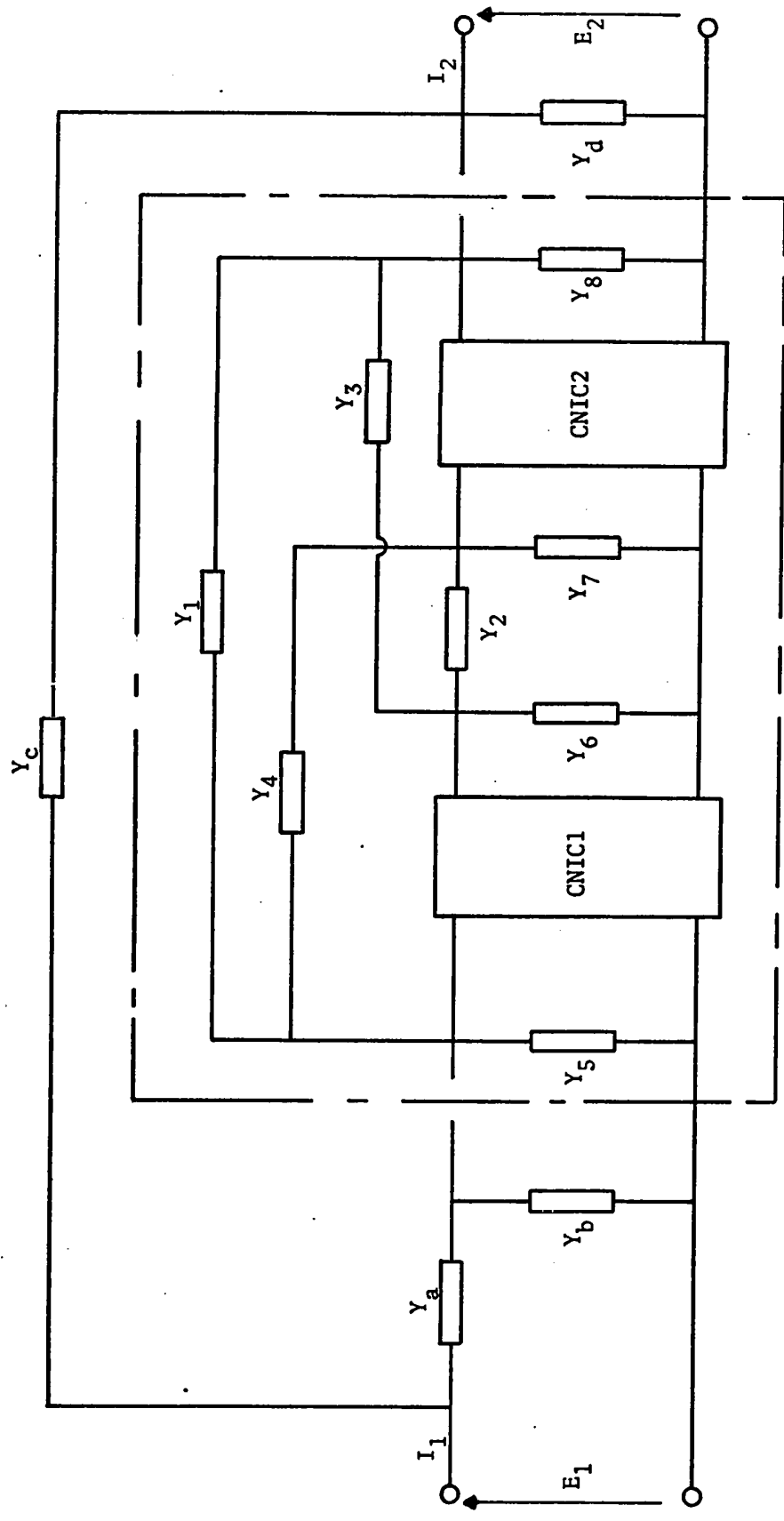


Fig. 3.2: Yanagisawa's Structure, when the GG is Realized using CNICs.

$$\begin{aligned}
 [Y]_G &= \begin{bmatrix} \frac{Y_2+Y_6}{k_1 k_2} & \frac{Y_2 k_1}{k_2} \\ \frac{Y_2 k_2}{k_1} & -(Y_2+Y_7) k_1 k_2 \end{bmatrix} + \begin{bmatrix} Y_1+Y_5 & -Y_1 \\ -Y_1 & Y_1+Y_8 \end{bmatrix} + \begin{bmatrix} \frac{Y_3}{k_1 k_2} & \frac{Y_3}{k_2} \\ \frac{-Y_3}{k_1} & Y_3 \end{bmatrix} + \begin{bmatrix} Y_4 & -Y_4 k_1 \\ Y_4 k_2 & -Y_4 k_1 k_2 \end{bmatrix} \\
 &= \begin{bmatrix} Y_1+Y_4+Y_5 & \frac{Y_2+Y_3+Y_6}{k_1 k_2} & \frac{Y_2 k_1+Y_3}{k_2} & -(Y_1+Y_4 k_1) \\ Y_4 k_2 - Y_1 + \frac{Y_2 k_2 - Y_3}{k_1} & & Y_1+Y_3+Y_8 & -(Y_2+Y_4+Y_7) k_1 k_2 \end{bmatrix} \quad (3.2)
 \end{aligned}$$

adding  $Y_b$  to  $Y_{11}$  and  $Y_d$  to  $Y_{22}$  of  $[Y]_G$  we get  $[Y]_{G'}$

$$[Y]_{G'} = \begin{bmatrix} Y_1+Y_4+Y_5+Y_b & \frac{Y_2+Y_3+Y_6}{k_1 k_2} & \frac{Y_2 k_1+Y_3}{k_2} & -(Y_1+Y_4 k_1) \\ Y_4 k_2 - Y_1 + \frac{Y_2 k_2 - Y_3}{k_1} & & Y_1+Y_3+Y_8+Y_d & -(Y_2+Y_4+Y_7) k_1 k_2 \end{bmatrix} \quad (3.3)$$

from which  $[a]_{G'} = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$  (3.4)

$$\begin{aligned} \text{where } A &= -\frac{Y_{22}}{Y_{21}} \\ &= \frac{k_1 k_2 [(Y_2 + Y_4 + Y_7) k_1 k_2 - (Y_1 + Y_3 + Y_8 + Y_d)]}{k_2 [k_1 (Y_4 k_2 - Y_1) + Y_2 k_2 - Y_3]} \end{aligned} \quad (3.5)$$

$$\begin{aligned} B &= \frac{1}{Y_{21}} \\ &= \frac{-k_1 k_2}{k_2 [k_1 (Y_4 k_2 - Y_1) + (Y_2 k_2 - Y_3)]} \end{aligned} \quad (3.6)$$

$$\begin{aligned} C &= \frac{\Delta Y}{Y_{21}} \\ &= \frac{H}{k_2 [k_1 (Y_4 k_2 - Y_1) + Y_2 k_2 - Y_3]} \end{aligned} \quad (3.7)$$

$$\begin{aligned} \text{where } H &= [k_1 (Y_4 k_2 - Y_1) + (Y_2 k_2 - Y_3)] [(Y_2 k_1 + Y_3) - k_2 (Y_1 + Y_4 k_1)] \\ &\quad - [k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_b) - (Y_2 + Y_3 + Y_6)] [(Y_1 + Y_3 + Y_8 + Y_d) - \\ &\quad (Y_2 + Y_4 + Y_7) k_1 k_2] \end{aligned}$$

$$\begin{aligned}
 D &= -\frac{Y_{11}}{Y_{21}} \\
 &= \frac{Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_b)}{k_2 [k_1 (Y_4 k_2 - Y_1) + Y_2 k_2 - Y_3]}
 \end{aligned} \tag{3.8}$$

The [a] of  $Y_a$  is given by

$$[a]_{Y_a} = \begin{bmatrix} 1 & \frac{1}{Y_a} \\ 0 & 1 \end{bmatrix} \tag{3.9}$$

From equations (3.4) and (3.9)

$$\begin{aligned}
 [a]_{Y_a, G} &= [a]_{Y_a} [a]_G \\
 &= \begin{bmatrix} 1 & \frac{1}{Y_a} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} A & B \\ C & D \end{bmatrix} \\
 &= \begin{bmatrix} \frac{AY_a + C}{Y_a} & \frac{BY_a + D}{Y_a} \\ C & D \end{bmatrix}
 \end{aligned} \tag{3.10}$$



The corresponding admittance of equation (3.10) is

$$[Y]_{Y_a, G} = \begin{bmatrix} \frac{DY_a}{BY_a + D} & \frac{Y_a (CB-DA)}{BY_a + D} \\ \frac{-Y_a}{BY_a + D} & \frac{AY_a + C}{BY_a + D} \end{bmatrix} \quad (3.11)$$

The admittance matrix of  $Y_c$  is

$$[Y]_c = \begin{bmatrix} Y_c & -Y_c \\ -Y_c & Y_c \end{bmatrix} \quad (3.12)$$

From 3.11 and 3.12

$$[Y]_T = [Y]_{Y_a, G} + [Y]_c$$

$$= \begin{bmatrix} \frac{DY_a}{BY_a + D} + Y_c & \frac{Y_a (CB-DA)}{BY_a + D} - Y_c \\ \frac{-Y_a}{BY_a + D} - Y_c & \frac{AY_a + C}{BY_a + D} + Y_c \end{bmatrix} \quad (3.13)$$

Using the equations (3.5), (3.6), (3.7) and (3.8) the parameters  $Y_{11}$ ,  $Y_{12}$ ,  $Y_{21}$  and  $Y_{22}$  of  $[Y]_T$  could be obtained.

Hence

$$Y_{11} = Y_c + \frac{Y_a [Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_b)]}{Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_a + Y_b)} \quad (3.14)$$

$$Y_{12} = \left[ Y_c + \frac{Y_a k_1 [Y_2 k_1 + Y_3 - k_2 (Y_1 + Y_4 k_1)]}{Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_a + Y_b)} \right] \quad (3.15)$$

$$Y_{21} = \left[ Y_c + \frac{Y_a k_2 [k_1 (Y_4 k_2 - Y_1) + (Y_2 k_2 - Y_3)]}{Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_a + Y_b)} \right] \quad (3.16)$$

and

$$Y_{22} = Y_c + \frac{H + k_1 k_2 Y_a [(Y_2 + Y_4 + Y_7) k_1 k_2 - (Y_1 + Y_3 + Y_8 + Y_d)]}{Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_a + Y_b)} \quad (3.17)$$

Following the same procedure described in section 2.41, the sensitivities of the different parameters  $Y_{11}$ ,  $Y_{12}$ ,  $Y_{21}$  and  $Y_{22}$  are obtained. These are tabulated in Table 3.1.

TABLE 3.1

Sensitivity of the [Y] parameters of the Yanagisawa Structure  
when the GG is Realized using CNICs and Passive Elements

<u>Element</u>	<u>Variation</u>	<u>S<sup>α</sup></u>	<u>S<sup>β</sup></u>	<u>S<sup>γ</sup></u>	<u>S<sup>δ</sup></u>
Y <sub>1</sub>	ε <sub>1</sub>	$\frac{1}{1 - k_1 k_2 Y_1 \epsilon_1}$ Q	S <sub>ε<sub>1</sub></sub> <sup>α</sup>	S <sub>ε<sub>1</sub></sub> <sup>α</sup>	S <sub>ε<sub>1</sub></sub> <sup>α</sup>
Y <sub>2</sub>	ε <sub>2</sub>	$\frac{1}{1 + Y_2 \epsilon_2}$ Q	S <sub>ε<sub>2</sub></sub> <sup>α</sup>	S <sub>ε<sub>2</sub></sub> <sup>α</sup>	S <sub>ε<sub>2</sub></sub> <sup>α</sup>
Y <sub>3</sub>	ε <sub>3</sub>	$\frac{1}{1 + Y_3 \epsilon_3}$ Q	S <sub>ε<sub>3</sub></sub> <sup>α</sup>	S <sub>ε<sub>3</sub></sub> <sup>α</sup>	S <sub>ε<sub>3</sub></sub> <sup>α</sup>
Y <sub>4</sub>	ε <sub>4</sub>	$\frac{1}{1 - k_1 k_2 Y_4 \epsilon_4}$ Q	S <sub>ε<sub>4</sub></sub> <sup>α</sup>	S <sub>ε<sub>4</sub></sub> <sup>α</sup>	S <sub>ε<sub>4</sub></sub> <sup>α</sup>
Y <sub>5</sub>	ε <sub>5</sub>	$\frac{1}{1 - k_1 k_2 Y_5 \epsilon_5}$ Q	S <sub>ε<sub>5</sub></sub> <sup>α</sup>	S <sub>ε<sub>5</sub></sub> <sup>α</sup>	S <sub>ε<sub>5</sub></sub> <sup>α</sup>
Y <sub>6</sub>	ε <sub>6</sub>	$\frac{1}{1 + Y_6 \epsilon_6}$ Q	S <sub>ε<sub>6</sub></sub> <sup>α</sup>	S <sub>ε<sub>6</sub></sub> <sup>α</sup>	S <sub>ε<sub>6</sub></sub> <sup>α</sup>
Y <sub>7</sub>	ε <sub>7</sub>	-	-	-	1
Y <sub>8</sub>	ε <sub>8</sub>	-	-	-	1
Y <sub>a</sub>	ε <sub>a</sub>	$\frac{1}{1 - k_1 k_2 Y_a \epsilon_a}$ Q	S <sub>ε<sub>a</sub></sub> <sup>α</sup>	S <sub>ε<sub>a</sub></sub> <sup>α</sup>	S <sub>ε<sub>a</sub></sub> <sup>α</sup>

Sensitivity of the [Y] parameters of the Yanagisawa Structure when the GG is Realized using CNICs and Passive Elements

<u>Element</u>	<u>Variation</u>	<u>S<sup>α</sup></u>	<u>S<sup>β</sup></u>	<u>S<sup>γ</sup></u>	<u>S<sup>δ</sup></u>
Y <sub>b</sub>	ε <sub>b</sub>	$\frac{1}{1-k_1 k_2 Y_b \epsilon_b Q}$	S <sup>α</sup> <sub>ε<sub>b</sub></sub>	S <sup>α</sup> <sub>ε<sub>b</sub></sub>	S <sup>α</sup> <sub>ε<sub>b</sub></sub>
Y <sub>c</sub>	ε <sub>c</sub>	1	1	1	1
Y <sub>d</sub>	ε <sub>d</sub>	-	-	-	1
k <sub>1</sub>	ε <sub>k<sub>1</sub></sub>	$\frac{1}{1-k_1 k_2 \epsilon_{k_1} (Y_1+Y_4+Y_5+Y_a+Y_b) Q}$	S <sup>α</sup> <sub>ε<sub>k<sub>1</sub></sub></sub>	S <sup>α</sup> <sub>ε<sub>k<sub>1</sub></sub></sub>	S <sup>α</sup> <sub>ε<sub>k<sub>1</sub></sub></sub>
k <sub>2</sub>	ε <sub>k<sub>2</sub></sub>	$\frac{1}{1-k_1 k_2 \epsilon_{k_2} (Y_1+Y_4+Y_5+Y_a+Y_b) Q}$	S <sup>α</sup> <sub>ε<sub>k<sub>2</sub></sub></sub>	S <sup>α</sup> <sub>ε<sub>k<sub>2</sub></sub></sub>	S <sup>α</sup> <sub>ε<sub>k<sub>2</sub></sub></sub>

S<sup>α</sup><sub>ε</sub> ≡ Sensitivity of variation (α) in Y<sub>11</sub> w.r.t. element variation.

S<sup>α</sup><sub>ε</sub> ≡ Sensitivity of variation (β) in Y<sub>12</sub> w.r.t. element variation.

S<sup>α</sup><sub>ε</sub> ≡ Sensitivity of variation (γ) in Y<sub>21</sub> w.r.t. element variation.

S<sup>α</sup><sub>ε</sub> ≡ Sensitivity of variation (δ) in Y<sub>22</sub> w.r.t. element variation.

$$Q = (Y_2+Y_3+Y_6) - k_1 k_2 (Y_1+Y_4+Y_5+Y_a+Y_b)$$

### 3.22 Sensitivity of the Structure when the GG is Realized using VNIC and an IPG or an ING

In this case, the GG, used in the realization of an arbitrary voltage transfer function, is realized, using VNIC and an IPG or an ING as shown in Fig. 3.3.

The [Y] of the structure shown in Fig. 3.3 is obtained, following the same procedure outlined in Case I, and is given by:-

$$[Y] = \begin{bmatrix} \frac{Y_a Y_b}{Y_a + Y_b} + Y_c & -\frac{Y_a}{z(Y_a + Y_b)} - Y_c \\ \frac{Y_a g_1}{z g_2 (Y_a + Y_b)} - Y_c & \frac{Y_d z^2 g_2 (Y_a + Y_b) g_1}{z^2 g_2 (Y_a + Y_b)} + Y_c \end{bmatrix} \quad (3.18)$$

The sensitivities of the different parameters of [Y], with respect to each element used in the realization are tabulated in Table 3.2

### 3.23 Sensitivity of the Structure when the GG is Realized using INIC and an IPG or an ING

Here, the GG used in the realization of an arbitrary voltage transfer function is realized by using INIC instead of VNIC. (See Fig. 3.4.) The [Y] of the structure shown in Fig. 3.4 is given by:

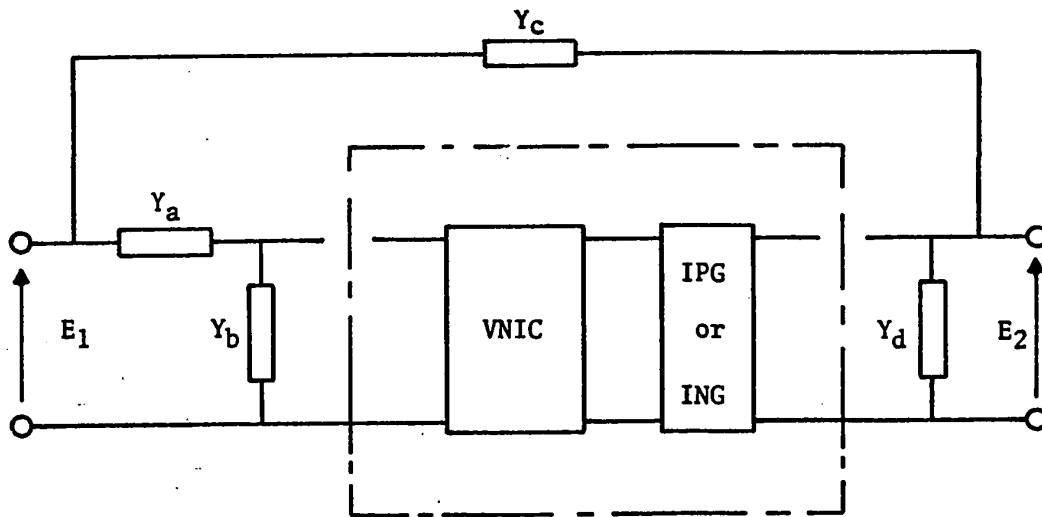


Fig. 3.3: Yanagisawa's Structure, when GG is realized using VNIC and ING.

TABLE 3.2

Sensitivity of the [Y] parameters of the Yanagisawa Structure when the GG is Realized using VNIC and ING.

<u>Element</u>	<u>Variation</u>	$\frac{S^\alpha}{S^\alpha}$	$\frac{S^\beta}{S^\beta}$	$\frac{S^\gamma}{S^\gamma}$	$\frac{S^\delta}{S^\delta}$
$Y_a$	$\epsilon_a$	$\frac{1}{\frac{Y_a \epsilon_a}{1+Y_a+Y_b}}$	$S^\alpha$	$S^\alpha$	$S^\alpha$
$Y_b$	$\epsilon_b$	$\frac{1}{\frac{Y_b \epsilon_b}{1+Y_a+Y_b}}$	$S^\alpha$	$S^\alpha$	$S^\alpha$
$Y_c$	$\epsilon_c$	1	1	1	1
$Y_d$	$\epsilon_d$	-	-	-	1
$G_1$	$\epsilon_1$	-	-	1	1
$G_2$	$\epsilon_2$	-	-	$\frac{1}{1+\epsilon_2}$	$S^\gamma$
$Z$	$\epsilon_3$	-	$\frac{1}{1+\epsilon_3}$	$S^\beta$	$S^\beta$

$S_\epsilon^\alpha$  = Sensitivity of variation ( $\alpha$ ) in  $Y_{11}$  w.r.t. element variation.

$S_\epsilon^\alpha$  = Sensitivity of variation ( $\beta$ ) in  $Y_{12}$  w.r.t. element variation.

$S_\epsilon^\alpha$  = Sensitivity of variation ( $\gamma$ ) in  $Y_{21}$  w.r.t. element variation.

$S_\epsilon^\alpha$  = Sensitivity of variation ( $\delta$ ) in  $Y_{22}$  w.r.t. element variation.

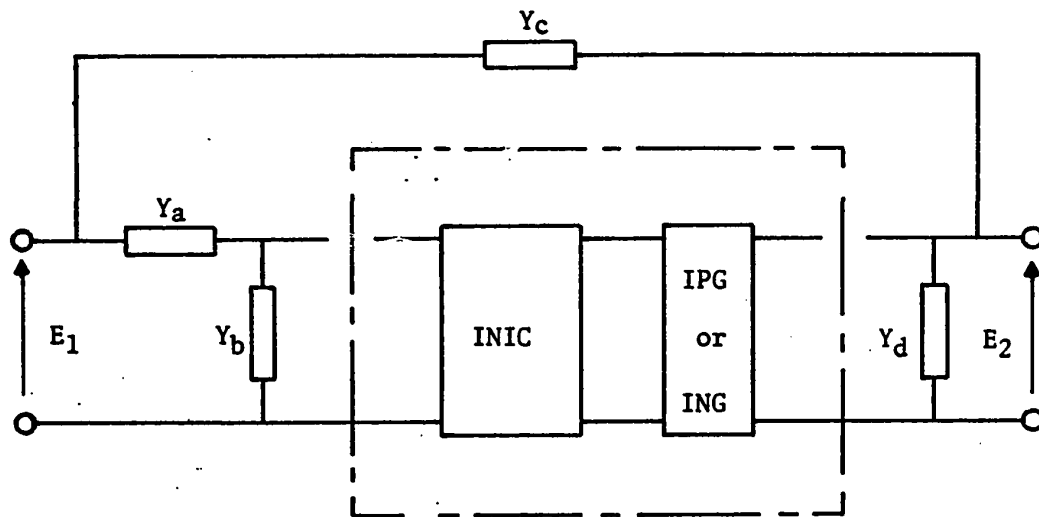


Fig. 3.4: Yanagisawa's Structure, when GG is realized using INIC and ING.



$$[Y] = \begin{bmatrix} \frac{Y_a Y_b}{Y_a + Y_b} + Y_c & \frac{g_2 (k+1) - g_1}{g_2 - (k-1)g_1} - Y_c \\ \frac{-Y_a}{Z(Y_a + Y_b)} - Y_c & \frac{g_2 [Z^2 Y_d (Y_a + Y_b) - (k+1)] - g_1 [Z^2 Y_d (k-1) (Y_a + Y_b) + 1]}{Z(Y_a + Y_b) [g_2 - (k-1)g_1]} + Y_c \end{bmatrix} \quad \dots\dots (3.19)$$

The sensitivities of the different parameters of equation (3.19) are obtained and are tabulated in Table 3.3.

### 3.3 Sensitivity of the Coefficients of a Biquadratic Voltage Transfer Function Realized using Yanagisawa Structure with the GG as the Active Element.

In this section, the sensitivity of the coefficients of a biquadratic voltage transfer function realized using Yanagisawa structure with the GG as the active element will be investigated.

The voltage transfer function of the structure shown in Fig. 3.2 is given by:

$$T_V = -\frac{Y_{12}}{Y_{22}}$$

Sensitivity of the [Y] parameters of the Yanagisawa Structure  
when the GG is Realized using INIC and ING.

<u>Element</u>	<u>Variation</u>	<u>S<sup>α</sup></u>	<u>S<sup>β</sup></u>	<u>S<sup>γ</sup></u>	<u>S<sup>δ</sup></u>
Y <sub>a</sub>	ε <sub>a</sub>	$\frac{1}{1 + \frac{Y_a \epsilon_a}{Y_a + Y_b}}$	-	S <sup>α</sup>	S <sup>α</sup>
Y <sub>b</sub>	ε <sub>b</sub>	$\frac{1}{1 + \frac{Y_b \epsilon_b}{Y_a + Y_b}}$	-	S <sup>α</sup>	S <sup>α</sup>
Y <sub>c</sub>	ε <sub>c</sub>	1	1	1	1
Y <sub>d</sub>	ε <sub>d</sub>	-	-	-	1
g <sub>1</sub>	ε <sub>1</sub>	-	$1 - \frac{1}{g_2^{-(k-1)} g_1}$	-	S <sup>β</sup>
g <sub>2</sub>	ε <sub>2</sub>	-	$1 + \frac{g_2 \epsilon_2}{g_2^{-(k-1)} g_1}$	-	S <sup>β</sup>
Z	ε <sub>3</sub>	-	-	$\frac{1}{1 + \epsilon_3}$	S <sup>γ</sup>
k	ε <sub>4</sub>	-	$1 - \frac{g_1^k \epsilon_4}{g_2^{-(k-1)} g_1}$	-	S <sup>β</sup>

S<sub>ε</sub><sup>α</sup> ≡ Sensitivity of variation (α) in Y<sub>11</sub> w.r.t. element variation.

S<sub>ε</sub><sup>β</sup> ≡ Sensitivity of variation (β) in Y<sub>12</sub> w.r.t. element variation.

S<sub>ε</sub><sup>γ</sup> ≡ Sensitivity of variation (γ) in Y<sub>21</sub> w.r.t. element variation.

S<sub>ε</sub><sup>δ</sup> ≡ Sensitivity of variation (δ) in Y<sub>22</sub> w.r.t. element variation.

$$\text{where } -Y_{12} = Y_c + \frac{Y_a k_1 [Y_2 k_1 + Y_3 - k_2 (Y_1 + Y_4 k_1)]}{Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_a + Y_b)}$$

$$Y_{22} = Y_c + \frac{H + k_1 k_2 Y_a [(Y_2 + Y_4 + Y_7) k_1 k_2 - (Y_1 + Y_3 + Y_8 + Y_d)]}{Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_a + Y_b)}$$

and

$$\begin{aligned} H = & [k_1 (Y_4 k_2 - Y_1) + (Y_2 k_2 - Y_3)] [(Y_2 k_1 + Y_3) - k_2 (Y_1 + Y_4 k_1)] \\ & - [k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_b) - (Y_2 + Y_3 + Y_6)] [(Y_1 + Y_3 + Y_8 + Y_d) \\ & - (Y_2 + Y_4 + Y_7) k_1 k_2] \end{aligned}$$

$$\begin{aligned} \text{i.e. } T_v = & \frac{Y_c [Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_a + Y_b)] + Y_a k_1 [Y_2 k_1 \\ & + Y_3 - k_2 (Y_1 + Y_4 k_1)]}{Y_c [Y_2 + Y_3 + Y_6 - k_1 k_2 (Y_1 + Y_4 + Y_5 + Y_a + Y_b)] + H + k_1 k_2 Y_a [(Y_2 \\ & + Y_4 + Y_7) k_1 k_2 - (Y_1 + Y_3 + Y_8 + Y_d)]} \end{aligned} \quad (3.20)$$

Let the given  $T_v$  be of the form

$$T_v = \frac{a_2 S^2 + a_1 S + a_0}{b_2 S^2 + b_1 S + b_0} \quad (3.21)$$

For convenience, and out of several possibilities,

let

$$\begin{aligned} Y_1 &= G_1, \quad Y_2 = SC_2, \quad Y_3 = G_3 \\ Y_4 &= G_4, \quad Y_5 = G_5, \quad Y_6 = G_6 \\ Y_7 &= G_7, \quad Y_8 = G_8, \quad Y_a = G_a \\ Y_b &= G_b, \quad Y_c = SC_2, \quad Y_d = G_d \end{aligned} \quad (3.22)$$

Substituting (3.22) in (3.20) and equating the result with equation (3.21), we get

$$a_2 = C_1 C_2$$

$$a_1 = C_1 [G_3 + G_6 - k_1 k_2 (G_1 + G_4 + G_5 + G_a + G_b)] + C_2 (G_a k_1^2)$$

$$a_0 = G_a k_1 [G_3 - k_2 (G_1 + G_4 k_1)]$$

$$b_2 = C_1 C_2$$

$$b_1 = C_1 [G_3 + G_6 - k_1 k_2 (G_1 + G_4 + G_5 + G_a + G_b)] \\ + C_2 [k_1^2 (k_2 G_4 - G_1) + k_1 k_2 (G_1 + G_5 - G_7 + G_a + G_b) \\ - k_2^2 (k_1 G_4 + G_1) + G_3 (k_2 - k_1) + G_1 - G_6 + G_8 + G_d]$$

$$b_0 = k_1^2 k_2^2 [(G_4 + G_7) (G_1 + G_4 + G_5 + G_a + G_b)] \\ - k_1 k_2 [(G_1 + G_3 + G_8 + G_d) (G_1 + G_4 + G_5 + G_a + G_b) \\ + (G_3 + G_6) (G_4 + G_7) + (G_4 k_2 - G_1) (G_1 + G_4 k_1) - 2G_3 G_4] \\ + (G_1 + G_3 + G_8 + G_d) (G_3 + G_6) - G_3^2 + G_3 G_1 [k_2 - k_1]$$

The sensitivities of the above coefficients  $a_0$ ,  $a_1$ ,  $a_2$  and  $b_0$ ,  $b_1$ ,  $b_2$  are obtained and tabulated in Table 3.4.

Next, let us investigate the existence of Yanagisawa's structure for the two cases:-

$$(i) \quad k_1 = k_2 = 1$$

$$(ii) \quad k_1 k_2 = 1$$

TABLE 3.4

Sensitivities of the Coefficients of a Biquadratic Voltage Transfer Function Realized using Yanagisawa Structure with the GG as the Active Element

<u>Element</u>	<u>Variation</u>	<u>S<sup>a2</sup></u>	<u>S<sup>a1</sup></u>	<u>S<sup>a0</sup></u>	<u>S<sup>b2</sup></u>	<u>S<sup>b1</sup></u>	<u>S<sup>b0</sup></u>
C <sub>1</sub>	α <sub>1</sub>	1	1	-	1	1	-
C <sub>2</sub>	α <sub>2</sub>	1	1	-	1	1	-
G <sub>1</sub>	ε <sub>1</sub>	-	1	1	-	1	1
G <sub>3</sub>	ε <sub>3</sub>	-	1	1	-	1	1
G <sub>4</sub>	ε <sub>4</sub>	-	1	1	-	1	1
G <sub>5</sub>	ε <sub>5</sub>	-	1	-	-	1	1
G <sub>6</sub>	ε <sub>6</sub>	-	1	-	-	1	1
G <sub>7</sub>	ε <sub>7</sub>	-	-	-	-	1	1
G <sub>8</sub>	ε <sub>8</sub>	-	-	-	-	1	1
G <sub>a</sub>	ε <sub>a</sub>	-	1	1	-	1	1
G <sub>b</sub>	ε <sub>b</sub>	-	1	-	-	1	1
G <sub>d</sub>	ε <sub>d</sub>	-	-	-	-	1	1
k <sub>1</sub>	ε <sub>k<sub>1</sub></sub>	-	Q <sub>1</sub>	Q <sub>2</sub>	-	Q <sub>3</sub>	Q <sub>4</sub>
k <sub>2</sub>	ε <sub>k<sub>2</sub></sub>	-	1	1	-	Q <sub>5</sub>	Q <sub>6</sub>

$$Q_1 = \frac{1}{C_2 G_a k_1 \epsilon_{k_1}} \frac{1}{1 - \frac{2k_1 C_2 G_a (1 + \epsilon_{k_1}) - C_1 k_2^F / G_4 + G_7}{C_2 G_a k_1 \epsilon_{k_1}}}$$

$$Q_2 = \frac{1}{G_4 k_1 k_2 \epsilon_{k_1}} \frac{1}{1 - \frac{2G_4 k_1 k_2 (1 + \epsilon_{k_1}) + G_1 k_2 - G_3}{G_4 k_1 k_2 \epsilon_{k_1}}}$$

$$Q_3 = \frac{1}{C_2 k_1 (k_2 G_4 - G_1) \epsilon_{k_1}} \frac{1}{1 - \frac{2C_2 k_1 (k_2 G_4 - G_1) (1 + \epsilon_{k_1}) + N - C_2 (k_2^2 G_4 - G_3)}{C_2 k_1 (k_2 G_4 - G_1) \epsilon_{k_1}}}$$

$$Q_4 = \frac{1}{k_1 k_2 (k_2^{F+M}) \epsilon_{k_1}} \frac{1}{1 - \frac{2k_1 k_2 (k_2^{F+M}) (1 + \epsilon_{k_1}) - (M_2^2 + k_2^{H+L})}{k_1 k_2 (k_2^{F+M}) \epsilon_{k_1}}}$$

$$Q_5 = \frac{1}{C_2 k_2 (k_1 G_4 + G_1) \epsilon_{k_2}} \frac{1}{1 - \frac{2k_2 C_2 (k_1 G_4 + G_1) (1 + \epsilon_{k_2}) - N - C_2 (k_1^2 G_4 + G_3)}{C_2 k_2 (k_1 G_4 + G_1) \epsilon_{k_2}}}$$

$$Q_6 = \frac{1}{k_1 k_2 (k_1^{F-M}) \epsilon_{k_2}} \frac{1}{1 - \frac{2k_1 k_2 (k_1^{F-M}) (1 + \epsilon_{k_2}) + (M k_1^2 - k_1^{H+L})}{k_1 k_2 (k_1^{F-M}) \epsilon_{k_2}}}$$

$$F = (G_4 + G_7) (G_1 + G_4 + G_5 + G_a + G_b)$$

$$N = C_2 (G_1 + G_5 - G_7 + G_a + G_b) - C_1 (G_1 + G_4 + G_5 + G_a + G_b)$$

$$M = G_1 G_4$$

$$H = (G_1 + G_3 + G_8 + G_d) (G_1 + G_4 + G_5 + G_a + G_b) + (G_3 + G_6) (G_4 + G_7) - 2G_3 G_4 - G_1^2$$

$$L = G_1 G_3$$

Again, for convenience and out of several possibilities, the following conditions have been chosen for the two cases mentioned above:-

$$Y_c = SC_1 \quad Y_2 = SC_2$$

$$Y_1 = Y_4 = Y_5 = Y_7 = G_1, \quad Y_3 = Y_6 = Y_8 = G_3 \quad (3.23)$$

$$Y_a = G_a, \quad Y_b = G_b, \quad Y_d = G_d$$

Substituting (3.23) in (3.20) and comparing it with (3.21), we get:-

$$a_0 = G_a k_1 [G_3 - k_2 G_1 (1 + k_1)]$$

$$a_1 = C_1 [2G_3 - k_1 k_2 (3G_1 + G_a + G_b)] + C_2 G_a k_1^2$$

$$a_2 = C_1 C_2$$

$$\begin{aligned} b_0 = G_1 [2k_1^2 k_2^2 (3G_1 + G_a + G_b) - k_1 k_2 (2G_1 + 8G_3 + G_a + G_b + 3G_d) \\ + k_1 k_2 G_1 (k_1 - k_2 - k_1 k_2) + G_3 (k_2 - k_1 + 2)] \\ - 2G_3 [k_1 k_2 (G_a + G_b) - G_d] - 3G_3^2 - k_1 k_2 G_d (G_a + G_b) \end{aligned} \quad (3.24)$$

$$\begin{aligned} b_1 = C_1 [2G_3 - k_1 k_2 (3G_1 + G_a + G_b)] \\ + C_2 [G_1 [k_1^2 (k_2 - 1) - k_2^2 (k_1 + 1) + k_1 k_2 + 1] \\ + G_3 [k_2 - k_1] + k_1 k_2 (G_a + G_b) + G_d] \end{aligned}$$

$$b_2 = C_1 C_2$$



Case (i)  $k_1 = k_2 = 1$ :

Substituting  $k_1 = k_2 = 1$  in equation (3.24) and for simplicity putting  $C_1 = C_2 = 1$ , we get:-

$$\begin{aligned}
 a_2 &= b_2 = 1 \\
 a_1 &= 2G_3 - 3G_1 - G_b \\
 a_0 &= G_a (G_3 - 2G_1) \\
 b_1 &= 2G_3 - 3G_1 + G_d \\
 b_0 &= G_1 [G_a + 3G_1 + G_b - 3G_d - 6G_3] - G_3 [2(G_a + G_b - G_d) - 3G_3] - G_d (G_a + G_b)
 \end{aligned} \tag{3.25}$$

Solving (3.25) for  $G_a$  in terms of  $G_1$ , we get :-

$$G_a^3 (b_1 + 2G_1) + G_a^2 (b_0 - a_1 b_1 - 2a_1 G_1) + G_a (2a_0 G_1) + a_0^2 = 0 \tag{3.26}$$

By assigning any positive value to  $G_1$ ,  $G_a$  could be obtained.

It is to be noticed, from equation (3.26), that  $G_a$  has at least one positive value and consequently the values of the other elements can be calculated. Hence the structure can always be realized.

Case (ii)  $k_1 k_2 = 1$

Similar to the previous case, substituting  $k_1 k_2 = 1$  and  $C_1 = C_2 = 1$  in (3.24), we get:-

$$a_2 = b_2 = 1$$

$$a_1 = 2G_3 - (3G_1 + G_a + G_b) + G_a k_1^2$$

$$a_0 = G_a [k_1 (G_3 - G_1) - G_1]$$

$$b_1 = G_1 \left( \frac{k_1^3 - k_1^4 - k_1^2 - k - 1}{k_1^2} \right) + G_3 \left( \frac{1 + 2k_1 - k_1^2}{k_1} \right) + G_d \quad (3.27)$$

$$b_0 = G_1 \left[ G_1 \left( \frac{k_1^2 + 3k_1 - 1}{k_1} \right) - G_3 \left( \frac{k_1^2 + 6k_1 - 1}{k_1} \right) + G_a + G_b - 3G_d \right] \\ - G_3 [2(G_a + G_b) - 3G_3] - G_d (G_a + G_b - 2G_3)$$

Solving (3.27) for  $G_a$  in terms of  $G_1$  we get:-

$$G_a^3 k_1^4 [G_1 (1 + k_1^2) + b_1] + G_a^2 k_1^2 [b_0 - a_1 b_1 - a_1 G_1 (1 + k_1^2) - a_0 (1 - k_1^2)] \\ + G_a a_0 [G_1 (1 + k_1^2) + a_1 (1 - k_1^2)] + a_0^2 = 0 \quad (3.28)$$

By assigning a value to  $G_1$ ,  $G_a$  could be obtained, which at least has one positive value. Hence a solution can always be found.

### 3.4 Summary

In this Chapter, the sensitivity of Yanagisawa's structure, when the GG is used as the active element, is investigated with the three different realizations of the GG.

It has been shown that the sensitivity of the [Y] with respect to the majority of the elements used in the realization depends on the variation in the element nominal value and the values of all other elements while the sensitivity of the [Y] with respect to the remaining elements does not depend upon the elemental values. However, in all the cases, the value of the sensitivity is always less than or equal to unity, (including the value zero).

Also, in this chapter, the realizability of such a structure for a biquadratic voltage transfer function has been examined and it is shown that it is always realizable.

CHAPTER IV  
CONCLUSIONS

The work in this dissertation has been divided into three parts. The first part is concerning the investigation of the sensitivities of the three Generalized Gyrator realizations. The second part deals with the sensitivity of the Yanagisawa structure when the generalized gyrator, used as the active element, is realized in three different ways. The third part investigates the realizability of this structure for a biquadratic voltage transfer function.

It has been shown that the sensitivity of GG realized, using CNICs or VNICs, with respect to all the elements used in the realization, were either identically equal to zero or unity, while the sensitivity with respect to the conversion ratio  $k_1$  was inversely proportional to the change in its value.

In contrast to the above, it has been shown that the sensitivity of the GG realized using a cascade combination of VNIC and ING, with respect to the majority of the elements is inversely proportional to the change in the nominal value.

In the third case, where the GG has been realized using INIC and ING, it is shown that, although the sensitivity of A, B, and D parameters, with respect to all the elements used in the realization are either identically zero or equal to unity, the sensitivity of the C parameter is dependent on both the variation and the nominal values of the different elements and will always be less than unity.

Sensitivity study on Yanagisawa's structure, realized using Generalized Gyrator as the active element, reveals that the sensitivity of the structure, when the Generalized Gyrator is realized using CNICs and passive elements, is better than the sensitivities of the other two structures where the Generalized Gyrotors used are realized using either VNIC or INIC cascaded by ING. This is due to the fact that the structure sensitivity with respect to all elements used in the realization is directly proportional to the factor  $Q$ . It can be seen that the sensitivity could be minimized if  $Q$  is minimized.

From the above, it is clear that, from the sensitivity point of view, the Generalized Gyrator realized, using CNICs or VNICs and passive elements, is better than the other two realizations and could improve the sensitivity of Yanagisawa's structure, if it is used. It has been shown that the above mentioned structure is always realizable for a biquadratic voltage transfer function.

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