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End Depth and Flow Relationships for Smooth Open Trapezoidal and Circular Channels

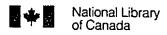
Karl Ahlen

A Thesis
in
The Department
of
Civil Engineering

Presented in Partial Fulfilment of the Requirement for the degree of Master of Applied Science at Concordia University, Montreal Quebec Canada.

February 1994

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and submitted in partial fulfilment of the requirements for the degree of

Master of Applied Science

complies with the regulations of this University and meets the accepted standards with respect to originality and quality.

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ABSTRACT

End Depth and Flow relationships for Smooth Open Trapezoidal and Circular Channels Karl Ahlen

The current study's objective was to obtain an accurate relationship between the end depth Y_e and the discharge rate for smooth open channels with trapezoidal and circular cross sections. To accomplish this, the momentum equation was used. The velocity and pressure head distributions at the end depth Y_e were determined to obtain the corresponding velocity and pressure coefficients, (alpha α , beta β and K).

The pressure head readings were obtained through the use of a static Pitot tube. Velocity readings were obtained through the use of a Pitot tube and a Laser Doppler Anemometer (LDA) system. The velocity measurements with the Pitot tube utilised procedures to take into account the curvilinear nature of the flow in the Y_a region.

The present investigation improves on existing studies in several ways.

- (1) The velocities over the entire end depth and critical depth sections for circular and trapezoidal cross sectional channels were measured over a range of flow conditions.
- (2) The pressure distribution at the end depth section

for circular and trapezoidal cross sectional channels were measured to incorporate the pressure force term in the momentum analysis.

- (3) The pressure and velocity coefficients K, α , and β were evaluated based on the velocity and pressure distribution data.
- (4) Pressure head values were also calculated indirectly at the end depth section using velocity distribution data for circular and trapezoidal cross sectional channels.

Another aspect of the study was the improved analysis of the momentum equation with the calculation of α and β coefficients for both circular and trapezoidal channels.

The improved analysis of the momentum equation provides for a more accurate functional relationship between the two flow variables. This would permit the establishment of a simple method for monitoring the flow rate in existing channels at their discharge point.

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Symbols and Abbreviations

A = cross sectional area B = Width of Channel. D and D_o = Diameter of Pipe $G = 9.81 \text{ m/s}^2 \text{ (gravitational constant)}$ $H = Pressure head P/\gamma$ K = pressure coefficient M = momentumQ = Flow rate P = pressure V or v = velocity Y = Depth Subscript e = end depth section Subscript c = critical depth section $r = Y_e/Y_e$ $v_m = maximum velocity$ z = elevation $\gamma = 9870 \text{ N/m}^3$ α' = Pressure distribution coefficient β' = Pressure distribution coefficient α = Corolis coefficient

 β = Momentum Coefficient

Chapter 1 Introduction

1.0 General Remarks

To predict the discharge in open channels, earlier studies have been conducted to determine a functional relationship between the flow rate Q and end depth Y_e. End depth relationships have been studied more extensively for the rectangular cross sectional channels than for circular and trapezoidal cross section channels. See Fig. 2.1 for a summary of previous studies.

End depth pressure and velocity fields are also available for rectangular, (Rajarantam et al 1968)) and triangular, (Repologle(1962)) cross sectional channels. Keller et al (1989) generated a pressure coefficient K, from data of the previous authors who investigated triangular and rectangular channels. The present investigation has attempted to validate the assumptions utilised in the above mentioned study. It may be noted that none of the earlier investigations had determined the nature of alpha (α) and beta (β) coefficient (Table 3.2) for circular and trapezoidal channels.

This study aims to verify basic assumptions in formulating the governing equations relating the main geometric and hydrodynamic parameters. The refinement of existing relationships between parameters was done with the

use of data collected with an Laser Doppler Anemometer (LDA) system. It should be noted that the alpha(α) and beta(β) coefficients have not been evaluated for either the circular or trapezoidal channels in previous studies. These coefficients were determined experimentally in the current study and used to accurately evaluate the momentum equation (Eq 2.3).

1.1 Scope of Study

The present study was mainly experimental and the analysis is limited to the interpretation of test data collected. The objectives of the study were as follows;

- (1) Using the Pitot and Static Pitot tube
 - (a) The pressure field for both the circular and trapezoidal open channels at the end depth and critical depth sections were measured.
 - (b) The velocities for both channels at the end depth and critical sections were measure.
- (2) Using the Laser Doppler Anemometer (LDA) data
 - (a) The three main velocity components in the trapezoidal and circular open channels were determined
 - (b) The α and β coefficients for both the trapezoidal and circular open channels were evaluated and the assumptions made in some of

- the previous studies were validated.
- (c) The momentum equation (Eq 2.3) was used to refine the Q=F(Y_e) more accurately based on the velocity and pressure distribution data.
- (d) The Pressure head (P/ γ) values were calculated from the measured velocity distribution data and compared it with the direct static probe pressure measurements.

Chapter 2 Literature Review

2.0 Introduction

To predict discharge in horizontal circular or trapezoidal channels, it is desirable to have a simple and accurate method. This method could use the end depth as a single measurement to evaluate the discharge and reduce errors. Several studies have been carried out on this topic for both channels.

2.1 Literature Review on Trapezoidal Channels

There have been numerous studies on end depths in rectangular channels while fewer studies related to trapezoidal channels. The first study into end depth relationships in rectangular channels was done by Rouse (1936) for which the Y_e/Y_c , end depth vs critical depth, ratio 0.72 was determined. Diskin(1961) performed experiments on trapezoidal channels relating Y_e to the discharge. Charts describing some of the previous studies on end depths in various types of channels are shown in Fig. 2.1.

Rajaratnam et al (1968) and Replogle (1962) performed velocity measurements in the vicinity of the end depth section in open channels with various geometries. Replogle (1962) measured the velocity profile in rectangular and triangular

sections. Rajaratnam et al (1968) measured velocity distributions in rectangular channels and calculated the β coefficient. The coefficient β ranged from 1.074 to 1.148.

There have been several recent studies to determine the nature of the Y_e/Y_c ratio for trapezoidal channels. For instance, Keller et al(1989) assumed a pressure distribution coefficient, K, (Table 3.1) from previously measured data for rectangular and triangular channels. For a rectangle channel of width B, Ferro(1992) showed that for $0.8 < B/Y_e < 17.9$ the ratio Y_e/Y_c did not change. Gupta et al(1993) obtained a dimensionless calibration curve relating $(Qm^{1.5}/g^{0.5}B^{2.5})$ with $(e^{5.5(so)}mY_e/B)$ for predicting the discharge Q with Y_e known. B was the bottom width of the channel, m was the slope of the side walls and S_c was the slope of the channel. For the present investigation, S_c was always zero. See Fig 3.1 for definition sketch.

2.2 Literature Review on Circular Channels

Both Smith 1962, and Rajaratnam et al $1964(\underline{b})$ investigated the end depth in horizontal circular channels. The studies were based solely on end depth to discharge measurements.

Smith(1962) investigated the relationship between end depth and discharge. A relationship between $A_{\rm e}/A_{\rm c}$, ratios of areas of the end depth and critical sections, and $Y_{\rm c}/D$ was

found.

Rajaratnam et al (1964) (b) investigation determined that the Y_e/Y_c ratio for horizontal circular channels was 0.725. The Y_e/Y_c ratio remained constant until the Y_c/D ratio was greater than 0.9. Rajarantam et al (1964) performed a theoretical analysis to determine a pressure factor to account for nonhydrostatic conditions. This factor was not verified through experimental investigations.

Diskin(1962) stated that a linear relationship could be generated by comparing Y_e/D vs $Q/G^{0.5}D^{2.5}$. An equation illustrating the relationship was generated(Eq 2.1).

$$\frac{Q}{(gD^5)^{0.5}} = 1.82 \left(\frac{Ye}{D_a}\right)^{1.96}$$
 2.1

Eq 2.2 shows a relationship of $Y_{\rm e}/Y_{\rm c}$ with changing pipe diameter.

$$\left(\frac{Ye}{Yc}\right) = \frac{0.72}{\left(\frac{Yc}{D_o}\right)^{0.005}}$$
 2.2

Diskin (1963) observed the Y_e/Y_c ratio to be higher than that obtained by Rajaratnam et al (1964) (b). For a ten inch diameter pipe, Diskin (1963) found the ratio Y_e/Y_c ranged from 0.785 to 1, when the Y_c/D_c ratio ranged from 0.5 to 0.132. Diskin (1963) also noted several objections to using the end depth as a measuring device. These were the existence of cross waves and a hump in the transverse section. Measuring the depth further upstream was proposed as an alternative device.

Other authors, (Argyropouls et al (1964)), expanded further on equations developed by Rajaratnam et al(1964) and Smith(1962). Compared using the end depth ratio to different formulas developed earlier for predicting the flow rates.

2.3 Theoretical Considerations

The governing equation for the end depth problem for both the trapezoidal and circular channel is the momentum equation. Eq 2.3.

$$P_{\theta} + M_{\theta} = P_{c} + M_{c} - F_{L}$$
 2.3

Here the pressure and momentum terms are represented by P and M. The suffixes e and c denote the end depth and critical sections (see Fig 3.1 for definitions). F_L represents the friction force. A through presentation of the derivation and analysis of the governing equation is presented by the several earlier investigators; (Rouse 1936, Diskin 1964, Rajaratnam 1962, and Neogy 1972).

The components of pressure and momentum at the end depth could not be evaluated easily on the basis of test data, as the flow is highly curvilinear at the end depth section. Since the stream lines were curvilinear, hydrostatic rules could not be applied. To evaluate the component terms, the following equations had to be used, (Rajarantam et al 1964 and 1968).

$$P_{\theta}=0.5K_{1}Y_{\theta}\gamma A_{\theta} \qquad 2.4$$

$$M_{\rm e} = \frac{\gamma Q^2}{g} \frac{1}{A_E} \beta$$
 2.5

For an accurate evaluation of P_e and M_e , K_1 , a coefficient to account for nonhydrostatic conditions, and β had to be evaluated. To accurately evaluate K_1 and β , experiments had to be performed. The β coefficient in previous studies had been assumed to be 1.0. This assumption would be examined in this study.

The α coefficient for the velocity had to be determined for use in the energy equation. The true velocity head is denoted by, $\alpha V^2/2g$. Alpha is known as the energy coefficient (Coriolis coefficient). It is generally not equal to unity when the flow is curvilinear.

Chapter 3 Equipment and

Procedure

3.0 Introduction

The experiment was performed on two different apparats. A diagram of each experimental layout is shown in Fig. 3.1, Trapezoidal channel, and 3.2, Circular channel.

3.1 Trapezoidal channels Equipment Set up

The smooth stainless steel horizontal channel used in this experiment had a bottom width (B) of 0.127 m, side slopes (m) of 1:1 and a height of 0.334 m(see Fig. 3.1). It was 6.85 meters long. The end section(0.70 m long) was constructed of clear plexiglass to facilitate Laser Doppler Anemometer(LDA) measurements.

Screens and a fine mesh were set up 0.50 m before the entrance to the channel to reduce large scale turbulence. A low resistance mesh, (1cm by 1cm), was placed just in the entrance to the trapezoidal channel and 0.52 m into the channel to reduce scaler turbulence in the channel. The discharge was measured with the use of a standard V-notch.

3.1.1 Laser Doppler Anemometer (LDA) Probe Positioning

A diagram of the laser mount is shown in Fig. 3.3. The moving mechanism as illustrated in Fig. 3.3 was used to move the laser probe in steps of 1mm. The probe was placed in two different orientations and was always normal to the channel walls. When the probe was placed in position 1(Fig 3.3) the axial velocity U_z and lateral velocity U_x were measured in the rectangular sub section of the trapezoidal channel. In position 2 (Fig 3.3) the probe measured the axial velocities U_z in the triangular sub section of the channel.

3.2 Circular Channel Equipment Setup

A diagram of the circular channel is shown in Fig. 3.2. It consisted of a head tank that funnelled water into a horizontal circular pipe. The pipe was 10 meters long and 0.3048 m in diameter. At the end depth section water flowed into a tail gate box and was then channelled into a standard V-notch.

A square to circular transition section was placed at the channel entrance to greatly reduce turbulence and entrance head losses. Sufficient damping devices (screens, honeycombs) were placed in the head box to reduce larger scale turbulence.

3.2.1 Laser Doppler Anemometer (LDA) Probe Positioning

For laser measurements in a circular pipe, the laser probe had to be positioned perpendicular to the channel axis to reach locations along a radial axis. Along with this requirement, the probe also had to be moved parallel to the channel axis. The LDA probe measured velocities in the θ and z directions (Fig 3.4). The velocities in the radial (r) direction were calculated using the U_z and U_θ data because U_r could not be measured. (Appendix C)

Diagrams of the laser probe mount are shown in Fig. 3.5(a) & (b). The mount consisted of a circular sleeve that was concentric to the channel and had two flanges attached to it. The two flanges were for circular rotation around the pipe at a fixed axial location. A mechanism was attached to the outer flange to allow for radial motion of the probe.

The laser mount could be moved accurately to the nearest 1 mm for linear motion and 2 degrees for circular motion.

3.3 Laser Doppler Anemometer (LDA)

The laser doppler anemometer (LDA) system used in this study was supplied by Dantec Inc. It consisted of an argon ion laser that measured velocity in two directions. The power of

the laser was 300 mw. The laser light was first directed through a transmitter that split the beam in two. After the laser beams had gone through the transmitter, they were directed through fibre optic cables to the probe. There were four laser beams coming out of the probe. Two of them were blue and the other two were green. The diameter of the beams were 1.35 mm and their wave lengths were 488.0 nm (blue) and 514.5 nm (green). The beam spacing was 38 mm and there were 35 fringes. The probe system had a light transmitting efficiency caused by the interference phenomena of about 70%.

Velocity was calculated by measuring the light scattered when extraneous particles crossed the fringe. The fringes were located in the measuring volume at the focal point of the beams. Velocity was calculated by the following equation based on manufactures calibration data.

$$U=f_{d}d_{f}=f_{d}\frac{\lambda}{2\sin\left(\frac{\theta}{2}\right)}$$
 3.1

U= Component of velocity in the plane of the two laser beams and perpendicular to their bisector.

 f_d = Doppler frequency, d_f = fringe spacing

 λ = Wavelength of laser light, θ = beam intersection angle

In the current study the collection and transmitting of light was done with one probe operating in the backward scatter mode.

3.4 Experimental Procedure

3.4.1 Critical Depth(Y_c)/End depth(Y_e) measurements

End depths, surface water profiles and side water profiles, were measured by a metric depth gauge which had an resolution of 0.10 mm. The total flow rate was measured by passing flow over a standard V-notch and using standard procedures to calculate the flow rate (Q). Critical depths (Y_c) were calculated by using standard methods (Chow 1959). The equations used are listed below.

For Circular Channels;

$$Y_c = 0.325 \left(\frac{Q}{D_o}\right)^{\frac{2}{3}} + 0.083 \left(D_o\right)$$
 3.2

For Trapezoidal Channels

$$\frac{0.5(0.127+Y_c)Y_c}{0.127+2Y_c} = \frac{(\frac{Q}{(0.127+Y_c)Y_c})^2}{2g}$$
 3.3

3.4.2 Pressure Head Measurements

Wall pressure heads were measured using manometers. A diagram of pressure tap locations are shown in Fig. 3.4 and 3.6. The pressure taps were 1.6 mm in diameter. The manometers could measure the pressure head to the nearest 0.1 mm.

The manometers displayed the static head $((P/\gamma)+z)$. To obtain the true (P/γ) value, a datum was established. The datum was the bottom elevation of the channels when $(P/\gamma)=0$.

To determine the pressure distribution in the channel flow, a static pitot tube was used. The static pitot tube measured the static head($P/\gamma+z$) at any point. Used the same datum established for wall pressure head readings.

A diagram showing the set up for the Pitot tube is shown in Fig.3.7.

3.4.3 Velocity Measurements by a Pitot Tube in Curvilinear Flow.

A static pitot tube, in conjunction with a pitot tube, was used to measure the velocity in curvilinear flow. The pitot tube was used to measure the dynamic head, $(P/\gamma + z + U^2_z/2g)$. Velocity head was calculated by subtracting the static head, $(P/\gamma + z)$ from the dynamic head, $(P/\gamma + z + U^2_z/2g)$, to get $U^2_z/2g$ and subsequently U_z . Additional details on the orientation of the axis are provided in Fig. 3.4 and 3.6.

When taking velocity measurements at the end depth, the static and dynamic pressure readings were taken at the exact same location.

3.4.3.1 Calculation of U_y , U_x , and U_r

The velocity \mathbf{U}_y had to be calculated in both the circular and trapezoidal channels using both LDA and pitot tube data by the following procedure:

- (1) The slope of the water surface at the end depth section was measured. The y and z components of the velocity at any point at the end depth section were related by the following relationship, $dy/dz = U_y/U_z$ along any stream line. The dy/dz ratio was determined by measuring the slope of the water surface and then fitting an equation to the profile by the least square method.
- (2) The slope dy/dz of stream lines was assumed to linearly increase from zero at the channel bottom, to a maximum at the water surface.
- (3) Dy/dz was obtained by multiplying the elevation of pitot tube measurement by the dy/dz/y ratio. Then multiplied the dy/dz ratio by Uz, which was measured, to obtain Uy.

For calculating U_r in the circular channel, the continuity relation was used. An initial value of U_r near the core of the channel was calculated by relating U_r to U_y by the following equation $U_r = U_y/\cos\theta$. The rest of the values for U_r were calculated using the continuity relationship. (Appendix

C Sample Calculations).

Used the measured value of U_z and the calculated value of U_y along with the continuity principle to determine U_x in the triangular section(Fig. 4.6) of the trapezoidal channel.

3.4.4 LDA Measurements

The process of measuring velocities with the laser was more involved than with the pitot tube. First the velocities could not be measured exactly at the end depth due to the disposition of the laser beams. To measure the velocity with the beams, both beams had to pass through a nearly flat surface. At the end depth section, both beams do not traverse the fluid through similar paths. Velocities at several axial locations z=1.5, 3, 6 cm upstream of the end depth section had were measured. Extrapolation techniques were then used to calculate the end depth velocities. Three locations upstream of the end depth section were considered a minimum for extrapolation purposes.

For the LDA system, continuous and repetitive modes were available. When running on continuous mode, data was saved to a file. In the repetitive mode, the average velocity on the screen along with a histogram were displayed. Both modes were used in this study. A typical velocity histogram is shown in Appendix E.

3.4.5 Determination of Pressure and Velocity Coefficients

In analyzing the results, several coefficients had to be determined due to the nonuniform velocity and pressure distributions. These included the α , α' , β and β' coefficients (Table 3.1-3.2) for velocity and pressure distributions. Other pressure coefficients were calculated (K, K_e), and used in calculating the pressure force. The pressure force is used in the momentum equation. The coefficients were used to account for non hydrostatic conditions at the end depth.

To calculate these coefficients, two different computer programs were written. One was for calculating the velocity coefficients and the other for pressure coefficients. (Table 3.1).

The source code and flow charts for all the programs are included in Appendix B. All programs were written in Turbo Pascal 6.0.

Table 3.1 (Pressure Coefficients)

Author	Formula	
	Formula	Computer Method
Chow (1959)	$\alpha^1=1+\frac{1}{Qy}\int_0^A cvda$	A = Total area of the integral dA v= Q/A C=v ² /g z=2/3 Ye
	$\beta^1 = \frac{1}{AZ} \int_0^A c dA + 1$	2-2/3 ie
Rajaratnam (1968) Rouse (1936) and more	$P_e = AK_e \frac{\gamma Y_e}{2}$	P=(p/γ)*γ*A*0.5 K1=P/(A*0.5*Ye*γ)
Keller (1989)	$K = \frac{4}{3} \frac{0.215 + 0.175 X_{\theta}}{1 + X_{\theta}} = \frac{4}{3} k_{\bullet}$	Follow equation as written

Appendix B shows a flow chart of the program for calculating the velocity coefficients. The program used a grid to determine all the incremental areas. These areas were then multiplied by the corresponding velocity component and summed up. See Table 3.2 for the procedure for calculating α and β coefficients.

Table 3.2 (Velocity Coefficients)

Coefficients	Formula
Alpha	$\alpha = \frac{\int_0^A v^3 dA}{V^3 A}$
Beta	$\beta = \frac{\int_0^A V^2 dA}{V^2 A}$

3.4.6 Verification of the Momentum Equation

To verify the momentum equation, the terms at each end of a control volume were calculated. (Fig. 3.1 and 3.2) The control volume was bound by the end depth section at the down stream location and the critical section at the up stream section. Boundary friction was neglected when balancing the momentum relation (Eq 2.3)

For calculating the pressure force at the end depth section, the following procedure was used;

- (1) Symmetry of flow was assumed and verified.
- (2) The areas at the end depth section and critical section were calculated. The area at the end depth section was divided into sub areas where the pressure head was measured or calculated.
- (3) The average pressure over a sub area was multiplied

by the sub area to obtain the pressure force.

- (4) All pressure forces over the entire end depth section were summed.
- (5) Standard procedures and formulas were used to calculate other terms in the momentum equation.

Appendix C provides for more details on the calculations related to the momentum analysis.

3.4.7 Energy equation

The main equation used for the energy analysis is the energy equation. This equation together with the continuity equation is shown below.

$$\frac{P}{Y} + z + \frac{V^2}{2g} = constant$$
 3.4

$$Q = V_1 A_1 = V_2 A_2$$
 3.5

The continuity equation Eq 3.5 was used to check for continuity of flow. Eq 3.4 was used to calculate P/ γ at the end depth section where V²/2g+z values were known.

When Eq 3.4 was used to calculate P/ γ values at a vertical end depth location, the following procedure was used.

(1) A location on the water surface across the cross section was used as the reference point to calculate P/γ for the a vertical cross section

because P/ γ =0 and z and V²/2g were known at the reference point. V is the total velocity and is defined by the following equations.

For Trapezoidal Channels

$$V^2 = U_z^2 + U_x^2 + U_r^2 3.6$$

For Circular Channels

$$V^2 = U_z^2 + U_\theta^2 + U_r^2 3.7$$

- (2) The P/ γ values were calculated over the entire end depth section at discrete locations outside the boundary layer were V^2 and z are known.
- (3) The pressure distribution in the boundary layer was assumed to be linear.

Chapter 4 Results

4.0 Introduction

For trapezoidal and circular channels the velocity and pressure head values at the end depth section were measured for a range of discharge values. With the measured data, the velocity coefficients were determined. The presentation and analysis of the results are presented in subsequent sections.

4.1 Observations

4.1.1 Pressure Head measurements

For both the circular and trapezoidal channels, the pressure along the perimeter of the end depth section was zero. In the interior of both channels, the pressure head was found to be greater than atmospheric. Figs 4.1 and 4.2 qualitatively illustrate the general pressure distributions in trapezoidal and circular channels.

Fig 4.3 illustrates a typical pressure head distribution pattern for a vertical section in a circular channel. Fig 4.4 illustrates the pressure head distribution along the periphery of the wall 3.2 mm upstream of the end depth section. Although both figures show pressure distributions in just circular channels, similar patterns were observed in trapezoidal channels.

To check that there was no sudden change of gradient in the pressure head measurements, the following ratios $P/P_{\rm ref}$ vs $L/L_{\rm ref}$ were compared(Fig. 4.5). P was the measured pressure at any given distance L from the end depth and $P_{\rm ref}$ was the pressure head at an arbitrary reference location $L_{\rm ref}$ distance from the end depth which was greater than the critical distance $L_{\rm c}$.

Fig 4.5 shows that there is no sudden change in the gradient of pressure head measurements along the centre line. No sudden change in the gradient in the pressure head measurements across the end depth section was observed. This observation would contrast with an assumption by an earlier investigator, Keller et al(1989).

As shown earlier in this study, Keller et al(1989) obtained a pressure coefficient, K Table 3.1, for trapezoidal channels from combining previous data for triangular and trapezoidal channels. This procedure would result in an imaginary line (A-B Fig. 4.6) separating the rectangle and triangle sections. At this point the pressure head distribution assumed by Keller (1989) was discontinuous (Fig. 4.6). Measured pressure head data in this study indicated that the trapezoidal channel had to be treated as a whole unit to exclude discontinuity. There was no discontinuity observed in the pressure head measurements since pressure is always continuous. Keller's assumption would also affect the pressure coefficient (K).

4.1.2 Y_•/Y_c vs Q comparisons

For circular and trapezoidal channels, the variation of Y_e/Y_c vs Q for the present study was found to correspond to previous studies. (Fig 4.7 ,4.8 and 4.9) Similarly, Rajaratnam et al (1964) (b) presented a relationship Y_e/D vs $Q/G^{0.5}D^{2.5}$ which was compared to existing data (Fig 4.8). In this study, the range of data presented, was $0.22 < Y_e/D < 0.4$ and $0.10 < Q/G^{0.5}D^{2.5} < 0.26$. A regression by the least square method was performed using the present data. This resulted in a relation between Y_e/D with $Q/G^{0.5}D^{2.5}$ (Eq 4.1).

$$\frac{Q}{(GD^5)^{1/2}} = 1.0213 \left(\frac{Ye}{D_o}\right) - 0.12848$$

Correlation was found to be very good.

Fig 4.9 shows the variation of A_e/A_c with Y_c/d were A_c and A_e are the cross sectional areas at the critical and end depth sections. The present set of data follows the trend suggested by Smith (1962).

The above comparisons were used to calibrate the equipment used in this study. Because similar results were obtained, equipment and procedure was deemed proper.

4.1.3 Velocity measurements with a Pitot tube

The highest velocities at the end depth section were observed near the bottom of the channel which was consistent with earlier observations (Rajarantam et al 1968). The axial U_z velocity distribution along the centre line corresponded qualitatively with previously published data (Insert Fig. 4.10(a)). A typical velocity contour profile developed by measured velocity points is also shown in Fig. 4.10(a) along with sample measured data.

Fig 4.10 (b) shows the axial velocity contours for a circular channel using Pitot tube measurements

For a numeric comparison of the velocity profiles for both channels and with Rajarantam et al (1968), refer to Fig 4.10(c). This figure shows the profile developed from both pitot tube and LDA measurements.

4.1.4(a) Laser Doppler Anemometer (LDA) Measurements for The Trapezoidal Channel

Velocities were measured or calculated according to procedures laid out in section 3.4.3 The laser probe measured velocities in two directions.

Fig 4.11 (a)-(c) illustrates typical velocity contours for all 3 velocity components at $Y_{\rm e}$ for one given flow rate in

a trapezoidal channel. Sample velocity measurements are also included in Fig4.11(a)-(c) Velocities were measured for six different flow rates. The contours for each velocity component of all flow rates showed similar patterns.

The axial velocity U_z for all flow rates where velocity measurements were taken, were multiplied by the incremental areas to directly calculate the flow rate. The difference between the calculated and measured flow rates was less than 5%. Irrotationality out side the boundary layer and continuity of the flow were also checked and confirmed through the use of basic principles (Appendix C).

In Keller et al(1989) study, the boundary line between the rectangle and triangle section was assumed to have a velocity of zero(line A-B, Fig 4.6). As can be seen in Fig 4.11(a), the velocity is not zero at this boundary line. This assumption would affect the value of the α and β coefficients

4.1.4(B) Velocity Measurements for Circular Channels

The results of the LDA tube measurements for circular channels are shown in Fig. 4.12(a)-4.12(c). Velocity measurements were taken for six different flow rates. Fig 4.12(a)-4.12(c) show the three components of velocities for a given flow rate using LDA. All velocity profiles for all flow

rates showed similar patterns. For the circular channel, the θ , r and z cylindrical coordinate system is shown in Fig 3.4. The velocity in the θ and z direction were measured while the velocity in the r direction was calculated using the z and θ values, (Appendix C). The boundary layer was also found to be around 0.1Y, when θ ' was 0° .

Because of limitations with the range of the laser, the pitot tube had to be used for regions which were out of range of the LDA lens. At the higher flow rates, pitot data was used in the 10 to 15% of the centre region that was not covered by LDA data. Procedure to measure velocities with the pitot tube were described in section 3.4.

Velocities calculated by the pitot tube data in regions were the velocity was measured by the laser showed close correlation in the U_z direction. Could then use a hybrid set of data to generate the velocity contours.

Along the 5° radial line (Fig 4.12(a)), the velocities in the z direction showed the same characteristics as the results of Rajarantam et al (1968) (Fig 4.10 (c)).

The θ velocity on any given radial line increased from zero at the centre line to a maximum. The maximum was at a given angular distance θ' from the centre line from where it would decrease until the water surface. Fig 4.12(b) insert illustrates the above described relationship.

As in the trapezoidal channel, the axial velocity $\mathbf{U}_{\mathbf{z}}$ for all flow rates were multiplied by incremental areas to

directly calculate the flow rate. The difference between the calculated and measured flow rates was less than 5%. Irrotationality out side the boundary layer and continuity of the flow were also checked and confirmed through the use of basic principles (Appendix C). Irrotationality was checked in three othoganal directions (x,y,z).

4.1.5 Comparisons between pitot tube and laser measurements

The LDA was able to measure the velocity more accurately than the pitot tube and could also measure the velocity in two directions. It was more sensitive to fluctuations of velocity, especially near the channel surface because it was non intrusive. It could also measure velocities closer to the channel bottom than the pitot tube. The pitot tube was more sluggish in its response to velocity changes. Measuring, curvilinear flow posed no difficulties to LDA measurements.

4.1.6 Flow Profile

The slope of the water surface(dy/dz) at the end depth increased as the discharge(Q) decreased. This would indicate that the component U_y relative to U_z would increase as discharge decreased. When the end depth was approximately two

centimetres, the flow began to wrap around the end depth section. Data was not taken at these flow rates because surface tension forces became significant.

4.2. Calculated pressure coefficients

There were several kinds of pressure coefficients that were evaluated. The most common definition of the pressure coefficient used is stated in Eq 3.5 and was used by Rouse (1936) and Rajarantam (1968). Another definition for the pressure coefficient was introduced by Replogle (1962) and is stated below;

$$K_r = [(((P/\gamma) + z) - z)/Y]_{max}$$

 K_r could be determined experimentally. Keller(1989) introduced a pressure coefficient K, (Table 3.1), which was based on the end depth. Two other coefficients, (α' and β' Table 3.1), were used to analysis curvilinear flow (Chow 1955).

To calculate the above pressure coefficients for the trapezoidal channel, a computer program was written. Table 4.1 shows the pressure coefficients calculated for the trapezoidal channel. A graphical presentation of the results are shown in Fig 4.14.

Table 4.1 Calculated Pressure Coefficients For Trapezoidal Channel

Y _e (cm)	α'	β'	K ₁	K	K _r
Set 1	z = 0	mm	Location	A Fig	4.14
10.7	1.026	1.018	0.282	0.262	0.276
9.0	1.018	1.012	0.289	0.264	0.299
7.9	1.013	1.009	0.303	0.266	0.303
6.4	1.009	1.006	0.297	0.268	0.312
Set 2	z = -5	mm	Location	B Fig	4.14
10.7	1.024	1.016	0.235	0.262	0.234
8.7	1.028	1.019	0.276	0.265	0.246
7.3	1.011	1.008	0.288	0.267	0.287
5.0	1.004	1.002	0.282	0.272	0.326
Set 3	z = -7	mm	Location	C Fig	4.14
11.4	1.040	1.025	0.220	0.261	0.219
9.3	1.029	1.020	0.258	0.264	0.228
9.2	1.027	1.018	0.218	0.264	0.218
8.1	1.022	1.015	0.235	0.265	0.248
5.4	1.011	1.007	0.282	0.270	0.287

Caption

 Y_e = end depth

 α', β' = Pressure coefficient (Chow 1955)

 K_1 = coefficient as defined by Rajaratnam (1967) (See Table 3.1)

K = coefficient as defined by Keller (1989).(See Table 3.1)

 K_r = coefficient as defined by Replogle (1962) = $(P/\gamma/y)_{max}$

With respect to trapezoidal channels, there was an observable increase in α' and β' with an increase in Y_e . Coefficient, K, determined by Keller(1989) increased with Y_e .

A similarity in values between K_1 and K_r was observed. In Fig. 4.13 a comparison of pressure head coefficients, K_1 for circular, trapezoidal and rectangle channels is shown. The pressure head coefficients for the circular and trapezoidal channels were determined in this study, using Repogle's definition, while earlier studies had determined the values for rectangle channels.

The values of K_1 and K_r varied with the three sets as can be seen in Fig 4.14. The variation can be explained by the location of the Pitot tube. For set 3(Location C) the pitot tube was 7 mm down stream of the end depth section and had the lowest pressure head distribution values. The trend of decreasing pressure head values at sections down stream of Y_e was expected because the pressure head distribution would eventually become atmospheric throughout the flow region.

4.3 Calculated Velocity coefficients, α and β .

For both channels the α and β velocity coefficients were calculated and found to range from 1.03 to 1.10 for trapezoidal channels and 1.03 to 1.07 for circular channels. The coefficients were calculated using the formulas in (Table 3.2). Eq 4.2 and 4.3 were also used to calculated the α and β coefficients (Chow 1959).

$$\alpha = 1 + 3\epsilon^2 - 2\epsilon^3$$
 4.2

$$\beta = 1 + \epsilon^2$$
 4.3

$$\varepsilon = (U_m/U) - 1 4.3(a)$$

Um = Maximum velocity

U = Average velocity

Similar results were obtained from both formulas.

Rajarantam(1968) reported β values of 1.07 to 1.14 for rectangular channels.

4.4 The Momentum Equation

The momentum equation used in this present analysis is shown in Eq 2.4-2.6. In this discussion the friction force F_1 was neglected, since its value was found to be less than 1% of total forces.

The pressure force P_e was calculated with knowledge of measured pressure heads across the whole channel cross section. After determining the pressure force P_e at the end depth, the momentum equation was applied. Tables 4.2 and 4.3 show the results of applying the momentum equation at varying flow rates for the two different channel geometries used in this study. Refer to Appendix C for procedure used in

calculating the pressure force and other terms of the momentum Equation, (Eq 2.3), at the end depth section.

Table 4.2 Momentum Analysis for Trapezoidal Channels

Flow Rate	Y _e (cm)	Y _e (cm)	$M_e + P_e (N)$	M _c +P _c (N)	Me+Pe(N) ×
33.96(1/s)	10.16	13.97	52.8	57.0	56.62
27.46(1/s)	9.17	12.69	39.7	43.5	41.02
26.60(1/s)	8.87	11.94	39.5	41.2	40.5

Table 4.3 Momentum Analysis For Circular Channels

Flow Rate	Y _e (cm)	Y _c (cm)	$M_e + P_e (N)$	M _c +P _c (N)	M _e +P _e (N) *
38.76(1/s)	11.61	14.86	64.5	68.3	67.3
38.32(1/s)	11.11	14.76	63.0	67.3	67.0
27.57(1/s)	9.36	12.34	42.1	44.2	43.9
22.9(1/s)	8.5	11.2	33.3	35.0	34.5

* = analysis that include the β coefficient where β =1.05 for the trapezoidal channel and 1.03 for the circular channel.

Two of the trials showed near exact matching of the sum of the components of the momentum equation for the end depth and the critical section. Theoretically this is what was expected. When the β was added the equations balanced.

The main objective of this study was to obtain an equation to calculate Q by measuring $Y_{\rm e}$. This was done by using the total momentum calculated for the critical section and equations presented in section 2.3. It was done for all flow rates in table 4.2 and 4.3. The comparisons for the highest flow rate for both channels is presented below;

Discharge Discharge

Measured Calculated

Trapezoidal Channel 33.96 1/s vs 34.39 1/s

Circular Channel 38.76 1/s vs 39.65 1/s

The flow rates were calculated considering $\boldsymbol{\beta}$ to be greater than unity.

4.5 Discussion of energy equation

4.5.1 Application of the energy equation from the critical section to end depth section.

The energy relation Eq 3.4 was used to indirectly calculate the pressure head distribution at the end depth section using the velocity distribution data. Velocity and pressure head readings at the critical section, where the pressure head distribution was hydrostatic, were measured so that the total head could be evaluated. Eq 3.4 was then applied from the critical section to the end depth section (Fig 3.2). The velocity used in the energy equation was always the total velocity U as defined in Eq 3.6 and 3.7. One could only apply Eq 3.4 outside the boundary layer region. Fig 4.15 shows the velocity distribution at the critical and end depth section and the approximate boundary layer location.

4.5.2 Application of Energy Equation at the vertical End Depth section

The P/ γ values at discrete locations over a vertical cross section at the end depth section were individually obtained by the measured velocity distribution at these points. The details of the procedure are explained in section 3.4.7. Close agreement with the indirectly calculated P/ γ values and those directly measured by a pitot static probe was observed. Refer to Table 4.4 for a comparison of calculated P/ γ values and measured values.

Table 4.4 Comparisons of calculated and measured P/ γ values(Circular Channel) (Typical Test Condition)

Elevation (cm)	$(P/\gamma)/Y$ calculated $[Y_e=6.98]$ Q=18 1/s	(P/γ)/Y Measured
5.6	0.17	$[Y_e=7.10]Q=18.4 1/s$ 0.17
4.6	0.23	0.25
3.6	0.27	0.31

The differences in values can be attributed to the boundary layer effects

4.6 Momentum Analysis with Calculated Pressure head data for Circular Channel

The momentum analysis was applied with the calculated pressure head data and compared with the data in Table 4.2 and 4.3. The results of the comparison show a similar correlation between the sum of $M_{\rm e}$ and $P_{\rm e}$ vs sum of $M_{\rm e}$ and $P_{\rm c}$ (Eq 2.3) which were based on the following;

- i) Measured P/ γ values based on static probe data.
- ii) Calculated P/ γ values based on the velocity distribution data.

In table 4.5 are the results of the momentum analysis with calculated pressure head values (Eq 3.4).

Appendix C shows the data and calculations used in the momentum analysis. The pressure heads were calculated with use of the energy equation.

Table 4.5 Momentum Analysis with Calculated Pressure Forces

For Circular Pipes (High, Middle and Low Flow rates)

				DOW ITOW IA	
Q(1/s)	Y _e (Cm)	Y _c (cm)	$M_e + P_e (N)$	$M_e + P_e(\beta)$	$M_c + P_c (N)$
40.71	11.91	15.88	70.62	72.52	73.12
31.74	9.66	13.6	51.05	52.41	53.48
18.0	6.98	9.83	25.68	26.36	25.53

 $\beta{=}1.03$,Calculated from velocity data measured by the laser.See Eq 2.3 for momentum equation.

Clearly the addition of the β coefficients did make a difference in the calculations. It accounted for an additional three percent difference in the sum of the P_e and M_e terms (Eq 3.3). As can be seen in Table 4.5, the β coefficient improve the balance of the momentum equation.

The coefficient α was used in calculating $P_e.$ The momentum analysis with calculated P/ γ values and measured ones were compared. An improvement was observed (Tables 4.2-4.5), when the α coefficient was incorporated into the momentum analysis.

4.7 Discussion of Free vortex model of Ali(1972)

Ali(1972) analyzed the end depth problem on the basis of the free vortex theory. It was found that there could be a close correlation between experimentally determined end depths and the predicted end depths.

Ali (1972) derived two equations from the free vortex theory for the velocity of lower and upper stream lines. These formulas are shown below as in Eq 4.4 and 4.5

$$Vu = (2*g(H-h_a))^{0.5}$$
 4.4
 $Vl = (2gH)^{0.5}$ 4.5

H= Height of water surface Vu=upper stream line Vl=lower stream line H= H_c + A_c /2 T_c The velocities calculated with the above equations did not correspond with measured data. Values calculated by Ali(1972) were either too high or too low. For example, at Ye = 11.65, the lower velocity was measured as 1.67 m/s. Calculating this velocity from formula 4.5 resulted in a velocity of 2.3 m/s. The velocity for the upper stream section was lower than measured. However the difference was smaller. There were a couple of problems with the analysis related to the facts presented below;

- i) Stream lines in a vertical plane are not strictly circular.
- ii) The radius of curvature increases as one moves towards the interior of the flow region.

Chapter 5 Conclusions

5.0 General Remarks

New information relating the flow rate (Q) and end depth (Y_{α}) in trapezoidal and circular channels smooth open channels was obtained.

5.0.1 Trapezoidal Channel

In the current study, the velocity and pressure distributions for the trapezoidal channel were obtained, considering the end depth and critical depth cross section as a whole unit. The three components of velocity were also determined. This enabled the accurate determination of the velocity and pressure coefficients (α , β and K) from the velocity and pressure distribution data. The above coefficients were then used with the momentum equation to accurately evaluate the Q=F(Y_e) (Eq 2.3-2.5) relationship. The α and β coefficients were found to range from 1.03-1.07.

5.0.2 Circular Channel

The velocity and pressure head distribution for the entire end depth cross section permitted the evaluation of the

velocity(α and β) and pressure (K) coefficients. All other objectives laid out in section 1.1 were meet. This enabled one to accurately balance the momentum equation and establish the Q=F(Y_e) relationship.

5.0.3 Calculated Pressure Head Values

The energy equation (Eq 2.3) was used successfully to determine the end depth pressure field at the end depth section using the measured velocity distribution at that section.

5.0.4 Concluding Remarks

The accurate determination of the Q=F(Y_e) relationship would permit a cost effective method of flow rate monitoring at point source discharge locations.

5.1 Recommendations

- Measure all 3-d component with an LDA system instead of calculating one component, knowing the other two components.
- Perform measurements on channels with variable slopes and roughness values

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Appendix A

Fig. 2.1(a): List of Previous Studies

Renarks	Brect solution of end depth problem found Solution used to product discharge	Used relaxation method	Pressure Distribution Parabolic at Ye Pressure coefficient = P/(byY /2)	Velocity and Pressure distribution Investigated	Pressure and velocity distrubution similar to 68 study	Rougher surface = lower Ye/Yo Ratio Deterniation of Discharge at end Depth Q = 1/YC g b "82bYe"
Results	Results Similar to BullerCSG) Birect Found	solved for various Fo Used	Pressure Distribution Press	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	study	Range Studied BGYe/Yckla Rou BJYYc/Yckla Bot Charrel surfaces Glass, Canvas and Sand Pain:
Model	Rectangular Flune Trangular & Exponential Channels Vooden Sides	Numerical	Rectongular Free Overfall D-0.381n V V=0.457n L=6.09n	<u> </u>	Pressure & velocity Distribution for Sharp- crested Viers	Bauer & Graf Regtangular chamel Different Slopes and Materials Constant Slope
Invstigators	Rajaratnan t Hurakenar (1962)	farklandK19657	Rajaratnan E Huralidhar	(896))	Rajaratnan E Kuralidhar (1971)	Bauer & Graf (1971)

Fig. 2.1(b): List of Previous Studies

Investigators	Model	Resuts	Renarks
Au & Sykes (1972)	Used Rectangular+ Traingular Y3/YC=0.703 [_] Models Channel Length=6.in Ye/YC=0.793 \	Y3/Yc=0.703 [Compared results to nonentum and free Vortex theory
Neogy (1972)	Trapezoidal Broad Crested Veir	0.757>Ye/Yc>0.744 6.13>Bredth of wier Crest >2.6in	Lagfo vs Ye/Yc = thear No variation of Ye/Yc with bredth of weir crest
Rajaratnan L Muralidhar (1976)	Blocks to simulate Roughness	Pressure distribution sane as 68 study	Ks/Yc>al – Ye/Yc affected Ks=Height of Roughness block
Hager (1983)	Analytical investication	Fo increased Profile Uke Jet	Attempted to deternine surface profile through analytical means
Christodoulou (1985)	Christodoulou Used rectangular channel (1985) with variable drop sections	Ye/Yc decreased as Drop section Increased	Drop section found to affect Ye/Yc
Nezu & Rodi (1986)	Channel diresions L=20n V=0.6n, D=0.65n Flure Hydraudcally snooth Used LDA system	Friction velocity+Renolds Stress increases near mall	LDA system abtained nore accurate data
Keller Fong (1989)	Trapezoldal Flune	nYe/b .s G*n³/gb* relation ship obtained k=<4/3X<0.215+0.175Xe>	Dotained value for pressure coefficient combined known values for traingle and Regtangular channels

Fig. 2.1(c): List of Previous Studies

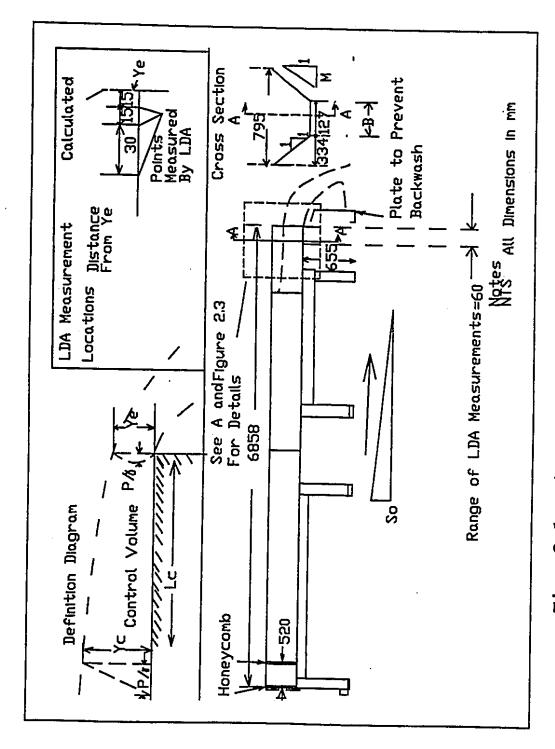


Fig. 3.1: Diagram of Trapezodial Channel

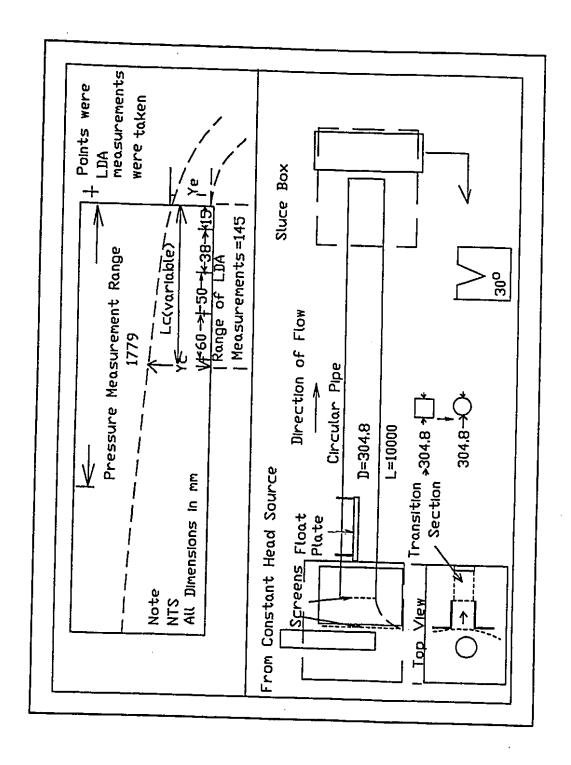


Fig. 3.2: Diagram of Circular Channel

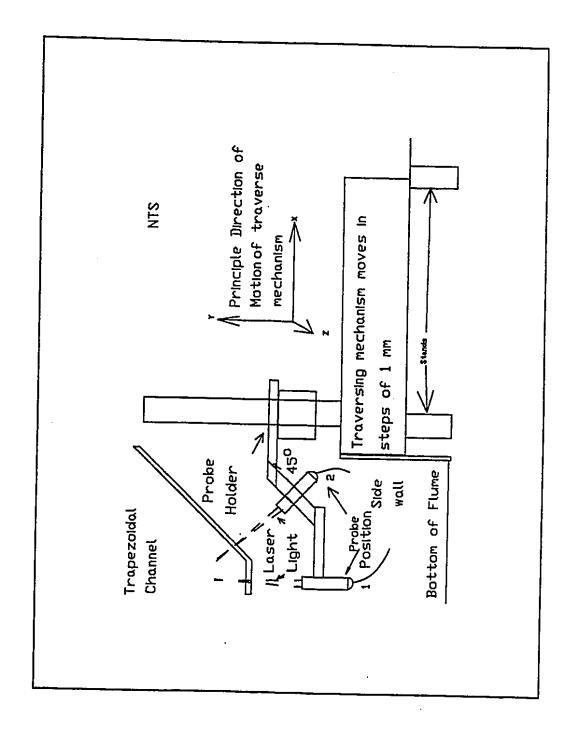


Fig. 3.3: Mount for Probe For Trapezoidal Channel

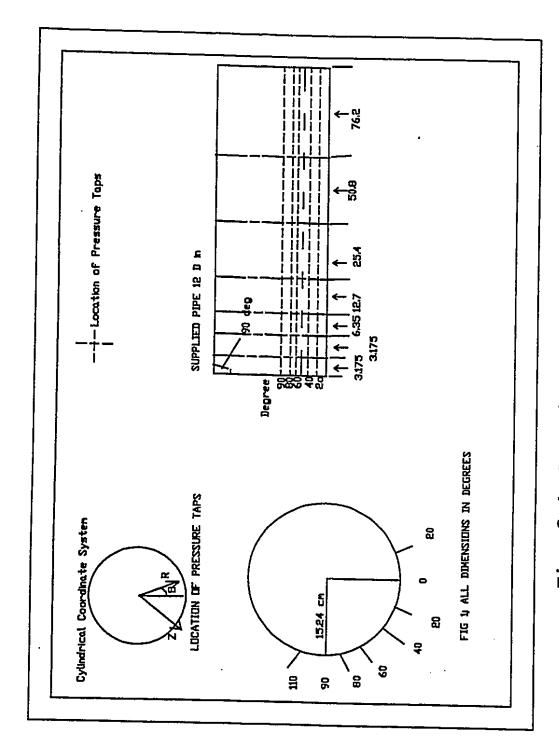


Fig. 3.4: Location of Pressure Tabs

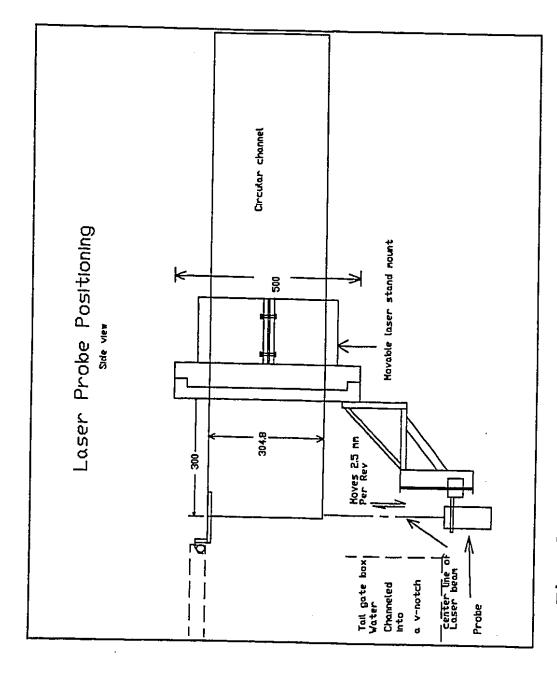


Fig. 3.5(a): Circular Laser Probe Positioning

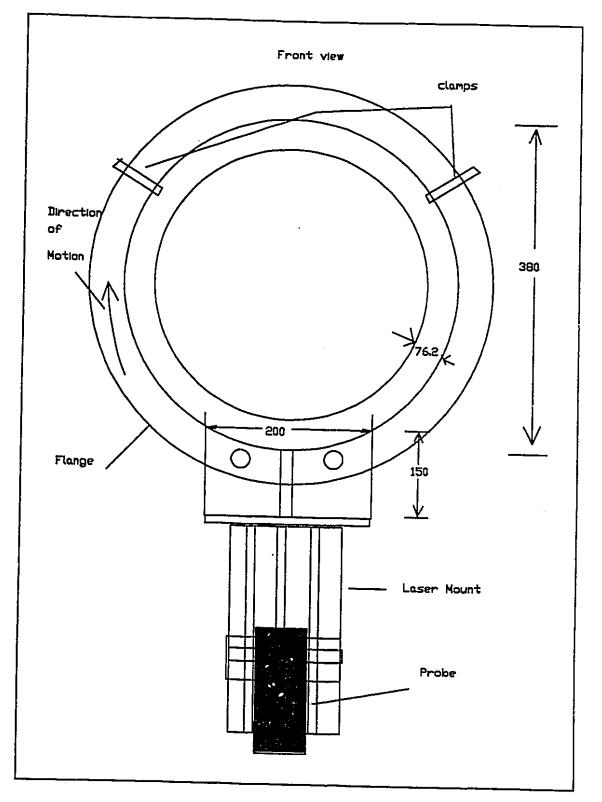


Fig. 3.5(b): Circular Laser Probe Positioning

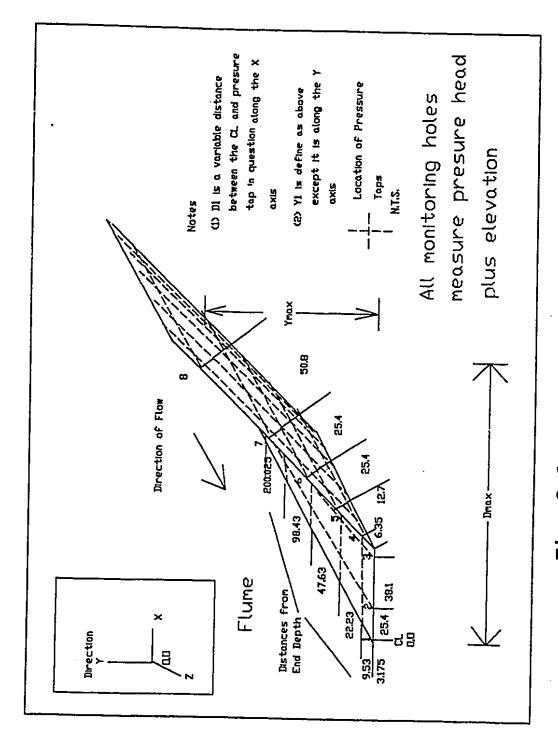


Fig. 3.6: Pressure Tap Location

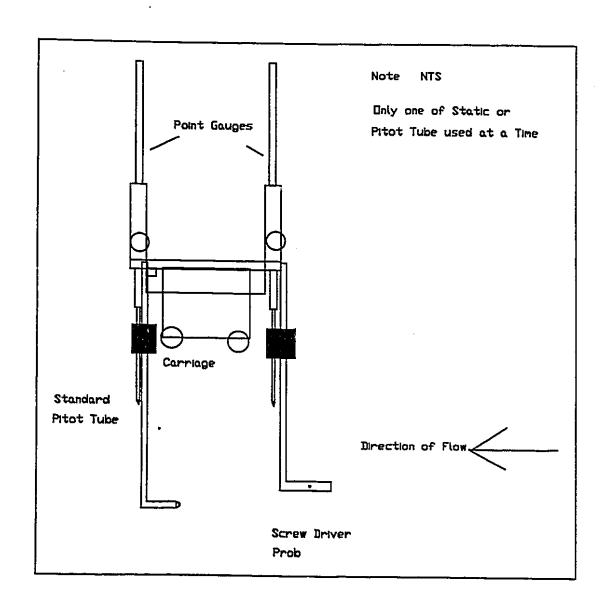


Fig. 3.7: Mounting for Pitot Tubes

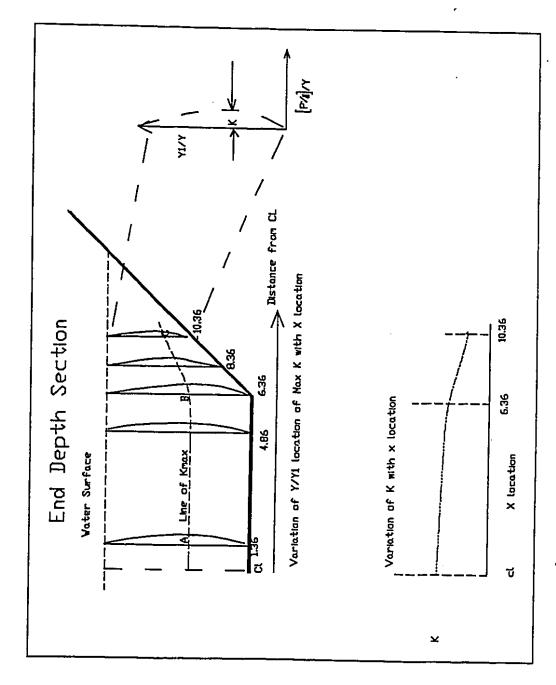


Fig. 4.1: Pressure Distribution at Brink

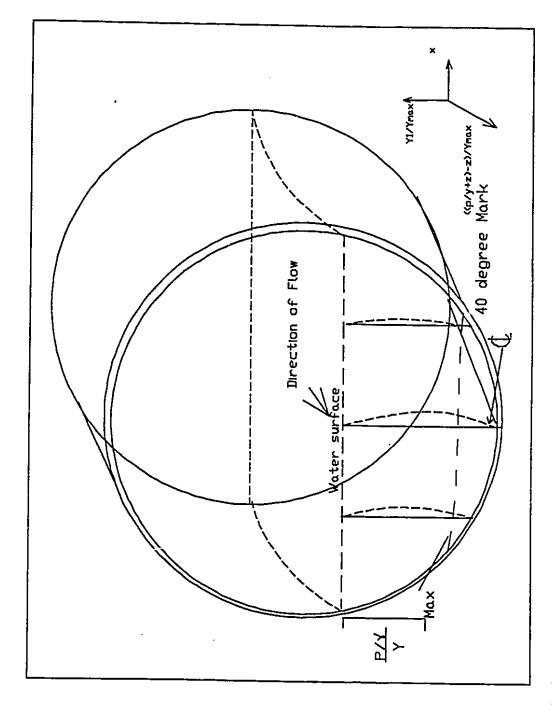


Fig. 4.2: Pressure Distribution at Brink Depth

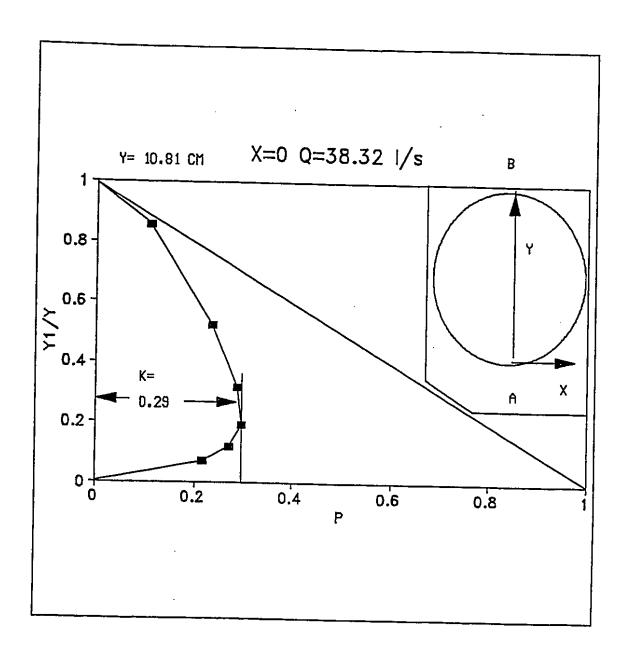


Fig. 4.3: Variation of P with Y1/Y $P=((P/\gamma+z)-z)/y; \text{ along center line } (A-B)$

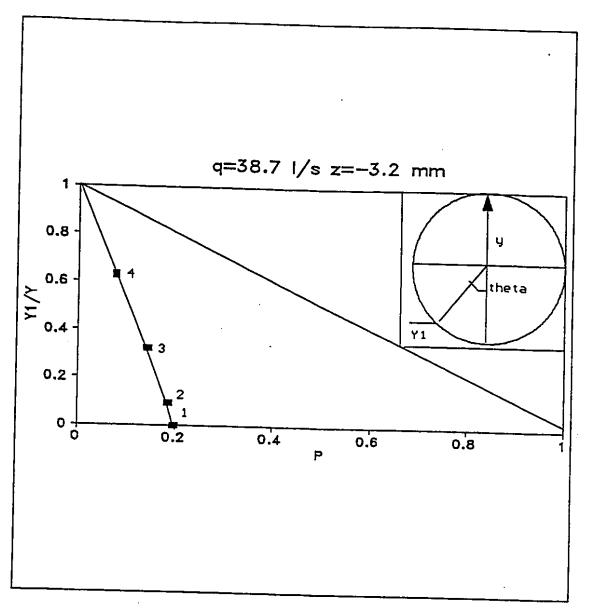


Fig. 4.4: Variation of P with Y1/Y $P=((P/\gamma+z)-z)/y; \text{Instert: wall pressure tap location: Y1=Y at Free Surface}$

Position Theta	
Theta	Height (Y1) (mm)
0	0
20	10.16
40	36.1
60	76.2
	Theta 0 20 40

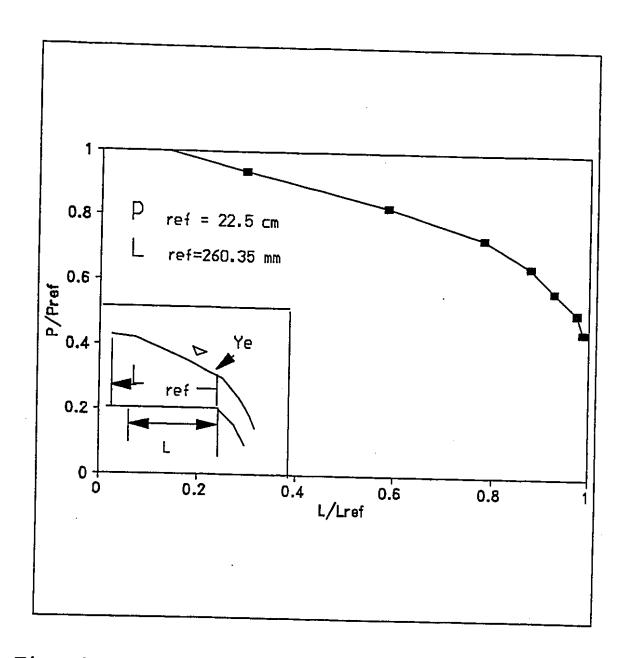


Fig. 4.5: Variation of P/Pref with L/Lref (Static Wall Profile along Channel Axis, X=0,Y=0) Q=38 l/s, Y== 11.2 cm, $P=P/\gamma=$ wall Pressures

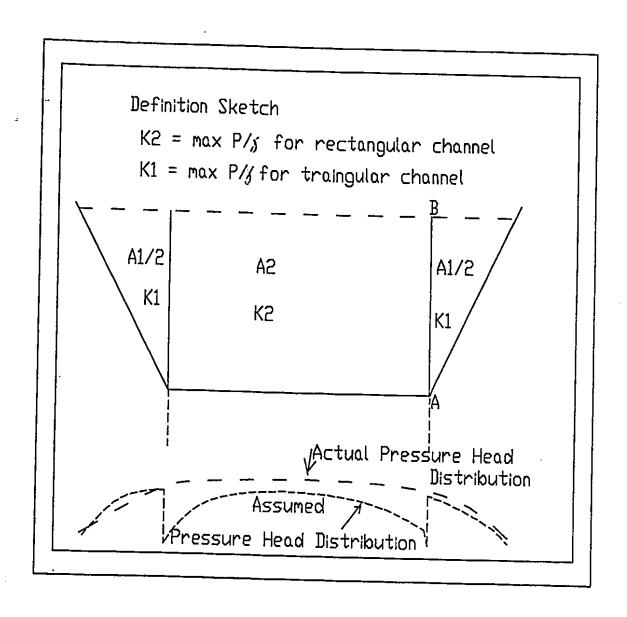


Fig 4.6: Definition Sketch used By Keller (1989) To calculated a pressure head coefficient.

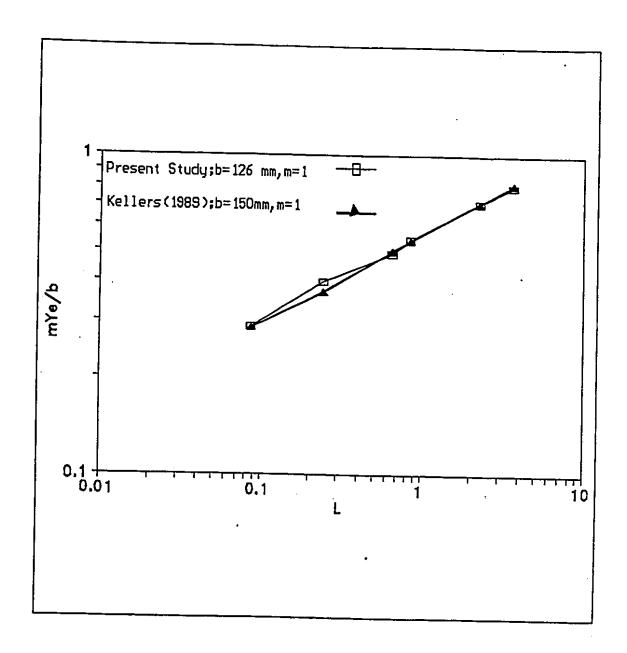


Fig. 4.7: Variation of mY_e/b vs L $L=Q^2m^3/gb^5$ m=side slope of channel

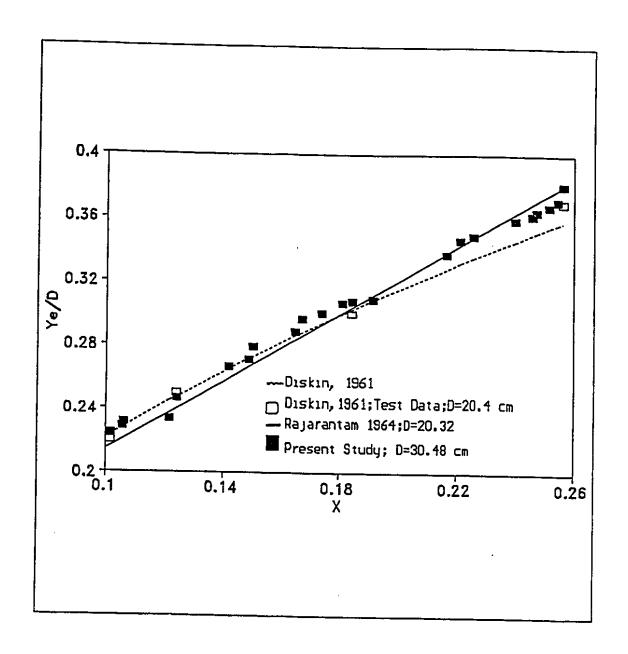


Fig. 4.8: Variation of Y_e/D with Parameter X $X=Q/(g^{0.5}D^{2.5})$

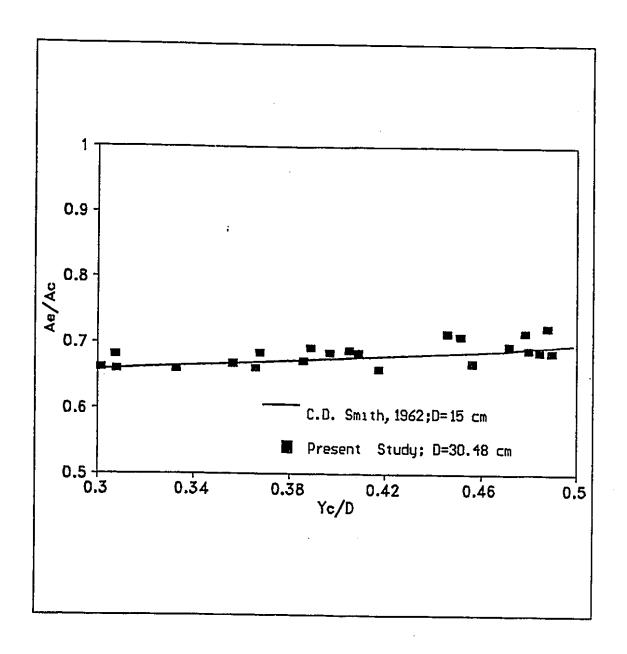


Fig. 4.9: Area Ratio vs Y_c/D Comparisons with Existing Data A = Frd donth area

A_e= End depth area

A_c= Critical section area

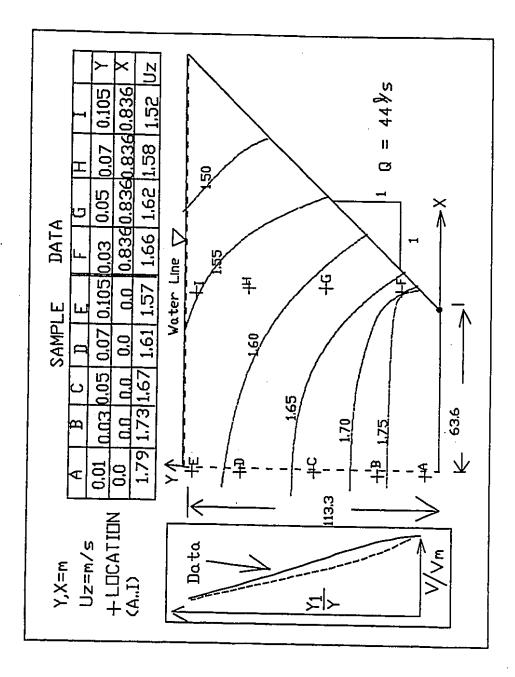


Fig. 4.10(a): Typical Velocity contours at Brink with Pitot tube; Insert:Qualitative comparison of centreline velocity profile with earlier study [Rajarantam(68) ---- Present Study -----] ---- Present Study

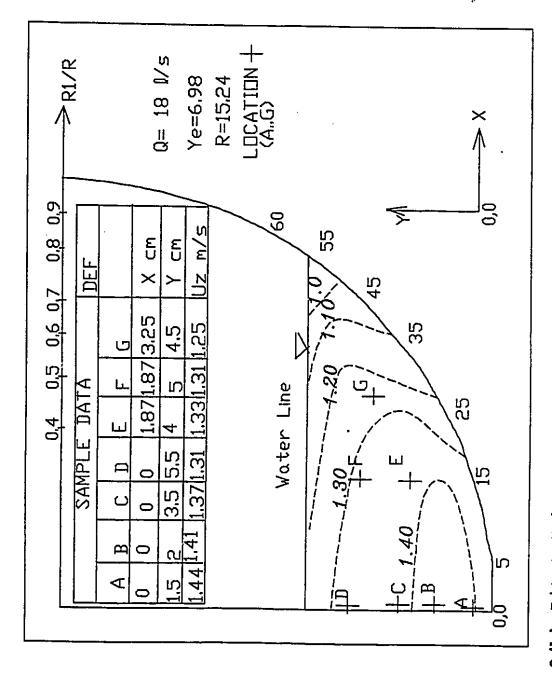


Fig 4.10(b): Pitot Tube Measurements U, in Circular Channel

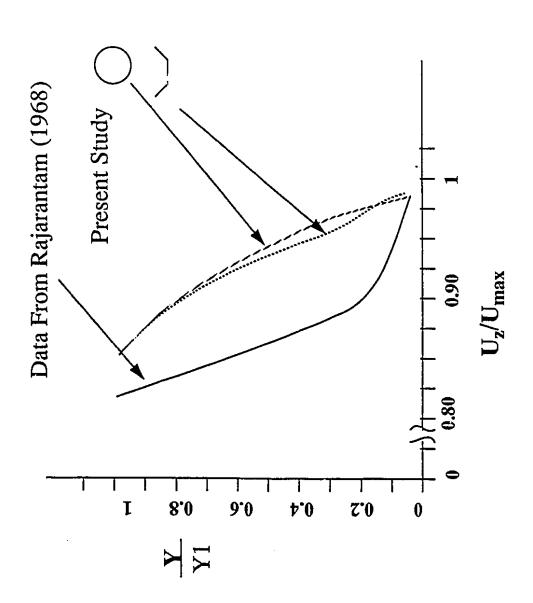
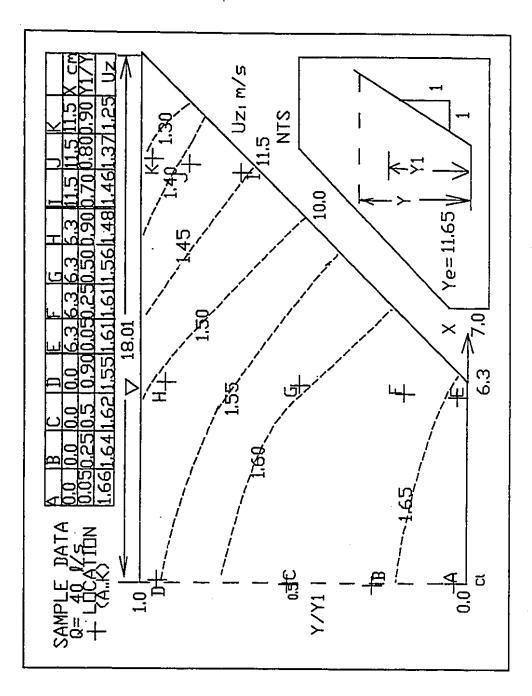


Fig 4.10(c): Comparisons of Velocity Profiles with Past Studies and Different Channel



contours for Laser Measurements; Fig. 4.11(a): Axial velocity (U_z) Insert:Definition Sketch

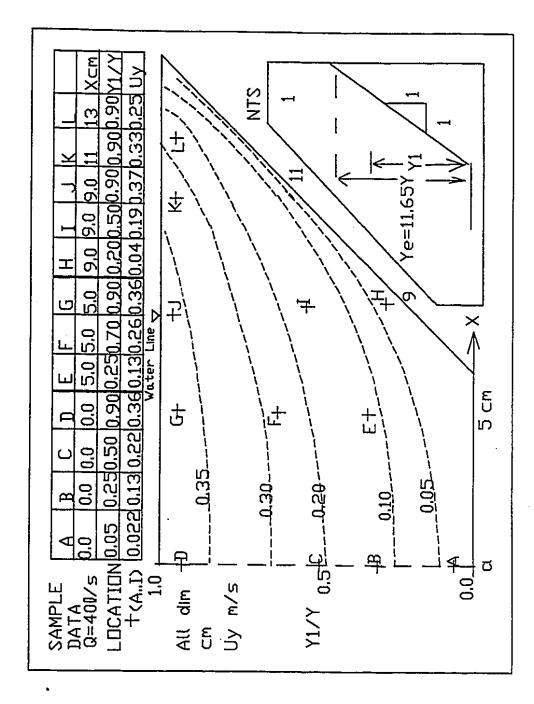


Fig. 4.11(b): Vertical Velocity (U_{γ}) contours for Laser Measurements; Insert: Definition Sketch

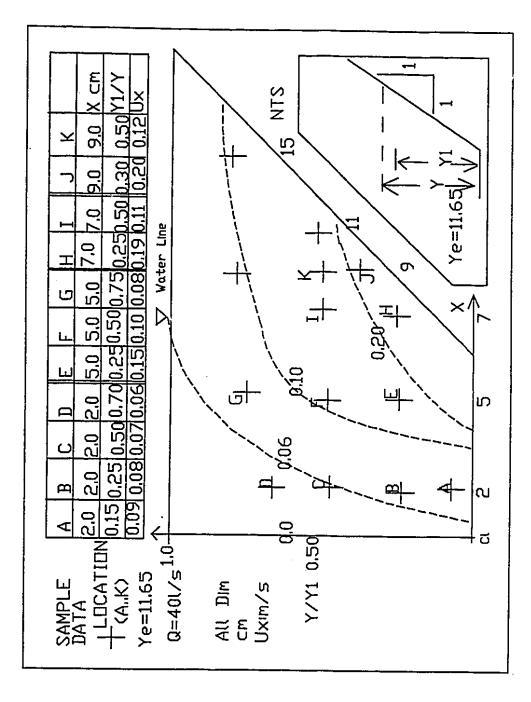


Fig. 4.11(c): Lateral velocity (U_x) contours for Laser Measurements; Insert: Definition Sketch

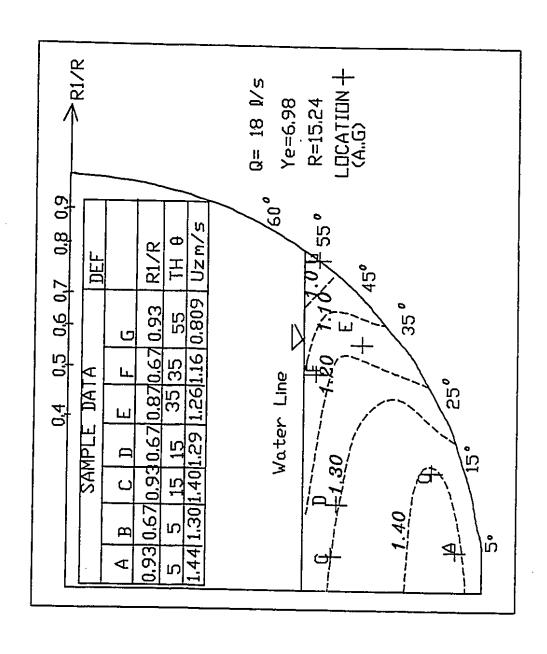


Fig. 4.12(a): Laser Measurements U, in Circular Channel

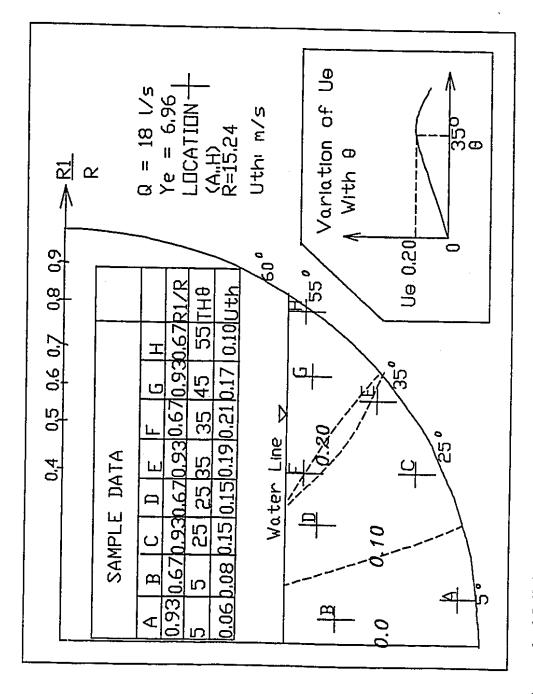


Fig. 4.12(b): Laser Measurements U_{θ} in Circular Channel;insert varitation of U_{θ} with θ

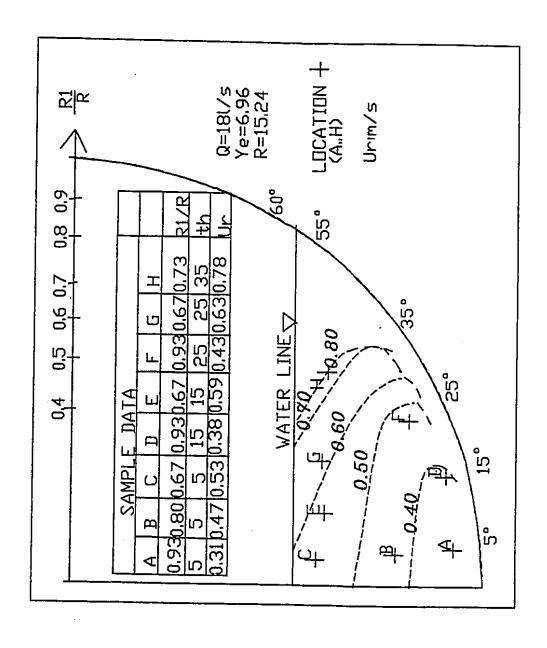


Fig. 4.12(c): Laser Measurements U, in Circular Channel

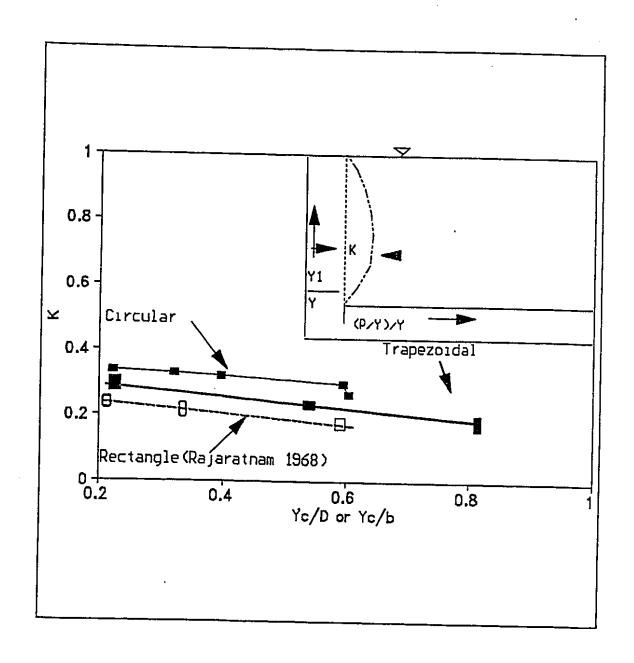


Fig. 4.13: Comparing Maximum (P/ γ)/Y values at end depth with different geometries Circular and Trapezoidal shapes determined in current study

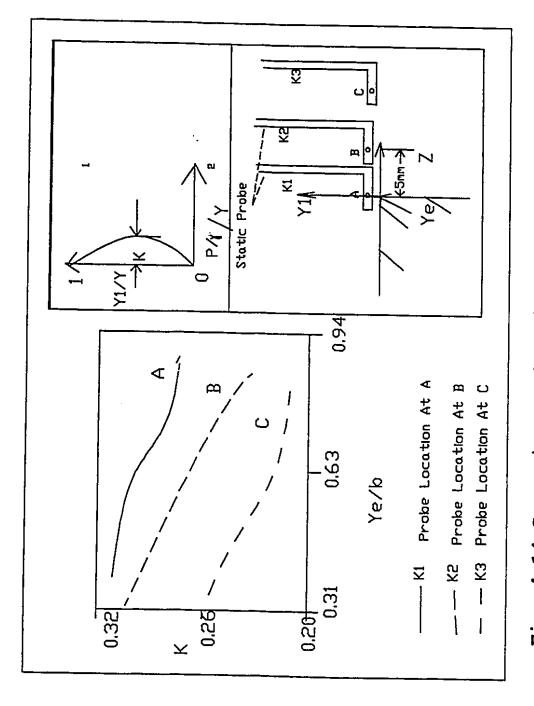


Fig. 4.14 Comparisons of K with Location of Probe; Top insert: Definition of K;Bottom insert: Position of static Probes

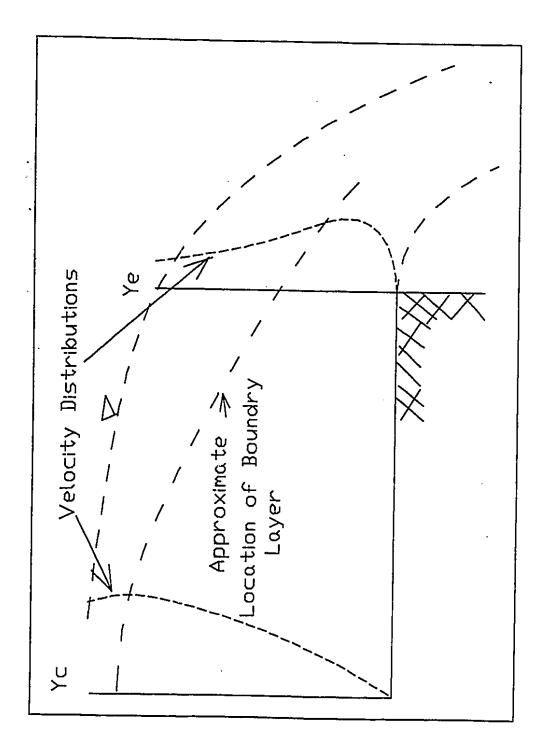


Fig4.15:Comparisons of velocity distributions at Ye and Ye.

Appendix B

Flow chart for computer program to calculate Alpha and Beta coefficients

Input data in the following format
One control Line
of Data Points, # of X points, # of Y Points

Several information lines Xposition Yposition and Velocity

Calculate the Average Velocity
Sum all the Velocity Points, If a velocity point
=0 then do not count it. Divide the sum of the
velocities by the number of data points that did
not have a velocity of 0.

Calculate the Dx and Dy

Dx and Dy are 1/2 the difference between measurement points. Used to calculate the area around each point.

Calculate alpha and beta Coefficients.

```
Program Alphabeta;
Uses Crt:
Var
  p : array[1..100,1..100] of real;
  x : array[1..100] of real;
  y : array[1..100] of real;
  v : array[1..100] of real;
  dy: array[1..100] of real;
  dx: array[1..100] of real;
  DeltaA:array[1..100] of real;
  corner:real;
  Y1: real;
  datapoints : integer;
  vave:real;
  v1:real;
  Xline:integer;
  Yline:integer;
  Xlineb:integer;
  Temp1:integer;
  Temp2:string;
  Vsum, Vtemp, Vtemp1, a1, area1: real;
  Vtemp3, Vtemp2, Vsum1, Beta:real;
  alpha:real;
Procedure Input;
(*read data in from either the screan or a data file*)
var
  m:integer;
  j,i:integer;
begin
  datapoints := 9;
  xline := 3;
  Yline :=3:
  writeln('Input the values of x,y,v below');
  writeln(' x y v');
  for m := 1 to datapoints do
    readln(x[m],Y[m],v[m]);
      for i := 1 to datapoints do
      begin
        for j:=1 to 2 do
        P[i,j] := x[i];
        P[i,j]:=y[i];
   end;
   for i:=1 to datapoints do
     begin
      for j:=1 to 2 do
        write(p[i,j]:8);
        writeln;
     end;
end;
```

```
Procedure Inputfile;
Var
  Filename:string;
  Samplefile:text;
  m, i, j:integer;
function fopened(var thefile: text; Fname:string):boolean;
  assign ( Thefile, fName);
  (*$I-*)
  Reset (thefile);
  (*$I+*)
   -If IOresult = 0 then
     Fopened := True
   else
     Fopened := false;
 end;
Begin
Writeln('Input the name of the input file');
readln(filename);
If Fopened(Samplefile, filename) = true then
 begin
  readln (Samplefile, datapoints, xline, yline);
  for m := 1 to datapoints do
    readln(Samplefile,P[m,1],P[m,2],v[m]);
    close (samplefile);
   end
   else
    writeln('could not open file', filename);
 end;
Procedure Avelocity;
(*calculates average velocity*)
var
 i:integer;
 vtemp:real;
 count, count1: integer;
begin
 v1:=0;
 count1:=0;
  for i := 1 to datapoints do
   begin
     If v[i] = 0 then
      vtemp:=v1
     else
      begin
      count := count1 + 1;
      vtemp:=v1+v[i];
      count1:=count
```

```
end;
      v1:=vtemp;
  end;
  vave:=v1/count1;
 writeln(vave, count1);
end:
Procedure dxdy;
var
    i,j:integer;
    m, m1:integer;
    begin
    Dy[1] := (p[2,2]-P[1,2])/2;
      for i := 2 to Yline do
        Dy[i] := (p[i+1,2]-p[i,2])/2 + (p[i,2]-p[i-1,2])/2;
       If Dy[i] < 0 then
          Dy[i] := (p[i,2]-p[i-1,2])/2;
       Dx[1] := (p[1+Yline, 1]-p[1, 1])/2;
      ml:=Yline;
      for i:= 2 to xline do
       begin
        m := m1+Yline;
                                          D
                                               Х
                                                          i
                                                               1
:= (P[m+1,1]-p[m,1])/2+(p[m,1]-p[m-(Yline+1),1])/2;
        m1:=m;
       End;
        If Dx[i] < 0 then
          Dx[i] := (p[M1,1]-p[M1-(Yline+1),1])/2;
      For i := 1 to Yline do
       Writeln(dy[i]:8);
      For j:= 1 to xline do
        writeln(dx[J]:8);
     end;
Procedure area;
  k,i,k1,j:integer;
begin
   K1 := 0:
   for i := 1 to xline do
     begin
      for j := 1 to Yline do
        begin
         k := k1+1;
         deltaA[k]:=dx[i]*dy[j];
         K1:=k;
        end;
       end;
    for i:= 1 to datapoints do
     writeln(deltaa[i]:3:3,' ',v[i]:3:3);
```

```
end;
Procedure Calc:
var
i:integer;
begin
 a1:=0;
 vtemp3:=0;
 Vtemp:=0;
 for i := 1 to datapoints do
  begin
    If v[i]=0 then deltaa[i] := 0;
    area1:= a1 + deltaa[i];
    al:=areal;
    vtemp1:=v[i]*v[i]*v[i]*deltaa[i];
    Vtemp2:=v[i]*v[i]*deltaa[i];
    vsum:=vtemp+vtemp1;
    vsum1:=vtemp2+vtemp3;
    vtemp3:=vsum1;
    vtemp:=vsum;
   end;
  writeln(al, vave);
  alpha:=vtemp/(a1*vave*vave*vave);
  Beta:=vtemp3/(a1*vave*vave);
  writeln('Alpha =',alpha:3:3,' Beta=',beta:3:3);
 end;
Procedure Output;
var
 i,j:integer;
 output:text;
 outl:string;
  writeln('Input the name of the outputfile');
  readln(out1);
  Assign (output, out1);
  Rewrite (output);
    For i := 1 to Yline do
     Writeln(output,'Dy[',i,']=',dy[i]:8);
   For j:= 1 to xline do
    writeln(output,'Dx[',j,']=',dx[J]:8);
  for i:= 1 to datapoints do
   writeln(output,'delta
                              A[',i,']=',deltaa[i]:3:3,'
','V[',i,']=',v[i]:3:3);
 writeln(output,'Beta=',beta:3:3,' Alpha= ',alpha:3:3);
  Close (output);
end;
```

```
Begin
 clrscr;
 Writeln('Do you want to input data from the screen or
File?');
 Writeln('(1)screen
                        (2)File');
 readln(temp1);
 If temp1 = 1 then
    Input
  else
    begin
     Inputfile;
   end;
 avelocity;
 dxdy;
 area;
 calc;
 output;
 readln;
end.
```

Flow chart for	
Flow chart for calculating the Pressure Coefficients	
Input Data in the Following Format	
Q, Ye, Pressure head	
IISO Formula - 1 1 1	
Use Formulas in Table 2.1 to calculate coefficients	
Output Results	

```
Program pressure coefficient;
uses Crt;
Var
A:array[1..100] of real; {area of cross section}
V:array[1..100] of real; {average velocity}
q:array[1..100] of real;{flow rate}
c:real;{pressure head correction}
alphaprim, Betaprim: array[1..100]
                                       of
                                              real; {Pressure
coefficients chow}
Ye:array[1..100] of real; {end depth}
z:real;
H:array[1..100] of real; {measured pressure head}
K1:array[1..100] of real;{Raja coefficient}
P:array[1..100] of real; {real pressure}
Gamma:real;{specific weight of water}
K:array[1..100] of real; {kellers coefficient}
Xe:array[1..100] of real;
Ko:array[1..100] of real;{Chris coefficient}
I:integer;
Trails:integer; {How many trails need calculating}
Procedure Input;
var
Filename:string;
Sample:text;
Temp:integer;
Function Fopened(Var thefile:text; Fname:string):boolean;
 Begin
   Assign (thefile, fname);
    (*$I-*)
   Reset (thefile);
    (*$I+*)
   If IOresult = 0 then
     Fopened := True
    else
     Fopened := false;
  end:
Procedure Finput;
Var
Filename: string;
samplefile:text;
m:integer;
```

```
Begin
 Writeln('Input the name of the input file');
 Readin (filename);
 If fopened(samplefile,filename) = true then
 Begin
  Readln(samplefile, trails);
  For m := 1 to trails do
  readln(samplefile,q[m],Ye[m],H[m]);
  close (samplefile);
  end
 else
  writeln('could not open file', filename);
end;
Procedure screen;
Var
Filename:string;
samplefile:text;
m:integer;
Begin
  Writeln('Input Name of input file to create');
  Readln (filename);
  Assign (samplefile, filename);
  Rewrite (samplefile);
  Writeln('Input number of trials');
  Readln(trails);
  Writeln(samplefile, trails);
   For m:= 1 to trails do
     begin
      Writeln('inpute Ye,Q,H');
      Readln(Ye[m],q[m],h[m]);
      writeln(samplefile,Ye[m],q[m],h[m]);
     end;
    Close (samplefile);
   end;
Begin
 writeln('Input data by (1) file or by the (2) screen');
 Readln(temp);
  If Temp = 1 then
   Finput;
  If temp = 2 then
   screen;
end;
```

```
Procedure chow;
 begin
  z := (2/3) * Ye[i];
  a[i] := (0.127 + Ye[i]) * ye[i];
  v[i]:=q[i]/a[i];
  c:= v[i]*v[i]/9.81;
  alphaprim[i]:= 1 + (1/q[i]*ye[i])*c*v[i]*a[i];
  betaprim[i]:= 1 + (1/a[i]*z)*c*a[i];
 end;
Procedure Raja;
 Begin
  gamma :=9810;
  p[i]:=h[i]*gamma*a[i];
  k1[i]:=p[i]/(a[i]* 0.5 * ye[i]*gamma);
Procedure keller;
 Begin
  xe[i]:=ye[i]/0.127;
  k[i] := (4/3) * (0.215+0.175*xe[i]) / (1+xe[i]);
 end;
Procedure Chris:
var
 m:integer;
 Yc:real; {critical depth}
 r:real;
 D:real;
 Temp1, temp2, temp3, temp4:real;
 tol:real;
begin
 Q[i] := q[i]/0.02831;
Yc:=2.0927+16.009*q[i]-7.8757*q[i]*q[i]+2.1849*q[i]*q[i]*q[i];
 r:=ye[i]/(0.01*yc);
 d:=0.25;
 temp1:=1/r;
 Temp3:=(d/yc)*(d/yc);
 temp4:=(H[i]/d)*(h[i]/d);
 Ko[i] := 0.01;
  repeat
   temp2:=1.5+0.5*(ko[i]*r*r+temp3*temp4);
    writeln(temp2, temp1);
    tol:=temp1-temp2;
    Ko[i] := 0.01 + ko[i];
    until ( abs(tol)<0.01);
end;
```

```
Procedure output;
 Var
  Output:text;
  outl:string;
  i:integer;
begin
    Writeln('Input the name of the output file');
    readln (out1);
    Assign(output,out1);
    Rewrite (output);
     writeln(output,'Ye alphaprim[i], ,betaprim[i], ,k1,
  ,k,
          ,ko');
     for i := 1 to trails do
      begin
writeln(output,'Ye[',i,']=',Ye[i]:3:3,'
',alphaprim[i]:3:8,' ',betaprim[i]:3:8,' ',k1[i]:3:8,'
',k[i]:3:8,'',k0[i]:3:8);
        writeln(alphaprim[i]:3:8,' ',betaprim[i]:3:8,'
',k1[i]:3:8,' ',k[i]:3:8,' ',k0[i]:3:8);
      end;
    Close (output);
 end;
Begin
 clrscr;
 input;
 For i:= 1 to trails do
  begin
   chow;
   Raja;
   Keller;
      chris; *)
  end;
 output;
 writeln('Press enter to continue');
 readln;
end.
```

Appemdix C

C.0 Using the Momentum Equation with Measured Pressure Heads

C.0.1 Circular

Equations used in the analysis

$$\theta = 2\cos^{-1}\left(\frac{0.3048/2 - H}{0.3048/2}\right)$$
 C.1

$$A=0.3048^2 \frac{\theta-\sin\theta}{8}$$
 C.2

V = Q/A

 $M = \rho QV_c$

 $P = 0.5HA\gamma$

 $P_e = 1/2 (P/\gamma)_{value measured} \gamma A^*$

 A^* = The sub area in the channel around which the $(P/\gamma)_{value}$ value was measured. Refer to Fig C.1 for definition of sub areas used in circular channels when calculating the pressure force with measured values of P/γ .

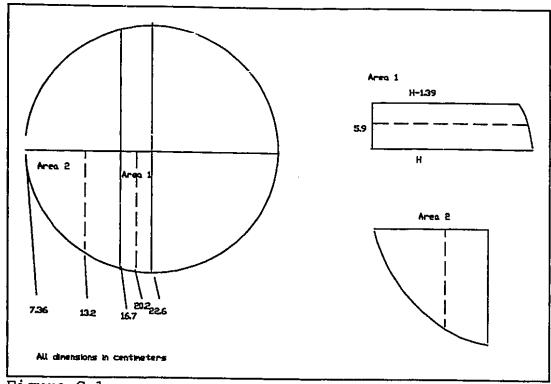


Figure C.1

Areas were calculated by the following method.

$$A1 = 5.9*(h-1.39)+0.5(5.9*1.39)$$

A2=A/2-A1

C.0.2 Trapezoidal Channel

The same method was used for the trapezoidal channel. The only difference was the way the incremental areas were calculated.

The procedure for calculating each incremental area were as follows:

(1) Took a line were vertical pressure head

measurements were performed.

- (2) Formed a rectangle around the line and calculate its area.
- (3) In the Triangle section the shape was a triangle plus rectangle.

The formula for calculating the area of a trapezoidal channel is shown below.

A=(b+y)y

C.1 Calculating Ur in circular channels.

Because the velocities were mearsue in two dimensions, U_r had to be calculated using the $\ U_z$ and $\ U_\theta$ data. To get the radial velocities, the following procedure had to be followed. Refer to Fig C.2 for definitions

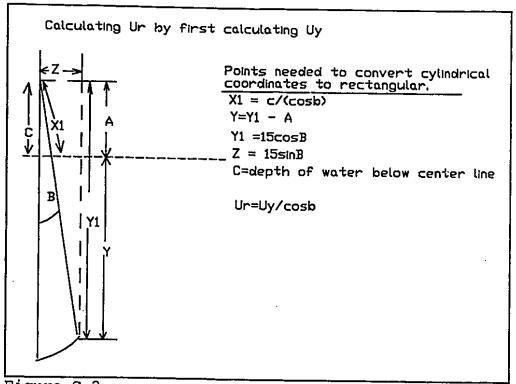


Figure C.2

First in calculating the $\ensuremath{\text{U}}_r$ component, the position of the LDA measureing volume was located.

To accurately calculate the position and thus U_r , a table had to be set up. An example of such a table is shown in Table C.1. This table was generated for a flow rate of 40.71 $1/s(Y_e=11.91)$.

To obtain a value of dy/dz/y, had to first obtain an equation for the slope of the water surface. The slope of the water surface was obtained by measuring the water surface profile and using the least square method to generate an

equation. After an equation had been generated, the first derivative (dy/dz) at the end depth (Y $_{\rm e}$) was taken. Then divided the first dirivative by Y $_{\rm e}$

Table C.1 Calculation Table 1

В	Y1	Z	Y	dy/dz/y
5	14.94	1.3	11.84	0.0428
25	13.6	6.33	10.5	0.0483
35	12.3	8.6	9.2	0.0511
55	8.6	12.28	5.5	0.0589

Refer to Fig C.2 for Definitions

For B= 25 Degrees

X1=3.42 cm (See Figure C.2)

Distance Below Water Surface

Along R coordinate position = 6.58 cm

 $Y = 6.58*\cos 25 = 6.58 \text{ cm}$

Z = 10 * sin 25 = 4.22 cm

Y = 11.19 and dy/dz/Y = 0.0455 by interpolation from Table C.1

Distance from Bottom of channel = 11.19 - 5.96 = 5.23 cm

dy/dz = 0.0455 * 5.23 = 0.238

Using the relationship of $dy/dz = U_y/U_z$

 $U_z = 1.61 \text{ m/s (measured)}$

$$U_y = 1.61 * 0.238 = 0.3804 \text{ m/s}$$

To Calculate U_r , use the following expression $U_r = U_y/\ \text{cos } 25 = 0.419$

For calculating the rest of the $U_{\rm r}$ values used Eq C.3.

$$\frac{\partial U_z}{\partial z} + \frac{1}{r} \frac{\partial U_x R}{\partial R} + \frac{1}{R} \frac{\partial U_{\theta}}{\Theta} = 0$$
 C.3

This equation was the continuity equation. Since U_z and U_θ were measured, the components with those terms could be evaluated. For each radial, the U_r component was evaluated by the following forward difference formula as shown in Eq C.4.

$$U_{r_i}R_i - U_{r_{i-1}}R_{i-1} = K*R*\Delta R$$
 C.4

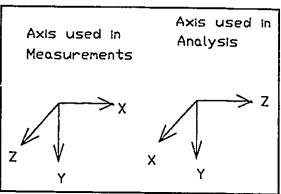
$$K = -\left[\frac{\partial U_z}{\partial z} + \frac{1}{R} \frac{\partial U_{\theta}}{\partial \theta}\right]$$
 C.5

C.2 Check on Irrotationality in Circular Channels

Used two different sets of axis for measurements and to check on irrotationality. Fig. C.3

shows the orientation of the axis.

analysis was done using rectangular coordinates. Circualr coordinates converted to rectangular coordinates with the help of Figure C.3 Opro.



A sample of calculations for irrotationality are presented below. The data is for Ye=11.91 and Q=40.71 1/s. Refer to Table C.2 for data used.

$$\frac{\partial V}{\partial x} = \frac{0.209 - 0}{0.09} = 2.22$$

$$\frac{\partial u}{\partial Y} = \frac{1.47 - 1.65}{0.057 - 0.1147} = 3.13$$

$$\frac{\partial u}{\partial z} = \frac{1.62 - 1.67}{0.0464 - 0.0688} = 2.23$$

0.179316 0.069734 0.209202 0,069734 0.069734 0.069734 9.338708 0.069734 1.73 0.280984 0.154088 1.71 0.326304 0.154088 0.154088 0,154088 0.154088 0.155673 0,163866 0.163866 0.163866 0.172059 0.154973 0.160713 0.510838 | 0.172193 0.149234 0.149234 0.24905 0.29886 1,46 0.373084 (0.385085 1.76 0.235664 0.377063 0.379782 0.294959 0.426051 0.426051 0.45918 0.482139 1.66 1.61 1,67 .63 1,65 1.63 1.62 1.61 4.8 1.47 9. 1.132452 0.958228 0.871117 12.68962 5.913849 5.069013 9.064012 4.224178 10.65129 7.453196 9.831956 6.879873 5.491431 8.026518 6.30655 5.733227 11.46422 10.64535 6.313725 9.007601 8.188728 13.94678 12.95058 9.961986 10.95818 10.87681 11.95438 11.78322 8.193296 9.03565 11.47061 9.012626 7.461675 5.73975 0.07 0.07 0.07 0.07 0.17 0.17 0.17 0.17 0.19 0.2 0.26 202 0.26 0.3 0.21 0.18 0.34 0.21 0.26 0.36 0.419 0.36 0.42 0.52 0.52 9.0 0.65 0.73 0.89 Table C.2 Converting cylidrical coord to Reg coor for Ye = 11.91 (6) 1.74 1.66 1.76 1.67 1.63 1.65 1.63 1.62 1.6 1.53 1.5 1 47 1.48 티인무 13 2 4 11 13 9 F 5 7 13 12 = 9 ខាធានា S श्रध 25 ध्रध 33 ន្តន 35 25 8 88 8 Theta

$$\frac{\partial w}{\partial x} = \frac{0.172 - 0}{0.09} = 1.19$$

$$\frac{\partial w}{\partial Y} = \frac{0.172 - 0.155}{0.1147 - 0.1147} = 0.51$$

$$\frac{\partial V}{\partial z} = \frac{0.32 - 0.29}{0.0507 - 0.0087} = 0.79$$

Several other points at the same flow rate, and at different flow rates were checked for irrotationality

C.3 Calculation of Pressure head Field

For calculating pressure head values at the end depth section , the following procedure was followed.

- (1) A position on the water surface point was used as a reference value since $P/\gamma=0$ and z and $U^2/2g$ were known.
- (2) Used Eq C.6 for calculating the piezometric head for the entire end depth section out side the boundry layer. The end depth sections piezometric head were calculated with the use of Quattro Pro. A sample of the output for a circular channel with Y_e = 6.98 and R=5 degrees is shown in Table C.3 for

Circular channels and Table C.4 for Trapezoidal channels at $Y_e = 11.91$.

$$\left[\frac{P}{\gamma}+z\right]_a + \frac{U_a^2}{2g} = \left[\frac{P}{\gamma}+z\right]_b + \frac{U_b^2}{2g}$$
 C.6

Table C.3 Sample Data for Calculated P/ γ values for Circular channel

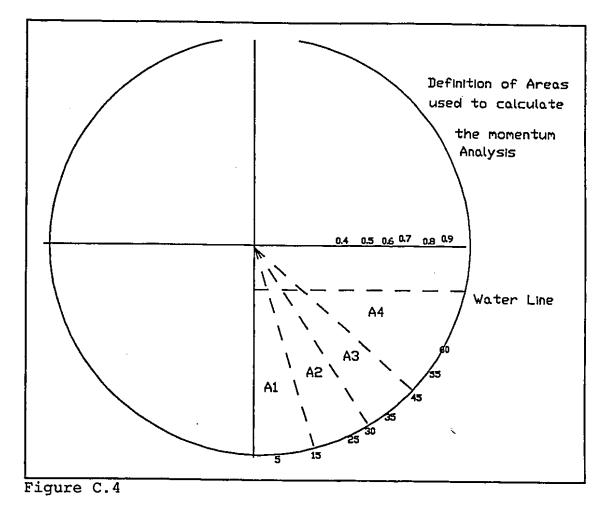
Theta	R	U _z m/s	U _r m/s	Uth	Y m	U²/2g	P/Y+Z	P/γm
5	14	1.44	0.31	0.06	0.010	0.119	0.046	0.036
5	13	1.43	0.40	0.05	0.020	0.120	0.045	0.025
5	12	1.38	0.47	0.06	0.030	0.116	0.049	0.019
5	11	1.31	0.53	0.06	0.040	0.109	0.056	0.016
5	10	1.26	0.54	0.06	0.069	0.096	0.069	0

Table C.4 Sample Calculated P/ γ values for trapezoidal channel

U _z (m/s)	U _y (m/s)	Y (m)	U₂/2g	P/γ(m)
1.81	0.022	0.005	0.165	0.069
1.73	0.10	0.03	0.153	0.056
1.67	0.22	0.056	0.145	0.038
1.60	0.26	0.07	0.135	0.03
1.52	0.35	0.115	0.124	0

C.4 Momentum Analysis With Calculated Pressure Data for Circular Channel.

The same procedure was used in the momentum analysis as was used with measured data. The only difference was in the method for calculating the incremental areas. Refer to Figure C.4 for definitions of areas used. For the particular case in question, used data for the Flow Rate = 40.71 1/s and Ye=11.91 cm.



$$A_1 = 1/2R^2\Theta - (0.031*0.031tan15)*0.5$$

 $A_2=1/2r^2\Theta-(0.031*0.031tan30)*0.5-(0.031*0.031tan15)*0.5$

 $A_3 = 1/2r^2\Theta - (0.031*0.031tan45)*0.5 - (0.031*0.031tan30)*0.5$

$$A_{\theta} = \frac{A_{\theta}}{2} - \sum_{1}^{3} A_{i}$$

When calculating the end depth pressure force, used equations in section C.0. Data in Table C.3 was for calculating the pressure force for Ye = 11.91.

Table C.5 Pressure Force Calculation

A (m ²)	Pave value (m)	P _e (N)	· · · · ·
0.00281	0.035	0.9715	
0.00279	0.027	0.737	
0.00281	0.031	0.86	_
0.0189	0.011	1	

For end depth section

 $P_e = 3.56 \text{ N} \quad M_e = \rho QV\beta = 63.50*1.03 = 65.41N$

 V_{ave} = 1.56 m/s (average velocity from laser measurements)

For critical section, use standard formulas for pressure force and momentum and calculation of area..

$$Y_c = 15.88$$
 cm

$$P_c = 30.74 \text{ N} \quad M_c = 42.40 \text{ N}$$

$$T_c = 73.12$$
 $T_e = 72.52$

C.5 Calculating Uy for Trapezoidal channel.

Followed the same procedure as was used in the circular pipe.

C.6 Checking Irrotaionality for Trapezoidal Channel

Location:Y1/Y=0.5, x=0, z=0

$$\frac{\partial u}{\partial Y} = \frac{1.66 - 1.55}{0.09} = 1.11$$

$$\frac{\partial v}{\partial x} = \frac{0.20 - 0.0}{0.20} = 1$$

Location:Y1/Y=0.5, x=0, z=0

$$\frac{\partial u}{\partial z} = \frac{1.64 - 1.56}{0.64} = 1.25$$

Location:Y1/Y=0.5, x=0.0476, z=0.015-.03

$$\frac{\partial w}{\partial x} = \frac{0.10 - 0.08}{0.015} = 1.35$$

Location:Y1/Y=0.3, x=0.05, z=0

$$\frac{\partial v}{\partial z} = \frac{0.13 - 0.04}{0.09} = 1$$

$$\frac{\partial w}{\partial Y} = \frac{0.15 - 0.08}{0.05825} = 1.2$$

Other points were also checked and irrotationality was confirmed. Continuity was also confirmed with several points. One of those points is shown below.

$$\frac{\partial u}{\partial x} = \frac{1.615 - 1.415}{0.015 - 0.06} = -4.44$$

$$\frac{\partial v}{\partial y} = \frac{0.13 - 0.22}{0.034 - 0.058} = 3.86$$

$$\frac{\partial w}{\partial Y} = \frac{0.10 - 0.08}{0.0526 - 0.0286} = 0.83$$

If the resultants all three equations s are added up, the result is 0.25. This value is close enough to zero to satisfy continuity.

Appendix D

Uncertainty Analysis

Uncertainties in measured variables

Discharge using standard Depth gauge	(ASME)	V-notch	Q ±3%
LDA measurements			$Y \pm 0.1$ mm
Ρ/γ			₩ ±0.5% ±0.5mm

Trapezoidal positioning

X±1mm Y±0.1mm Z±3mm

Circular Measurements

Θ±1 degree r±2mm Z±3mm

Calculated variables

Y/Y1 ([p/ γ +z]-z) from measured P/ γ data ([p/ γ +z]-z) from calculated P/ γ data Ur Uy(trapezoidal channel)	±5% ±2.5% ±5% +5%
	±5%
α β	±2%
Υ	+2%

Sample Calculations

In estimating the error for $U_{\gamma},$ the same procedure would apply for $U_{\rm r}$ since similar procedures were used.

 U_y is a Function of $(U_z, Y, dy/dz)$

The uncertainty in $U_z\gg Y$ or dy/dz so neglect Uncertainty in Y and X with average values are Y± 1% and X±5% By the following equation uncertainty in dy/dz is determined

$$W_x = \sqrt{(\frac{1}{100})^2 + (\frac{5}{100})^2}$$

Wr±5% for dy/dz and $U_y\pm5$ %

Appendix E

Units for all Tables are as follows

- (1) Locations(X,Y,Z) are in cm.(2) Velocities are in m/s
- (3) P/γ and manometer readings are in cm of water (4) End depth elevations (Y1, Ymax) are in cm

Table E.1 Results from laser Readings for Trapezoidal Channel Ye=11.65 and Q=40.71 1/s, Probe at 90 degrees

				
Y	Х	Uz	Ux	Ρ/γ
1.43	2.36	1.571	0.09	7.4
3.11	2.36	1.611	0.08	8.4
4.43	2.36	1.620	0.07	9.2
7.21	2.86	1.584	0.08	10.2
7.21	5.26	1.567	0.10	10.1
4.93	4.76	1.615	0.10	9.1
2.33	.86	1.597	0	
4.63	64	1.580	0	
6.58	14	1.576	0	
3.48	14	1.598	0	
1.99	64	1.600	0	
.33	64	1.61	0	
3.48	4.86	1.646	0.15	7.6
8.49	5.36	1.572	0.08	10.6
Pos2 3.0	cm from Y _e			
8.49	5.36	1.56	0.07	11.4
6.48	4.86	1.556	0.08	10.7
4.94	6.16	1.534	0.08	10.1
3.08	4.56	1.550	0.09	9.4
2.29	5.56	1.531	0.11	9.1
Pos3 6.0	cm from Y _e			
2.29	5.96	1.415	0.09	10.8
5.59	6.26	1.448	0.09	11.4
8.18	5.36	1.513	0.01	12.1
9.03	5.36	1.5	0.08	12.4
9.03	3.86	1.502	0.09	12.4

Table E.1 C'ont (Probe at 45 degrees)

Y	X			<u> </u>
		Uz	Uy*	P/y
6.66	8.76	1.483	0.41	9.8
7.24	6.26	1.562	0.36	10.3
3.98	6.26	1.551	0.34	8.5
1.38	6.86	1.23	0.24	6.7
5.94	8.56	1.477	0.36	9.4
7.33	10.16	1.468	0.39	9.9
9.59	9.86	1.474	0.36	11
9.7	12.76	1.414	0.36	11.4
9.63	13.86	1.366	0.38	11.4
8.59	10.86	1.46	0.37	10.7
7.93	12.86	1.367	0.37	10.4
4.44	7.56	1.515	0.37	8.7
4.88	5.56	1.57	0.37	
4.33	8.36	1.44	0.36	
7.56	8.36	1.474	0.29	
1.83	7.36	1.564	0.36	
4.03	9.16	1.552	0.44	
6.29	9.86	1.47	0.35	
3.27	8.16	1.509	0.36	7.8
5.33	9.36	1.489	0.36	8.6
Pos2				
5.08	5.36	1.513	0.27	10.1
4.05	8.26	1.419	0.3	10.3
7.34	7.66	1.438	0.34	10.9
8.54	12.16	1.416	0.31	11.6
6.99	10.16	1.456	0.33	10.8
Pos 3				
10.43	14.16	1.29	0.24	13.1

Table E.1 Probe at 45 degrees con't

10.87	8.36	1.441	0.26	
		1.441	0.26	12.9
7.23	3.16	1.505	0.25	12.1
4.54	3.76	1.486	0.23	11.4
4.98	5.56	1.43	0.21	11.5

Table E.2 Velocity at the critical section

Y	X	(P/γ+z+V²/2g)	Uz
9.9	4.35	29.4	1.17
7.9	4.35	28.5	1.09
4.9	4.35	27.5	1.00
1.9	4.35	25.9	0.829
0.4	4.35	24.8	0.686
9.9	6.35	29.2	1.155
7.9	6.35	28.3	1.08
4.9	6.35	27.3	0.981
1.9	6.35	25.8	0.816
0.4	6.35	25	0.714
11.9	11.35	29	1.13
9.9	11.35	28.2	1.07
7.9	11.35	27	0.95
4.9	11.35	24.8	0.686

Table E.3 Laser readings For Q=40.71 and Ye=11.91

theta	distance		
•	From	Uz	Uth
	Center (or		
5		1,630	0.070
	14	1.746	0.070
	13	1.743	0.070
	12	1,710	0.070
	11	1.640	0.070
	10	1.610	0.070
25	15	1.580	0.150
	14	1,700	0,170
	13	1.690	0,170
	12	1,675	0,170
	11	1.652	0.170
	10	1,625	0,180
3	5 15	1.484	0.200
	14	1.632	0.190
	13	1.610	0.200
	12	1.610	0.200
	11	1 600	0.200
	10	1,600	0.210
5	<u>5 · 15</u>	1,270	0.250
	14		0.260
	13		0.260
<u> </u>	12	1.480	
	11		
6			
	14		·
	13		
	12	1.470	
7	0 15	1,300	
	14		
	13		
	12		
7	<u>'5 15</u>		
1	14	1.340	0.190

Pos 2			
theta	distance		
	From	1 - 1	Uth
	Center (cm		
5	15	1.370	0.000
	14	1 575	0.000
	13	1,640	0.000
	12	1.620	+++++
	11	1.620	+++++
	10	1.610	+++++
55	15	1.219	0.256
	14	1,430	0,200
	13	1,450	+++++
	12	1,480	+++++
	11	1,470	+++++
Pos3	1		
5	15	1,200	0.000
	14	1,400	0.000
	13	1,490	0.000
	12	1,490	+++++
<u> </u>	11	1,500	++++++
_59	15	1.221	0.090
-	14	1,360	0.050
	13		+++++
	12		++++++
	11		+++++
Furthest	<u> </u>		
	15	1,077	+++++
	14		
	13		
	12		
	11	1	
	10		
			Actual

Readings			•
Ye \	V-notch	Ye	Q(cfs)
31.9	40.71	11.	91 1.41419
Y1	32.37 Y1	12.	38
Y2	32.91 Y2	12.	92
Y3	33.54 Y3	13.	.55

Table E4 Laser Readings for Flow Rate Q=31.74 Vs Ye=9.65

Pos 1			
theta	distance		
9	From	Ux	Uy⁴.
	Center (c	<u> </u>	'
5	15	1 475	0.078
	14	1.620	0.080
	13	1.630	0.074
 	12	1,600	0.060
	11	1.570	0,060
ļ	10	1.550	0.067
25	15	1.480	0.191
	14	1,550	0,158
	13	1.560	0.162
	12	1.540	0.150
	11	1.530	0.160
	10	1.500	0.160
35	15	1,250	0.273
ļ	14	1.500	0.220
	13	1.500	0.220
ļ	12	1.480	0.230
<u> </u>	11	1.460	0.220
ļ	10	1.430	0.230
55	15	1.120	0.270
 	14.5	1.270	0.250
	14	1,340	0.270
 	13.5	1 320	
<u> </u>	13	1.310	0.270
<u> </u>	12	1.300	0.290
	surface	1.290	
60	15	1.200	
	14	1.260	0.200
	13	1.200	0.230
65	15	1,012	0.180
	14	1.081	0.120

^{*}Measured at End Depth Section

Pos 2			
theta	distance		
1	From	Ux	Uy
<u> </u>	Center (c		Γ'
10	. 15	1.330	
<u> </u>	14	1,480	0,000
<u> </u>	13	1,510	0,000
	12	1.520	44444
	11	1,480	+++++
	10	1.480	++++
55	15	1.110	0.078
<u></u>	14.5	1,250	0,086
	14	1.330	0.072
	13.5	1,370	0.080
	13	1.370	
	125	1.340	
	12	1.320	
Pos3			
10	15	0,900	0.000
	14	1,290	0,000
	13	1.340	0.000
	12	1.413	+++++
	11	1.400	+++++
55	15	0.964	0.026
	14.5	1.150	0,000
	14	1 218	0.000
 	13.5	1.270	0.000
	13	1.320	_0.000
Furthest			
<u> </u>	15	0.940	111111
	14	1.142	++++++
	13	1.190	+++++
	12	1.270	++++
	11	1.300	+
	10		+++++

Reading	ne -	Actual				
Ye	ys V-notch	Ye	Olofos			
30	·•		Q(cfs) 1.121217			
Y1	31.14 Y		1.141417			
Y2	31.73 Ya	- 4,00				
Y3	32.55 Y					

Table E.5 Pressure Field Data For Circular Pipes

Flow Rate	Z	Y1	P/Y	Ymax
38.5	Center	0.6	1.9	11.61
		1.6	3	
		2.6	3.1	
		3.6	2.9	
		5.6	2.3	
		8.6	0.9	
	40° Line	4.6	1.4	
·		5.6	1.3	
		6.6	1	
	ļ	7.6	0.8	
		8.6	0.5	
38.3	Center	0.6	2.4	11.11
	<u> </u>	1.6	3	
		2.6	3.3	
		3.6	3.2	
		5.6	2.6	
		8.6	1.2	
	40° Line	4.6	1.4	
		5.6	1.6	
		6.6	1.5	
		7.6	1.3	
		8.6	0.9	

Table E6 sample Monometer Data

Monometer	Reading	Actual	P/y	Y1	Ymax
		Reading			
11	10.4	2.9	1.884	1.016	11.03
12	9.7	2.2	2.2	0	11.03
13	10.4	2.9	1.884	1.016	
14		4.8	1.1932	3.61	
15		-7.5	-15.12	7.62	
21	11.6	4.1	3.084	1.016	11.24
22		3.75	3.75	0	
23	11.6	4.1	3.084	1.016	
24	13	5.5	1.8932	3.61	
25	16.2	8.7	1.08	7.62	
31	13	5.5	4.484	1.016	11.34
32	12.8	5.3	5.3	0	
33	13	5.5	4.484	1.016	
34	14.5	7	3.3932	3.61	
35	16.5	9	1.38	7.62	
41	15	7.5	6.484	1.016	11.57
42	14.7	7.2	7.2	0	
43	15	7.5	6.484	1.016	
44	16.3	8.8	5.1932	3.61	
45	17.2	9.7	2.08	7.62	
51	17.1	9.6	8.584	1.016	11.93
52	17	9.5	9.5	0	
53	17.1	9.6	8.584	1.016	
54	18	10.5	6.8932	3.61	
55	19.2	11.7	4.08	7.62	
61	19.5	12	10.984		
62	19.2	11.7	11.7		
63	19.5	12	10.984		
64	19.8	12.3	8.6932		
65	20.4	12.9	5.28		
72	20.8	13.3	13.3		
75	21	13.5	5.88		
82	21.5	14	14		
<u>85</u>	21.9	14.4	6.78		
92	22	14.5	14.5		
95	22	14.5	6.88		
e1	22.1	14.6	14.6		

Table E.7 Pressure Field Measurements For Trapezoldal Channel

	Z	γ*	V	P/y+z	Y1	Viron	P/y
1.36	4.4	0.4	7.55	0.491	Y1real 10.27176	(p/y+z)r	
		5	1	8.8	0.431	10.2/1/6	1.95
		5.5	1.5	9.7		{	3.2
		6	2	10.4			4.1
		7.5	3.5	11.9		,	4.8
		9.5	5.5	13.5		1	6.3
		11.5	7.5	14.9		1	7.9 9.3
		13	9	15.65			10.05
6.36		4.4	0.4	7.6			10.05
		5	1	9			3.4
		5.5	1.5	9.7			4.1
		6	2	10.5			4.9
	<u> </u>	7.5	3.5	12			6.4
		9.5	5.5	13.5			7.9
		11.5	7.5	14.85			9.25
		13	9	15.7			10.1
8.36		6.5	2.5	9.3			3.7
		7	3	10.5			4.9
		7.5	3.5	11.2			5.6
		8	4	11.9			6.3
		9.5	5.5	13.4			7.8
		11.5	7.5	14.8			9.2
40.00	 	13	9	15.7			10.1
10.36		8.5	4.5	11.1		•	5.5
		9	5	12.2			6.6
	9.5	5.5	12.9			7.3	
		10	6	13.5			7.9
 -		11	7	14.4			8.8
		11.5	7.5	14.8			9.2
	<u> </u>	13	9	15.7			10.1
l							-5. 6

Table E.8 Q=34.32 l/s and Ye=9.67 cm

Mon #	Reading	Actual Reading	Monometer #	Reading	Actual Reading
1	7.8	1.8	31	14	8
2	7.8	1.8	32	14	8
3	7.8	1.8	33	14	8
4	7.8	1.8	34	14	8
5	7.8	1.8	35	14	8
6	7.8	1.8	36	14	8
7			37	14.2	8.2
8	10.4	4.4	38	14.6	8.6
9	11.4	5.4	39	15.4	9.4
10	14.0	8	40	16.6	10.6
11	9.5	3.5	41	16	10
12	9.5	3.5	42		
13	9.5	3.5	43	16	10
14	9.5	3.5	44		
15	9.5	3.5	45	16	10
16	9.6	3.6	46	16	10
17	10.2	4.2	47	16	10
18	11.4	5.4	48	16.8	10
19	12.4	6.4	49	16.8	10.8
20	15.2	9.2	50	17.2	11.2
21	11.6	5.6	51	17.6	11.6
22	11.6	5.6	53	17.6	11.6
23	11.6	5.6	55	17.6	11.6
24	11.6	5.6	56	17.6	11.6
25	11.6	5.6	57	17.6	11.6
26	10.8	4.8	58	17.6	11.6
27	12.0	6	59	17.6	11.6
28	12.8	6.8	60	18	12

Table E.8 Con't

29	13.2	7.2	u1	18.8	12.8
30	16	10	u2	18.8	12.8

