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Automatic Quality of Service Adaptation for Composite Web Services

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A Thesis

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Abstract

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Ming Qiao

Quality of Services (QoS) management has become an important issue for Web services. Indeed, QoS is becoming a crucial and a distinguishing criterion among functionally equivalent Web services. QoS Management consists of two complementary tasks: monitoring and adaptation. Both are very challenging because of the unpredictable and dynamic nature of Web service composition. We are motivated to solve the QoS problem by taking advantage of some characteristics of composite Web services, such as their similarity to traditional workflows.

In this thesis, we propose a broker based architecture that enables dynamic QoS monitoring and adaptation for composite Web services. Our approach consists of dynamically changing the execution paths of composed Web services by instrumenting the BPEL process. A new construct flexPath is introduced for supporting alternate execution paths definition in BPEL. We developed a BPEL compiler allowing automatic instrumentation for BPEL definition files. The BPEL process is deployed using the instrumented definition files in order to interact with the QoS broker during execution. The QoS broker is a key component in our architecture and is responsible of monitoring the QoS and managing the adaptation. We propose a broker that enables runtime monitoring of QoS, prediction of potential QoS violation, and the selection of the best execution path of the process in order to improve QoS when needed.
We developed a prototype to evaluate our proposed architecture. A case study is also presented through an example BPEL process and a number of partner Web services. The performance of the QoS adaptation has been analyzed and the results showed that the QoS of the BPEL process has been considerably adapted and improved comparing to the original one. In addition, we analyzed the major factors that affect the performance of our prototype tool.
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List of Acronyms and Abbreviations

AOP: Aspect-Oriented Programming
BPEL: Business Process Execution Language
BPML: Business Process Modeling Language
CORBA: Common Object Requesting Broker Architecture
DOM: Document Object Model
DTD: Document Type Definition
FTP: File Transfer Protocol
HTTP: Hypertext Transfer Protocol
HTN: Hierarchical Task Network
IIOP: Internet Inter-Orb Protocol
JMS: Java Message Service
OASIS: Organization for the Advancement of Structured Information Standards
OS: Operation System
QOS: Quality of Service
RAM: Random-access memory
RMI: Remote Method Invocation
RPC: Remote Procedure Call
SMTP: Simple Mail Transfer Protocol
SOA: Service-Oriented Architecture
SOAP: Simple Object Access protocol
UDDI: Universal Description, Discovery, and Integration
W3C: World Wide Web Consortium
WS: Web Service
WSCl: Web Services Choreography Interface
WSDL: Web Services Description Language
WSFL: Web Services Flow Language
WWW: World Wide Web
XML: Extensible Markup Language
Chapter 1

Introduction

This chapter presents a brief introduction to the domain, the problem statement, the motivations and the contributions of this thesis.

1.1 Introduction to the Research Domain

The concept of service is now familiar to the computer science community. Thinking in terms of service offers a new point of view for designing computer applications. A rough definition of service would be to provide a “black-box” application that can be invoked by humans and other applications. SOA (Service-Oriented Architecture) defines how services communicate with each other. OASIS (Organization for the Advancement of Structured Information Standards) defines SOA as a paradigm for organizing and utilizing distributed capabilities that may be under the control of different ownership domains [OASIS 2006]. Based on SOA, a service exposes its functionalities to other services through interfaces by using defined protocols. The services are loose-coupled which means the interaction among services is independent to the underlying technologies used by implementing the services such as the operation systems, programming languages, etc.
Among many approaches that can implement the service-oriented architecture, for instance, Jini, CORBA, etc., Web service technology has gained broad academic and industry acceptance. An application can be defined as a Web service which is accessible via standard internet protocols. Web service protocols are defined on top of a common data exchange standard which is XML. These protocols allow the communication among services to be platform independent. More specifically, how to interact with a Web service is defined by its messages and operations rather than its implementation details. This makes achieving the loose-coupling among Web services easier. In recent years, Web service has become a comprehensive solution for helping enterprises to create reusable services.

One of the key aspects of Web services is that a service can be composed of other services. Assembling multiple Web services into a new service is called Web service composition [Srivastava 2003] [Aalst 2003]. The composition can be defined using Web service composition languages. Defining a composition includes providing logics of interactions between the composed service and the Web services that participate in it [Khalaf 2003]. Some composition languages are workflow-based which makes the task of composing Web services similar to defining a workflow.

Since Web services wrap applications into services, the QoS of Web services would be one of the major concerns for service clients. QoS of Web services includes service quality such as latency, availability, timeliness and reliability [Chen 2003]. Service providers face challenges to guarantee the end-to-end QoS for their Web services given
the dynamic and the flexible environments of service execution. Therefore, it is critical for them to have QoS management support to assure the QoS provided to the clients.

1.2 Problem Statement

As mentioned in the previous section, QoS plays an important role for both service providers and requestors. A Web service should not only be manageable from the functionality perspective but also from non-functional aspects perspective. However, QoS for Web services is not managed in a well-structured manner nowadays. There are several aspects that should be included in a successful QoS management architecture. QoS specification, measurement, selection, monitoring, verification, negotiation, and adaptation are among those aspects.

A composite Web service is a special kind of Web service. Besides the issue of having a well-defined QoS management architecture, it is also facing its own QoS challenges because of its composite nature. For instance, figuring out the relationship between the composite QoS and the QoS of participating services is an important question that needs to be addressed.

Among many aspects in the QoS management, QoS adaptation is a topic that has not been studied thoroughly. In the Web service domain, this actually means the building of a Web service, which is QoS-adaptable. The QoS of a Web service constantly changes during run-time due to the dynamic variations of, for example, resource availability, traffic, etc. This kind of fluctuation can make the QoS completely unacceptable.
Therefore a QoS-adaptable Web service is defined as a service that is able to adapt to the QoS variation (e.g. degradation) at run-time. This is exactly the problem we are addressing in this thesis: define an architecture that enables automatic QoS adaptation for Web services. More specifically, we focus on composite Web services.

### 1.3 Goals and Motivations

Existing Web service standards do not support QoS adaptation. A QoS-adaptive Web service is capable of maintaining its QoS at an acceptable level. Without the QoS adaptability, QoS contracts would be meaningless to the clients, especially in Web services’ rapid changing environment.

There are several goals that we want to achieve in this thesis. First, the adaptation should be automatic, which means it should happen without human’s intervention. The procedure of monitoring QoS, making decision of when to trigger the adaptation, and the action of adaptation should all be executed automatically.

Second, we believe that the QoS adaptation should be triggered as soon as the QoS violation is expected to happen at run-time. The point here is the adaptation should not wait until the QoS requirement has already been violated. In other words, our goal is to build a pro-active adaptation technique.

The third goal to achieve is that the QoS adaptation should not stop the composite Web service execution. This is a drawback of some existing adaptation techniques. For example in [Canfora 2005], the service execution has to stop in order to re-plan the composition for improving the QoS. We believe that a good adaptation scheme for Web
services should be able to dynamically improve the QoS of the current running instance without stopping it.

1.4 Thesis Contributions

To solve aforementioned issues, we propose an architecture that enables automatic QoS monitoring and adaptation by dynamically changing the execution paths of composed Web services when necessary. Our main contributions include:

1. A broker-based architecture supporting QoS-adaptable composite Web service
2. A QoS broker design which is capable of interpreting the schema of composite Web services, monitoring the QoS, predicting the potential QoS violation, and triggering QoS adaptation.
3. A new activity for BPEL called "flexPath" which enables the definition of alternate execution path in BPEL. Note that BPEL is a language for defining Web services composition that will be introduced in the next chapter.
4. A mechanism for automatically instrumenting BPEL processes for the purpose of adaptation.

1.5 Organization of the Thesis

The second chapter gives an overview of Web services, the QoS issue for Web services, and the QoS adaptation in particular. We introduce the Web service paradigm in general at the beginning. Then, we discuss in detail Web services composition. We discuss the
issue of managing QoS for Web services in the second half. Similarly, we discuss the issue for Web services in general first before moving to the case of composite Web services. Finally, we discuss the problem of QoS adaptation.

The third chapter studies the related work in the area of QoS adaptation. We discuss a broker-based approach to manage QoS for Web services, on which our proposed architecture is based. Then, we introduce approaches of creating flexible workflows. We introduce and discuss related work on QoS adaptation, including approaches for general Web services and composite Web services. We also discuss a broker-based WS-QoS management architecture which provides a foundation to our work. A summary of the state-of-the-art in this area concludes this chapter.

The fourth chapter describes our proposed architecture in detail. We introduce the main components of the architecture and explain their respective roles. We also describe the procedure of the QoS adaptation for a typical composite Web service execution.

The fifth chapter introduces our proposed approach of BPEL instrumentation. The mechanism of automatic instrumentation is described in this chapter as well as how to instrument different parts of a BPEL description.

The sixth chapter describes our proposed QoS broker design. We explain the design of the three main modules in the QoS broker: the Topology Interpreter, the QoS Monitor, and the QoS Adaptor. For each module: the detailed design of the main features, the interface and interaction with other components are introduced and discussed.
The prototype implementation, a case study, and the analysis are provided in the seventh chapter. This chapter discusses the implementation architecture of the prototype tool and explains in detail a case study. Details on the test environment, some performance measurements and analysis are also provided.

The last chapter concludes the thesis by summarizing the contributions and pointing out possible future work.
Chapter 2

Web Services: Composition, Adaptation and QoS

This chapter contains three sections. Section 1 discusses the Web service paradigm including Web service composition. Section 2 studies the QoS issue for Web services. Section 3 extends the discussion into one of the most important QoS aspects, i.e. QoS adaptation.

2.1 Web Services

Web service technology allows different applications to be exposed as services via the network and interact with each other through standardized XML-based techniques. In this section, we will answer the following questions: What is Web service? What is the architecture of Web services? What are the major standards of Web services and what are their roles respectively?

2.1.1 Definition and Architecture of Web Services

Based on the definition by W3C [W3C 2004], a Web service is a software system designed to support interoperable machine-to-machine interaction over a network. It has an interface described in a machine-processable format, for instance WSDL (Web Services Description Language). Other systems interact with the Web service in a manner prescribed by its description using SOAP (Simple Object Access protocol) messages,
typically conveyed using HTTP with an XML serialization in conjunction with other Web-related standards.

The concept of Web service is always being confused with Web applications. The main difference between them is: Web services are designed for machine-use, while Web applications, such as a JavaScript application which can be accessed from a Web page, are mainly designed for human-use. Due to the fact that Web services are platform-independent and can be requested and invoked directly by other applications, they are generally more modular, self-aware, reusable, and manageable than Web applications [Papazoglou 2004].

Figure 2.1 illustrates the Web service architecture. There are three main components in this architecture: service registry which acts as a searchable directory for published service interfaces, service provider who creates, implements, and announces the service, and service requestor who uses the service.

![Figure 2.1: Web Service Architectural Model](image)
In this architecture, the service providers describe the interfaces and properties of their Web services by using WSDL. They then register the services into service registries using UDDI (Universal Description, Discovery, and Integration). Service registries act as Yellow Pages allowing the service requestors to discover services they want. After finding a service, the requestor obtains the necessary information to access the service such as the address of the service’s WSDL file from the registry. Then, the requestors can invoke the services using the SOAP in either asynchronous messaging or RPC (Remote Procedure Call) mode.

As illustrated in Figure 2.1, the operations among the three roles in the Web service architecture are defined as publish, find, and bind:

1. Publish: This operation consists of two parts: defining the service interface through WSDL by the service provider, and registering the service into service registry through UDDI.
2. Find: The service requestor uses this operation to find the service. It contains discovering the service from UDDI, and finding the location for service invocation.
3. Bind: The actual run-time service invocation happens on the bind operation. In this operation, the service requestor initiates the request to the service provider, reaches an agreement with the provider about service running, and invokes the service.

2.1.2 Web Service Technology Stacks

Web services involve a lot of technologies. W3C illustrates the Web service technology stacks as in Figure 2.2 in its working group note [W3C 2004]. A number of technologies
from different layers have become key Web service standards which define how to design, deploy, and run Web services.

Figure 2.2: Web Service Technology Stacks (taken from [W3C 2004])

Figure 2.2 provides a bottom-up view for Web service technologies. Starting from the bottom layer, many ubiquitous network protocols can be used as the communication protocols to carry Web services. This is one of the most important advantages of Web services that they are able to be accessed over different networks. From this layer up, a few of XML-based standards including SOAP, WSDL, and UDDI define the Web service messaging, description, and discovery. They are now well-accepted as core standards of Web services. The highest layer consists of standards that define the logics and strategies of business processes, such as languages for Web service compositions. In this section, we discuss the core standards in detail: SOAP, WSDL, and UDDI.
2.1.2.1 SOAP: Simple Object Access Protocol

W3C defines SOAP as a technology that provides a standard, extensible, composable framework for packaging and exchanging XML messages. It also provides a convenient mechanism for referencing capabilities (typically by use of headers). [W3C 2004]

As illustrated in Figure 2.2, SOAP is a communication protocol defined on top of the network layer. It defines how to transfer XML-formatted messages by using a request/response communication paradigm. A SOAP message usually contains an envelope, a header and a body. SOAP messages can be carried by a variety of network protocols: such as HTTP, SMTP, FTP, RMI/IIOP, or a proprietary messaging protocol.

2.1.2.2 WSDL: Web Services Description Language

WSDL is an XML-based language to describe Web services. It describes a Web service as a collection of endpoints/ports operating on messages containing either document-oriented or procedure-oriented information based on standard messaging protocol such as SOAP. An input message and/or an output can be defined for each operation. WSDL separate the abstract definitions of operations and messages from their concrete use which include the network protocols they bound and message formats.

2.1.2.3 UDDI: Universal Description, Discovery, and Integration

UDDI is a specification for Web service discovery. It describes a registry of Web services and programmatic interfaces for publishing, retrieving, and managing information about services described therein. The specification defines services that
support the description and discovery of (1) businesses, organizations, and other Web services providers, (2) the Web services they make available, and (3) the technical interfaces which may be used to access and manage those services. [OASIS 2004]

2.1.3 Web Service Composition and BPEL

One of the main advantages of Web services is the possibility of composing them for creating new ones. The logic of a composite Web service is implemented by individual services which participate in the composition. This is similar to the traditional workflow which is defined as an aggregation of activities [Dustdar 2005].

Defining Web service composition is still an open research area where a large number of approaches have been proposed. Many of composition approaches use programming languages to link Web services and define the transition among them. [Milanovic 2004] points out that a composition approach should meet several requirements including nonfunctional properties, connectivity, correctness, scalability and automaticity:

1. Nonfunctional properties: Nonfunctional properties such as QoS should be addressed in the composition description since the composing services are running in a highly dynamic distributed environment. Unfortunately, QoS specifications have not been integrated into most of today’s approaches. When composing a service, these approaches only focus on how to meet the user’s functional requirement.

2. Connectivity: A composition links multiple Web services together. These Web services can be running in different platforms or connected through different network technologies. Connectivity refers to the messaging and interfacing among the
composed service and partner services. A good composition approach should provide seamless message exchanging among different parties in the composition.

3. Correctness: The correctness means the truthfulness of the composed service’s specifications and properties, such as security or dependability.

4. Scalability: The composition framework should scale with the number of the participating Web services in the composition.

5. Automaticity: The composition should be done with minimum human intervention. It is a complex topic about how to achieve high level of automaticity on service composition. Most existing mechanisms such as BPEL are still considered as manual composition.

Existing well-known Web service composition languages include BPEL, WSFL, XLANG, WSCI, and BPML. WSFL (Web Service Flow Language) which is proposed by IBM and XLANG which is proposed by Microsoft are considered as the first generation of the composition languages. They are similar in terms of composition functionality, but they are not compatible. Researchers from IBM, Microsoft, BEA Systems, SAP, and Siebel Systems then developed the second generation composition language called BPEL which stands for Web Services Business Process Execution Language. This language combines WSFL, XLANG and BEA Systems’ WSCI (Web Services Choreography Interface). It is now seen as the de-facto standard of the composition language.

BPEL is an XML language that specifies Web service based business process behavior. Multiple Web services can be composed into a BPEL process which can be deployed as a new Web service. The BPEL process is defined to achieve a certain task by interacting
with different Web services. These Web services are called partners in BPEL. The designer needs to define interactions between the process Web service and each partner Web service. In BPEL, this interaction is modeled as partnerLinkTypes. A partnerLinkType normally defines the roles of two partners and the relationship between them. Note that the BPEL process itself is considered as a partner as well.

BPEL can define two different types of processes: abstract process and executable process. An abstract process is only a conceptual definition of a process which is not meant to be executed. It is not used much so far. In this thesis, when talking about BPEL processes we always refer to executable processes.

The BPEL process description is defined in an XML file which conforms to the BPEL standard. The latest BPEL standard is WS-BPEL 2.0 standardized by OASIS at 2007 which is defined in [OASIS 2007]. This standard specifies a process schema as a set of activities connected by links. BPEL defines two types of activities: structured activities and basic activities.

1. Structured Activities:
   - Flow: defines parallel and control dependencies processing
   - ForEach: defines processing multiple branches
   - If: defines conditional behavior
   - Pick: defines selective event processing
   - RepeatUntil: defines repetitive execution
   - Sequence: defines sequence processing
   - While: defines repetitive execution
2. Basic Activities:

- Assign: updating variables and partner links
- Empty: doing nothing
- Exit: immediately ending a process
- ExtensionActivity: adding new activity types
- Invoke: invoking Web service operations
- Receive: providing Web service operations
- Reply: providing Web service operations
- Throw: signaling internal faults
- Rethrow: propagating faults
- Wait: delayed execution

A typical BPEL process life cycle consists of three phases: design phase, deployment phase and execution phase. The designer defines the process schema in the BPEL definition file, the process interface in the WSDL file, and optionally the deployment detail in deployment description files at the design phase. These files are then deployed on the service provider’s Web server. At runtime phase, a process instance is created when a user invokes the process. An instance is terminated when the execution is completed.

Let us look at an example of BPEL process now. Figure 2.3 shows a loan approval process which is a sample included in ActiveBPEL V3.1 [ActiveBPEL]. This process receives a customer’s loan request for a certain amount. It returns the result of whether the loan is approved to the customer.
In this example, two partner Web services participate in the BPEL process: a LoanAssessor service, and a LoanApprover service. The LoanAssessor takes the customer’s credit information as input, and returns the risk of this customer as output. The LoanApprover receives the customer’s credit information and reply with the result of loan approval.

The business logic is defined as follows: The process is started by receiving the customer’s request which includes his credit information. If the requested amount is more than or equal to 10,000 dollars, the request is sent to the LoanApprover service. If it is less than 10,000 dollars, the request is sent to the LoanAssessor service. In this case, the
LoanAssessor evaluates the risk of this customer and return the result to the BPEL process. If the risk is low, the loan is approved and the final result is sent back to the customer. Otherwise, the request is sent further to the LoanApprover. The result of the LoanApprover is considered as the final result which is then replied to the customer. Figure 2.4 gives a snippet of the BPEL definition of this process.

```xml
<bpel:invoke inputVariable="request" name=InvokeLoanAssessor operation="check" outputVariable="risk" partnerLink="assessor" portType="Ins:riskAssessmentPT">
  <bpel:targets>
    <bpel:target linkName="receive-to-assess"/>
  </bpel:targets>
  <bpel:sources>
    <bpel:source linkName="assess-to-approve">
      $risk.level !='low'
    </bpel:source>
    <bpel:source linkName="assess-to-setMessage">
      $risk.level = 'low'
    </bpel:source>
  </bpel:sources>
</bpel:invoke>
```

Figure 2.4: Invoking the LoanAssesor Service in the Sample BPEL Process

2.2 QoS for Web Services

The need for QoS support for Web services is driven by two demands [Tian 2004]: From the service requestor's perspective, they expect to experience good service performance, such as fast response time, low cost, etc. A service with poor QoS is always unacceptable even if it satisfies user's functional requirement. From the service provider's perspective, offering QoS-aware Web services is able to attract more customers and therefore gaining more profit. It is an important differentiator for providing a better service compared to the competitors. For example, they can provide the same service in different quality levels to
meet different level of demands from customers. For services which are demanding on some QoS dimensions, QoS guarantees can be offered to the customers. For instance, IP phone service requires the latency to be less than a certain level. To provide good QoS, service provides normally need to find an optimal relation between user satisfaction and resource utilization.

Many researchers tend to believe that the main issue of Web service QoS at this moment is the QoS specification and management. QoS specification is the issue of defining the QoS parameters for Web services, such as response time, cost, etc. QoS management is a generic term which consists of different management functions such as QoS monitoring, adaptation, etc.

2.2.1 QoS Specifications

QoS can be measured from different dimensions. A QoS parameter is a property of the service in a given dimension which is observed by the Web service users [Menasce 2002]. Defining the QoS parameters is fundamental for designing QoS-aware Web services. It allows the user to specify their QoS requirement, and evaluate the service’s QoS performance. This section describes a number of important QoS parameters of Web services.

1. **Response Time**: It is the time a Web service takes to react to a given request. From the user’s perspective, response time can be measured from the moment when the service request is sent until the moment when the response is received. Normally, faster response time is considered as better.
2. **Availability:** It is the proportion of time that a Web service is in usable state. Availability is usually measured for a random observation period. It is often calculated as the ratio of the up time of a service to the total observation period. Higher availability indicates higher degree of operability of a service which is usually considered as better.

3. **Throughput:** Throughput is the average rate of service requests that are successfully handled. Due to the limitation on resources, higher throughput always causes longer response time [Kalepu 2003]. It is the service provider’s task to balance between these two QoS dimensions.

4. **Reliability:** Reliability is the probability that a Web service handles its requests as required within a maximum period of time [Kalepu 2003].

5. **Security:** Security is to measure the degree of safety that a Web service can provide. It could contain many safety-related properties, such as authentication mechanisms, confidentiality, data integrity, protection from vicious attacks, etc. [Menasce 2002].

6. **Cost:** It is the price that a user needs to pay for using a Web service. Normally, users expect lower cost. However, providing high quality of services always requires higher cost from service providers. A good provider should try to offer their services with low cost without sacrificing too much on other QoS dimensions.

### 2.2.2 Managing QoS for Web Services

QoS-enabled Web Services provisioning is achieved through a number of phases, each of which is an important function of QoS management [Serhani 2004]:

1. **QoS specification:** QoS specification defines dimensions of quality that the users are
interested for a certain Web service. It is the foundation of QoS management system. Normally, the user can pay attention to multiple QoS parameters at the same time. Modeling each of them and finding out their relationship should be done prior to managing the QoS for a service. The user can specify an overall QoS requirement before invoking the service. The QoS management system should be able to break down this requirement for each individual QoS parameters.

2. **QoS measurement:** QoS measurement defines algorithms and procedures to measure a QoS parameter at run-time. Choosing a method to measure a QoS parameter depends on its characteristics. It is an important step to be executed when verifying or monitoring the QoS.

3. **QoS selection:** The service requestor should be able to select the service from different candidates based on QoS requirement. In this case, the user’s requirement needs to be mapped to service provider’s QoS model. Then the selection is often modeled as a multi-criteria decision task [Serhani 2004]. For a composite Web service, QoS selection can be also referred to the task that planning a service composition for a certain QoS goal.

4. **QoS negotiation:** It is the phase when the service requestor and the service provider try to reach a QoS agreement. It could happen before the requestor bind to the service or after the agreement is violated during the execution. It is a challenge for both parties to be able to negotiate without human’s intervention. Normally, the negotiation is guided by pre-defined policies.

5. **QoS monitoring:** The run-time QoS should be monitored regularly. The service provider need to keep track of the actual QoS in order to decide whether the QoS
adaptation is required, and record the overall QoS performance after the execution is done. For each individual QoS parameter, appropriate method, frequency, and locations should be chosen for monitoring.

6. **QoS adaptation**: QoS adaptation is to maintain the run-time QoS as guaranteed in the agreement. Normally it involves the action to improve a degraded QoS. In some cases, the service provider might want to decrease the QoS in order to free some resources. QoS adaptation is initiated by comparing the actual QoS with a threshold. It will be further discussed later in this chapter.

### 2.2.3 QoS of Composite Web Services

The QoS of a composite Web service can be modeled as an aggregation of QoS of each individual partner services [Menasce 2004]. Understanding the relationship between the global QoS and QoS of participating services can help to achieve higher degree of flexibility when managing the QoS for composite services. For example, the QoS of composition might be able to be altered by changing the composition logic. In order to study this relationship, we first need to understand service composition patterns.

[Jaeger 2004] introduces seven patterns for Web service composition based on the workflow patterns in the workflow management. Each of these patterns represents a basic structural element of composition, such as a sequence, a loop, or a parallel execution. The logic of a composition can therefore be modeled as a single or a combination of multiple patterns. Figure 2.3 is taken from [Jaeger 2004] to illustrate these seven patterns.
CP1 is a simple sequential pattern. CP2 is a loop pattern where the service(s) execution is repeated for certain times. CP3 to CP7 are five parallel patterns. CP3 is XOR split followed by a XOR join. CP4 is AND split followed by an AND join. CP5 is AND split followed by an m-out-of-n join. CP6 is OR split followed by OR join, while CP7 is OR split followed by an m-out-of-n join. Understanding composition patterns can help us abstract the composition logic, especially when using workflow-based language such as BPEL to define the composition.

Since a composition can always be modeled by these patterns, studying the aggregation of QoS of for each pattern allow us to model the QoS of the composition. A number of works [Jaeger 2004] [Cardoso 2002] [Menasce 2004] [Yu 2005] have been done to
model the aggregation QoS for different QoS parameters, such as response time, availability, cost, etc. based on composition patterns.

2.3 QoS Adaptation

In a service-oriented environment, a QoS-adaptive service is one which is able to adapt itself to the change in QoS. The term QoS-adaptive should not be confused with QoS-aware. A QoS-aware service is one that can provide different levels of QoS to cope with the change in the service execution environment. However, QoS-adaptive means maintaining the initial QoS agreement if possible. When the agreement has been violated or is to be violated, QoS adaptation is triggered. There are a few crucial aspects required to be studied when designing an adaptation scheme:

1. Who should initiate the QoS adaptation? In most cases, QoS adaptation is triggered by the service provider who is responsible for maintaining the service agreement. However, the client can trigger the adaptation as well under certain business requirements.

2. What is the level of automation of QoS adaptation? Ideally, the adaptation can be triggered and maintained without human’s intervention. However, it is a difficult goal to achieve when dealing with highly flexible and autonomous Web services. That is why a lot of existing adaptation schemes still require partially or fully attention from human.

3. Which QoS parameters are considered for adaptation? When multiple QoS parameters are specified for a service, either part of them or all of them can be specified as the targets of adaptation. In this case, multiple QoS parameters construct
a multi-dimension space which represents the scope of overall QoS. This space can be
divides as two different areas: accepted QoS, and un-accepted QoS. The goal of
adaptation is to try to keep the overall QoS in the area of accepted QoS.

4. What are the conditions to trigger the adaptation? The conditions are normally
boundary values of QoS. It could be thresholds of minimum values or maximum
values. Again for multiple QoS parameters, these values that represent the overall
QoS should be mapped to each individual QoS dimension.

5. When should the adaptation be triggered? Obviously, if the overall QoS degrades
below the threshold, the adaptation should be triggered immediately. However, a pro-
active scheme can be implemented so that the adaptation can be triggered in advance
to prevent the QoS become un-acceptable. In this case, the threshold is usually still
acceptable QoS value. Note that in some cases the QoS adaptation needs to be
triggered as well when the QoS “outperforms”. In this thesis, we call the QoS is
degraded either it is becoming too bad or too good.

6. What is the QoS goal to achieve for a given adaptation? A goal should be set as a
condition to terminate the adaptation in order to minimize the waste of resources.
Theoretically, the adaptation should not bring the QoS beyond this goal.

7. What method is used to achieve the adaptation goal? Any mechanism that can alter
the QoS can be chosen for adaptation. For example, load balancing can be used at a
server to improve the throughput of a video playback service.
2.4 Summary

In this chapter, we introduced the necessary background knowledge for our research. We explained the concept of Web services, the Web service architecture, and the main technologies of Web services. We discussed the Web service composition and the existing composition languages. We also looked into BPEL in detail.

Next, we studied the QoS issue of Web services. We discussed a few of most important QoS parameters of Web services. Then, we discussed the QoS management for Web services, and the involved activities such as QoS monitoring, adaptation, etc. As a special case of Web service, QoS for composite Web services was studied at the end of this section. We studied different composition patterns and their aggregation QoS.

In the last section, we discussed QoS adaptation by breaking it down to a number of sub-tasks. In the next chapter, the related work of QoS adaptation for Web services will be reviewed.
Chapter 3

State-of-the-Art in QoS Adaptation for Web Services

A lot of work has been done for QoS adaptation in networking. Several approaches have been proposed for adapting QoS at network or middleware layers [Nahrstedt 2001]. Existing solutions include task scheduling, network flow control, resource management, etc. Resource management consists of methods, for instance, bandwidth allocation on Web servers, power management, etc. There are also other approaches that focus on QoS adaptation on certain application domains [Nahrstedt 2001]. For example, adaptive media coding and compression schemes can be used to create QoS-adaptive video applications. Supporting QoS adaptation at middleware layer has become a hot topic in recent years. In such cases, managing QoS requirement and adaptation polices can be easily separated from applications’ functionality implementation [Mujumdar 2005].

Supporting QoS adaptation for Web services is still immature as Web service is a relatively new area. In this chapter, we discuss the related work in the area of Web services first. Given the similarity between Web service composition and traditional workflow management, we discuss how the problem is proposed to be solved for workflow before we move on to Web service composition. In the third section, we review four approaches proposed for composite Web services. Finally, we look into an important work which is a broker-based solution for QoS management for Web services.
3.1 QoS-adaptive Web services

There are three types of techniques to support QoS adaptation for Web services in the literature: Web service replication, Web service relocation, and dynamic Web service invocation. All these approaches are generic solutions for Web services. For example, they treat different types of Web services as the same, either is a composite one or a basic one.

3.1.1 Web Service Replication

The basic idea of Web service replication is generating a number of replicas for a given Web service so that the service requestor can choose different replicas to bind according to the execution environment change. Existing approaches include [Keidl 2003] [Silva 2004] [Zegura 2000].

![Diagram of Web Service Replication Using a Gateway](image)

Figure 3.1: Web Service Replication Using a Gateway

There are two different patterns to deploy the Web service when using service replication. Figure 3.1 illustrates the pattern that makes use of a gateway Web service. Instead of bind
to the service directly, the service requestor binds to the gateway. The gateway is responsible for dispatching the requests to different replicas.

Another deployment pattern is shown in Figure 3.2. Instead of using a gateway service to select the replicas, a service selector is implemented at the service invocation layer of the client software. It decides which replica to bind based on different policies and directly binds to it. [Silva 2004] is an example that utilizes this pattern.

At the execution time, the service requestor can choose more than one replica to bind at the same time. In this case, load balancing are normally required to distribute the traffic to multiple replicas.

Replicas can be either offered by the service provider or found through UDDI. If provided by the service provider, replicas are just service instances which are duplicated from the original service and distributed to different hosts. Replicas can also be found through UDDI for a given tModel. At run time, the service user can query a registry to find out all the service instances (replicas) against a certain tModel.
The selection of replicas is another important issue of service replication. It is often modeled as a selecting the best set of replicas for binding. If QoS of a replica degrades, it is de-selected and a new set of replicas is re-selected.

Most of the existing approaches of service replication focus on developing algorithms for replica selection, replica load-balancing mechanisms, etc. They are normally motivated by improving the fault-tolerant ability of Web services. The adaptation is triggered by service faults. However, we believe that the adaptation should happen not only in the case of invocation failure, but also when the QoS will be potentially violated.

3.1.2 Web Service Relocation

Web service relocation is a method to transport a service instance from one host to another one (location) at run time without the service requestor’s awareness. Similar to the service replication, the purpose of this technique normally is to improve the ability of fault tolerance of the Web services. The service is relocated as soon as the current host is detected in fault status which is illustrated by Figure 3.3.
Fluid [Pratistha 2004] is a framework supporting Web service relocation. It allows Web services to be nomadic so that they can transport to different destinations for adapting to the changes in the surrounding environment. It is implemented by using mobile agent technology. A proxy is built between the service provider and requestor. The requestor can retrieve the location information from the proxy. [Pratistha 2004] points out the main requirements of service relocation: reactivity, transportability, and adaptability.

1. Reactivity: is the ability of a Web service to trigger the relocation automatically when sensing the need from surrounding changes.

2. Transportability: is the ability that allows a Web service to be relocated to a different host.

3. Adaptability: allows a service to detect its context such as available resources of the destination host, and adapt itself by reconfigure its structure to this context.

Both Web service relocation and replication alter the QoS by redeploy different resources of the service provider for the running services. Some future improvements that researchers are currently working on include improving the performance, scalability, and extending to different type of Web services.

3.1.3 Dynamic Web Service Invocation

Based on the existing Web service standards, the selection of services can not be changed once they are invoked at runtime. Improving QoS by dynamically choosing different Web services to execute is the goal of this method. It is illustrated in Figure 3.4.
In service relocation or replication, the requestor always binds to the same service. These techniques improve the QoS by changing the internal implementation of the service. However, the method of dynamic service invocation moves the binding from one service to another one. Therefore an important requirement of this method is that the new service should have the same functional signature as the original one.

[Yu 2004] proposes an architecture which extends Web service architecture to support dynamic service invocation. They introduce a proxy between the service requestor and the Web services. The proxy has a few functionalities: it monitors the status of the current running service. When the status changes, for example, the current service is temporary unavailable, the proxy retrieves a list of candidate services with the same function from UDDI. A new service is then chosen from them and the proxy starts to dispatch the traffic to it.

QoS adaptation can be achieved by dynamically binding to a new service with better QoS if the current one cannot provide an acceptable QoS. One of the main challenges of this
approach is the performance issue. The migration from one service to another should be fast and reliable. In addition, the service execution can not be stopped during the change.

3.2 QoS-Adaptive Workflows

Since composing Web services is similar to designing a workflow [Aalst 2003], we discuss some existing approaches to support QoS adaptation for workflow in this section.

In Workflow management, flexibility is a workflow's ability to modify its execution in order to meet certain goals. If maintaining QoS is the goal, being flexible can be a way to make the workflow QoS adaptable. In order to understand flexibility, a few concepts need to be explained first. The business process of a workflow is modeled by its type/schema [Petra 1999]. It defines the workflow by using workflow specification language at design phase. At the execution phase, workflow instances are instantiated from the workflow type.

A summary of the existing strategies for supporting flexible workflow is given in [Petra 1999]. They summarize two ways to achieve flexibility: by selection, or by adaptation:

1. Flexibility by selection: A number of alternate execution paths are defined in the workflow type. At runtime, the execution path can be altered to one of these pre-defined alternatives. This strategy is called flexibility by selection. It can be further divided into two methods:
   a) Advance Modeling: At design time, every concrete alternate execution path is defined.
b) Late Modeling: At design time, only abstract "black boxes" are defined for the alternate execution paths. The concrete paths are defined at runtime.

2. Flexibility by adaption: Instead of defined at design phase, alternate execution paths are generated on the fly at runtime and inserted into type definition or part of the instances. Flexibility by adaption contains two methods as well:

a) Type adaption: The change does not affect running instances. Only the type definition is modified. Therefore, the future instances will use the new workflow definition.

b) Instance adaption: Opposite to type adaption, instance adaption changes the running instances immediately. This change is only applied to individual instance.

We need to point out that type adaption and instance adaption are not black or white. Some recent researches combine them together to achieve better performance. In these works, instance changes are monitored at run-time. Those appeared with high frequency are collected and a type level change is made to reflect them.

If we compare these two strategies, flexibility by selection can be considered as "anticipated" since the freedom offered to the execution is pre-defined at design time. However, flexibility by adaption gives unanticipated freedom to the execution which only response to the runtime variation. Although flexibility by adaption is more flexible, it is expected to have worse performance due to the overhead introduced at run-time.

As we mentioned at the beginning of this section, flexibility can be used to develop QoS-adaptable workflows. [Klingemann 2000] proposed a framework to achieve this. At
design time, alternate execution paths are inserted into the workflow schema definition. On the other hand, the QoS goal is specified along with other functional specifications of the workflow. At runtime, the possibility of successful fulfilling the QoS goal for each possible execution paths is calculated based on the runtime monitored QoS. The most optimized one is automatically chosen to meet the goal.

Although this approach is more focused on the QoS specification and the optimization algorithm of path selection, the idea of improving QoS by changing the execution path at run-time inspires us to solve the problem in the domain of Web service composition.

### 3.3 QoS Adaptation for Composite Web services

In this section, we review the state-of-the-art of supporting QoS adaptive composite Web services. Since it is an evolving area, there are not many approaches that have been proposed. Plus, none of them provide a comprehensive solution. Based on the strategy used for QoS adaptation, we divide the existing works into 4 groups: 1) dynamic partner Web services re-selection, 2) dynamic modification of composition schema, 3) automated planning, and 4) AOP (Aspect-Oriented Programming) method. These 4 types of approaches will be studied in this section.

#### 3.3.1 Dynamic Partner Web Services Re-selection

Partner Web services are the basic units that form the composition. Based on the current standards, the composition schema is developed at the design phase. During this stage, which partner Web service should be selected for each task has decided. Current way of composition does not offer any flexibility to change a partner Web service at run-time.
However, achieving this kind of flexibility can improve the QoS when, for instance, a partner service is temporarily unavailable or it cannot offer its advertised QoS at run-time. This is what motivates the research of dynamic partner service re-selection. We use Figure 3.5 to show this method.

![Diagram of Dynamic Partner Web service Re-selection]

**Figure 3.5: Dynamic Partner Web service Re-selection**

For each partner Web service, a number of alternate services are selected to be the candidates who are ready to be chosen during the run-time. Candidate services can be found at the design phase when developing the composition, or at run-time. Usually, the candidate service should have the same portType as the original partner service while potentially providing different level of QoS. Finding the candidate services is normally done by a proxy service. During the run-time, when a partner service needs to be re-
selected, the best candidate service is found and swapped with the current one. This task can be also fulfilled by the proxy service.

[Karastoyanova 2004] proposes a mechanism called “find and bind” to support partner service re-selection. They introduce a new activity find_bind for BPEL. Before the invocation of each partner service, a find_bind is executed. Within this activity, the UDDI registry is queried and a list of candidate services is retrieved. Then based on certain policies, the best candidate is chosen and the subsequent invocation activity will bind to it. This approach can provide an optimized service selection for every task. However, the overhead introduced by find_bind is not negligible.

Another approach is proposed in [Canfora 2005]. Unlike the previous work, this approach will not trigger the re-selection unless the overall QoS becomes un-acceptable. When the re-selection is triggered, the execution stops. Which part of the composition has not been executed is determined. Then the best candidate service is chosen for each remaining partner service to maximize the overall QoS. After the re-binding is done, the service execution is restored. This approach is able to provide good flexibility and the overall QoS goal is taken into account. However, stopping the execution for the re-selection is not acceptable in many cases.

[Patel 2003] proposes an architecture called WebQ. Instead of assigning a single partner service to a task, a set of candidate services is assigned. Load balancing is used to distribute traffic to different candidates. When a candidate service is detected providing poor QoS, it will be de-selected and another set of candidates will be chosen to provide
best possible QoS. This work is focused on designing the selection algorithm. It does not provide enough detail for the adaptation procedure.

A middleware approach is introduced in [Zeng 2004]. Similar to [Canfora 2005], they replan the selection of all the partner services which are about to be executed during the run-time under the consideration of overall QoS. However, they also focus only on selection algorithm.

The last work we would like to discuss is TRAP/BPEL which is proposed in [Onyeka 2007]. It is a framework which utilizes the transparent shaping programming model to provide self-healing and self-optimization to BPEL process. They are more interested in the programming detail of proxy implementation for service re-selection.

3.3.2 Dynamic Modification of Composition Schema

Although changing individual partner services provides flexibility for QoS adaptation, sometimes we need to change the composition logic to gain bigger impact on the overall QoS.
The modification of the composition schema can happen at any phase. If it happens at non-execution phase, all the new instances will use the modified schema. A modification that happens at execution phase is shown in Figure 3.6. When the QoS is becoming unacceptable, the modification is triggered. A more optimized schema is designed for the rest of the composition which is normally the un-executed portion right after the current execution point. The new schema which might contains new logic or partner Web services will replace the old one.

[Karastoyanova 2004] introduces a new activity called <evaluate> for BPEL. This activity is designed for 2 purposes: changing the portType of a partner Web service at
run-time, and changing the composition schema at run-time. In order to change the schema dynamically, the basic idea is to use the `<evaluate>` activity to wrap the portion of the schema that is supposed to change. Also, assign a template which is a piece of reusable code to the substitution schema in the `<evaluate>` activity. At runtime, the user has to provide concrete parameters for the template to form a new schema to replace the wrapped portion of `<evaluate>` activity. The need of user intervention may interrupt the service execution which is not expected by the user sometimes. Also their approach requires extending the current BPEL standards.

[Yu 2005] also proposes an approach. In this work, the designer specifies alternate execution paths that can replace part of or all the composition. A composition manager then find out all the possible execution plans based on user’s input prior to the execution. At runtime, when a service encounters problems, the execution engine select the best backup path from the stored execution plan and switch to it for the rest of the process. Although this work enables the composite Web service to change its schema on the fly, the change is triggered only by the error of a partner service.

3.3.3 Automated Planning

Automated planning is a branch of artificial intelligence. The main concern is about generating action sequence to meet certain goals. Given its similarity with Web service composition, some researchers have tried to solve the composition issue by using automated planning tools.
An example is the approach that is proposed in [Vukovic 2004]. They use a planner tool called SHOP2 to change the composition logic when the monitored context environment changes. SHOP2 is a HTN (Hierarchical Task Network) based planner. Its main feature is implementing an abstract task by decomposing it and forming an execution plan. The context and composition goal are fed into SHOP2. It generates a SHOP2 plan which is then transformed into a BPEL schema. The proposed architecture contains a monitor which constantly monitors the context. When the context changes, a new SHOP2 plan will be generated and transformed into another BPEL schema. Although their work is not designed for adapting QoS change, the core concept of how to solve the adaptation issue is similar.

Changing the composition logic through planner is an interesting idea. However, there are still a lot of challenges to be overcome such as how to fully map the Web service description to the domain of planning.

3.3.4 AOP Method

AOP is a programming paradigm which aims at separating crosscutting concerns with other functionalities. There are three key concepts in the AOP model: join point, pointcut and advice. They are the basic units to define an aspect.

1. Join points are points in the execution of a program. For example, join points in object-oriented programs can include method calls, constructor calls, field read/write, etc.
2. In order to modularize crosscutting concerns, pointcut is introduced as a set of related join points.

3. An advice specifies certain codes that run at a join point. It can be executed before, after, or around a join point. The advice specifies when and what behavior must be executed at the selected join points.

Since an aspect can be virtually anything, a number of existing approaches [Charfi 2004] [Courbis 2004] [Verheecke 2004] use AOP to develop QoS-adaptive composite Web services. Generally, these approaches define new composition logic as aspects and insert them into the composition definition. If the composition schema needs to be modified at run-time for adapting QoS change, the execution engine can just activate / de-activate the appropriate aspects. The advantage of AOP is that advices can be executed before, after or around a given point. It is therefore possible to add, delete, or replace activities in a composition dynamically.

Using AOP to enable the dynamic change of composition logic has become an active topic although AOP itself is immature and lack of tool support. These approaches normally require modification to the current composition execution engine.

3.4 A Broker-based Architecture of QoS Management for Web Services

In this section we discuss an approach of Web service QoS management proposed by M. A. Serhani et al. [Serhani 2005] [Serhani 2006]. The reason we discuss it in a separate
section is that their idea of using QoS broker to do the QoS monitoring and adaptation has been adopted by our research. Their architecture is illustrated in Figure 3.7.

![Diagram of Broker-based Architecture for QoS-enabled Web services](image)

**Figure 3.7: Broker-based Architecture for QoS-enabled Web services**

Different from the standard Web service architecture, they introduce a QoS broker and replace the traditional UDDI registry with a QoS-enabled registry called UDDIe [Ali 2003]. UDDIe allows service providers to publish their services with non-functional specifications. It enables that a service is selected based on QoS constraints. The key component is their architecture is the QoS broker. The broker is responsible for QoS provisioning and management for Web services. It is a third-party Web service that can be found through UDDI.

When a service provider publishes its Web service to UDDIe, it needs to receive a certification from the QoS broker to prove the authenticity of the service's claimed QoS. If a service requestor look up a service through UDDIe, it can use the result of the certification to ensure the trustworthy of the service's QoS. When the requestor chooses
the service, the QoS broker initiates a QoS negotiation between the requestor and the provider. Once both of them reach an agreement of the QoS level, the negotiation is done and the agreement is stored into the broker's database. The requestor can then bind to the service. During the execution, the broker is responsible for monitoring the run-time QoS. If the QoS violates the agreement, a QoS adaptation is initiated by the broker until the QoS becomes acceptable again. If the adaptation fails, a re-negotiation will be triggered so that a new agreement can be reached.

This architecture is reported in [Serhani 2005] which inspires us to use a similar broker in our architecture to solve QoS issues. Their work has focused on basic Web services, i.e. Web services which do not result from a composition. We adapt the concept of QoS broker and propose a new design to support composite Web services. Another architecture, CompQoS, introduced in [Serhani 2006] supports composite Web services. However, it is more focused on QoS management and monitoring, while we focus on QoS adaptation.

3.5 Summary

In this chapter we reviewed the state-of-the-art of QoS adaptation for Web services. We first gave a brief review of the research works on QoS adaptation. Then we studied the approaches for supporting QoS-adaptive Web services. Three different types of solutions were discussed, which include Web service replication, Web service relocation, and dynamic Web service invocation. These solutions are generic for Web services. They do not address the specific requirements of composite Web services.
Since our research focus on composite services, the related works were studied in the
next section. We summarized these approaches into 4 different methods: dynamic partner
Web services re-selection, dynamic modification of composition schema, automated
planning, and AOP method. For each type of method, its advantages and disadvantages
were studied.

The last section discussed a broker-based architecture for QoS management. This work
introduced an idea of solving QoS for Web services by using a third party broker. The
broker allows QoS negotiation, monitoring and adaptation to be integrated into the Web
service architecture. Our approach adopts this idea to solve the issue for composite Web
services.

We mentioned the requirements of supporting QoS adaptation for composite Web
services in Chapter 1. Through reviewing the state-of-the-art, we found that none of the
related work is able to meet all these requirements. From the next chapter, we will
introduce our proposed approach and explain how it solves these requirements.
Chapter 4
An Architecture for QoS Adaptation for Composite Web Services

Since BPEL is considered as the de-facto standard of composition languages, we focus on the Web service composition that is defined by BPEL in our work. The architecture we propose enables automatic QoS monitoring and adaptation by dynamically changing the execution paths of composed Web service when needed. In order to integrate the definition of alternate execution paths into BPEL, we propose a new construct called flexPath for BPEL which will be discussed in the first section. In the second section, we will introduce the overall architecture and its major components. A typical procedure of how QoS monitoring and adaptation works based on our architecture will be shown in the third section.

4.1 flexPath: An Extension for BPEL

Current BPEL standard only supports one execution path. Once the BPEL process is defined at the design phase, there is only one possible path for the process to be executed. In order to provide flexibility into the process execution, we introduce the concept of alternate execution path into process definition which is shown in Figure 4.1.

As we can see in Figure 4.1, the original execution path is a sequential execution of activity W, X, Y, and Z. Then we add one alternate path for activity Y. It is a sequential
execution of activity A and B. In this example, the process now contains 2 possible execution paths: WXYZ, or WXABZ. The changeable portion is Y/AB which is wrapped by a new construct called flexPath. Therefore, a flexPath defines a segment of process where multiple execution paths are defined. Among these paths, one of them is assigned as the default path. The other paths are all backups which can be switched to at run-time.

![Diagram of flexPath concept](image)

**Figure 4.1: Defining Alternate Execution Path in BPEL**

A question might be brought up at this point: current BPEL standard defines construct such as `<switch>` to allow the definition of possible multiple branches that the process make take. Is it doing the same job as flexPath? Similar question has been answered in the domain of traditional workflow management. Conceptually, `<switch>` in BPEL language represents an or-split/join structure. From the programming perspective, flexPath is similar to an or-split/join structure. However, [Klingemann 2000] points out
that from the workflow perspective, they are different, only the chosen path in an or-split/join is considered as a "correct" path and the decision is made based on the evaluation of a predicate and cannot be influenced, while the flexPath has the opposite characteristics.

In the rest of the thesis, the term flexPath refers to the segment in the BPEL process that is wrapped in a flexPath structure.

4.2 The Overall Architecture for QoS-adaptive Composite Web Services

Our proposed architecture is based on the usage of a third party QoS broker. This idea is brought from the work of Serhani et al. as we mentioned in Chapter 3. The QoS broker is responsible for managing the QoS and can be exposed as a Web service. In our architecture, however, the broker is specifically designed to monitor the QoS of a composed Web service and managing the QoS adaptation for it when needed. Figure 4.2 illustrates our proposed architecture.
Figure 4.2: Overall Architecture for QoS-adaptive Composite Web Services

The architecture consists of five main components: Service requestor, BPEL process, partner Web services, BPEL compiler, and QoS broker:

1. Service requestor is the customer that invokes the composite Web service.

2. BPEL process is the composed Web service published by the service provider.

3. Partner Web services are the basic units that form the composition of the BPEL Web service. They can be published by the same service provider who publish the BPEL process, or other service providers.

4. BPEL compiler is a tool for instrumenting the BPEL process. After a BPEL process is designed, it needs to be instrumented to make it adaptation-enabled. Without the instrumentation, the BPEL process will not be able to be managed by the QoS broker.
5. QoS broker is published as a Web service responsible for managing the QoS of BPEL processes. It mainly interacts with the BPEL process during the run-time to monitor its QoS and change its execution path when the QoS is too poor. It also interacts with the service requestor and the partner Web services. As mentioned in [Serhani 2005], each service needs to get a certification from the QoS broker to verify their claimed QoS before they are published in UDDI. Therefore, for each partner Web service, there should be at least 2 pieces of data stored in the broker’s database: its claimed QoS, and its actual QoS based on its past performance statistics. The broker also needs to communicate with the service requestor for tasks like QoS negotiation [Serhani 2005]. After a successful negotiation, the QoS agreement is stored in the broker’s database. It is a key reference for the broker to decide whether the adaptation should be initiated at runtime. The main components of the QoS broker include topology interpreter, QoS monitor, QoS adapter, and QoS database. They will be explained in detail later.

Note that UDDI registry is not included in our architecture. It is because that we do not need it to participate into the task of QoS monitoring and adaptation. It is preferable that the service providers publish their composite Web services into a QoS-enabled registry such as UDDIe. In that case, the broker can directly get the QoS information of each service from the registry.
4.3 Procedure of QoS Adaptation Based on the Proposed Architecture

We introduced the overall architecture and its main components in the previous section. In this section, we describe how the BPEL service adapts to the QoS goal based on this architecture. Figure 4.3 describes how the components interact with each other.

![Figure 4.3: Component Interaction of Proposed Architecture](image)

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1. During the design phase, the BPEL process designer finds all the segments inside the process that can be replaced by alternate execution paths. He defines a flexPath wrapping each segment with all the possible alternate execution paths.

2. Before publishing at the UDDI registry, all the services including partner Web services and the BPEL service itself need to get a certification from the QoS broker. The QoS broker stores the QoS information of these services.

3. The BPEL process is then sent to the BPEL compiler for instrumentation with new activities which interact with the broker. The service provider then use the instrumented BPEL definition files which are considered as adaptation-enabled to deploy on the server.

4. Before the service requestor binds to the BPEL Web service, the broker starts the negotiation between them in terms of QoS. Once an agreement is reached, the QoS contract is stored into the broker’s database.

5. The service requestor binds to the BPEL service.

6. At the execution phase, an instance of the BPEL process is instantiated whenever a request is received from the requestor.

7. As the BPEL process starts to execute, it sends the BPEL definition files to the broker. The broker abstracts the topology from the definitions, and starts the adapter and monitor to manage the QoS of the execution.

8. During the execution, the QoS monitor measures the QoS at certain places in the process. As soon as the QoS is considered as unacceptable, the adapter will trigger the adaptation. It finds out the next flexPath to be executed, and calculates the best execution path among all the alternate paths. The result of path selection is sent to
the BPEL process. The BPEL process switches to the new path according to the notification from the broker.

9. After a successful execution, the broker updates the historical QoS data of each partner Web service by using its QoS results.

4.4 Summary

In this chapter, we discussed our proposed architecture. We introduced our extension to BPEL which is a construct called flexPath to support alternate execution paths in the BPEL definition. Our solution is changing the execution path of the BPEL process during the run-time in order to adapt to QoS degradation.

The overall architecture was discussed in section 2. We use a QoS broker to monitor the QoS and manage the adaptation for the BPEL process. The process is instrumented by a BPEL compiler before deployment so that it is able to be managed by the broker. The main components of the architecture and their roles were studied in this section. In the next section, we studied the interaction among these components. From the next chapter, we will discuss the design of each component in our architecture.
Chapter 5

BPEL Process Instrumentation

As we mentioned in the previous chapters, the BPEL process needs to be instrumented in our architecture. We discuss the procedure of instrumentation in this section. Describing a BPEL process usually contains a number of files. There should be at least a BPEL definition file, a WSDL file, and a file to define the deployment details. In our architecture, we design a BPEL compiler which takes these files as input and automatically modifies them. The content added to these files is responsible for communicating with the broker at run-time to fulfill the task of QoS monitoring and adaptation. Mainly, there are three things that are inserted by the BPEL compiler: partnerLinkType and partnerLink of the broker, probes, and PathSelectors. The design of BPEL compiler will be discussed in the first section. The instrumentation of each type of contents will be discussed in the second section.

5.1 Automatic Instrumentation Using JDOM

The architecture of the BPEL compiler is described in Figure 5.1. All the files that need to be instrumented are written in XML. These XML files are first parsed by an XML parser. Then we use JDOM [JDOM] to model it in JAVA. After the instrumentation is done, new XML files are generated.
In order to instrument the new contents, the BEPL compiler needs to know where to put them. This job is done by using JDOM. JDOM is a JAVA toolkit which maps an XML file into java “Document Object Model”. By using the API provided by JDOM, an XML file can be easily manipulated in JAVA after it is parsed by an XML parser. In JDOM, each XML element is an instance of JAVA class: Element. Each XML attribute is an instance of JAVA class: Attribute. Since the files for instrumentation are all written in XML, all the BPEL activities, WSDL elements, etc. can be handled as JAVA objects.

The procedures of instrumenting different files are similar. For each element in the file, its attributes are examined. The BPEL compiler then determine if new content needs to be inserted prior to or after this element. Since everything is element in JDOM, new contents are inserted as elements too. If an element contains sub-elements, the same procedure is repeated.
5.2 Instrumentation of partnerLinkType and partnerLink for the Broker

partnerLinkType and partnerLink are constructs defined in BPEL standards which describe the relationship between the BPEL process and the partner Web services. A partnerLinkType defines at most 2 partners who form a relationship. The definition includes their roles and their WSDL portType. Usually the partnerLinkType is defined in the WSDL file of the BPEL process. A partnerLink is an instance of a partnerLinkType. In a BPEL file, each partner service should have a partnerLink defined.

When a BPEL programmer designs a process, he is not aware of the existence of the QoS broker. From the BPEL process point of view, the QoS broker is just another partner Web service which can be invoked during the execution. This is why we need to add the definitions of its partnerLinkType and partnerLink. Normally, the partnerLinkType is instrumented into the WSDL file, and the partnerLink is instrumented into the BPEL file. Figure 5.2 and Figure 5.3 give examples of partnerLink and partnerLinkType defined for a QoS broker.

```xml
<partnerLink name="QoSBrokerPLT">
  <partnerRole endpointReference="static">
    <wsa:EndpointReference xmlns:wsa="http://www.openuri.org/">
      <wsa:Address>http://localhost:7001/WebProjectQoSBroker/QoSBroker.jws</wsa:Address>
      <wsa:ServiceName PortName="QoSBrokerSoapPort">s:QoSBroker</wsa:ServiceName>
    </wsa:EndpointReference>
  </partnerRole>
</partnerLink>
```

**Figure 5.2: Example of partnerLink for a QoS Broker**
5.3 Instrumentation of Probes

We define a probe as a group of activities with the main task to invoke QoS broker Web service for the purpose of QoS monitoring. It is instrumented into the BPEL file. During the run-time, the probes are the locations where the monitor measures the QoS. For example, each time the execution of a partner service is completed, the QoS should be measured. Therefore, at least one probe should be inserted prior to and after a partner service invocation. We also wrap each flexPath with 2 probes so that its QoS can be monitored as a whole. An example of instrumenting probes into a BPEL file is shown in Figure 5.4.
Each probe is a sequence of BPEL activities. The brief design of a probe is shown in Figure 5.5. Three actions are executed in a probe. At first, a unique probe ID is generated and assigned to the probe. This ID is used by the QoS broker in order to identify the probe. The probe then invokes the QoS broker Web service. As soon as the broker is invoked, it measures the current QoS and decides if the adaptation should be triggered. This decision is included in the response which is sent back to the probe. It will be used to update a flag called isAdaptationRequired defined in the BPEL process. It is a variable that is instrumented into the BPEL file. This flag indicate whether or not the adaptation should be triggered. Whenever a flexPath is about to be executed, this flag is checked. If it is TRUE, then the BPEL process knows that a better execution path needs to be selected within this flexPath.
Figure 5.5: Design of the Probe

Not all the probes are designed in the same way. For example, the first and the last one have their own tasks. Except doing the aforementioned actions, the first probe in the process needs to send the BPEL definition as a XML string to the broker. It is for the broker to understand the schema of the composition at the beginning of the execution. The last probe needs to collect some extra information such as the statistics of the performance of the execution.

5.4 Instrumentation of pathSelector

We define a pathSelector as a group of activities that are responsible for selecting the execution path of a flexPath. It is always inserted right before a flexPath. Figure 5.6 shows the result of instrumenting probes and pathSelectors into the previous example which is described in Figure 5.4.
As same as the probe, a pathSelector is a sequence of BPEL activities. Its design is shown in Figure 5.7. A unique pathSelector ID is generated and assigned for each pathSelector. Then it checks the flag isAdaptationRequired. If it is FALSE, the pathSelector will do nothing and the default execution path will be selected for the following flexPath. If the flag is TRUE, it will ask the QoS broker which path to choose. Upon receiving the request from the pathSelector, the broker determines the best execution path based on the pathSelector’s location and the current QoS.
5.5 Summary

In this chapter, we explained the process of instrumentation which is accomplished by the BPEL compiler. The design of the compiler was discussed in the first section. The instrumentation is done by using JDOM toolkit. We then introduced the concept of probe and pathSelector. They are activities inserted into BPEL file for communicating with QoS monitor and adapter in the broker. We studied the design of them, and where they should be instrumented. We also discussed the instrumentation of partnerLink and partnerLinkType of the broker into BPEL and WSDL files.
Chapter 6

A QoS Broker for Automatic Monitoring and Adaptation

We introduced and discussed automatic instrumentation of BPEL processes in the previous chapter. In this chapter, we will discuss the design of the QoS broker in detail. As we mentioned in Chapter 4, the broker consists of 4 components: topology interpreter, QoS monitor, QoS adapter, and QoS database. We will study the design of each component in this chapter.

6.1 Topology Interpreter

While monitoring a running process, there are two important things that the broker needs to know: 1) what is the schema of this running instance? 2) Where is the current execution point, such as the location of the last probe and the next flexPath? This task is done by the Topology Interpreter.

When the BPEL process starts its execution, the first probe will notify the broker with its BPEL definition. Similar to the instrumentation process, the Topology Interpreter parses this BPEL file by using JDOM. However, the JDOM representation is not able to provide details such as the locations of probes, flexPaths, etc. We therefore designed a tree data structure on top of the JDOM representation to represent the schema.
Before we explain the topology abstraction, we need to understand different patterns in Web service composition. We have discussed the composition patterns in Chapter 2. In a composed Web service, the relationship between basic partner Web services can be sequential, parallel, conditional, or loop [Yu 2005]. [Cardoso 2002] shows that all these patterns can be converted into the sequential one. Therefore, this thesis focuses on BPEL processes containing only sequential composition.

Now let us continue the discussion of designing the data structure that models the BPEL process. In this tree data structure, each node is called a section. Every section is a BPEL activity. The root section represents the BPEL process itself. Not all the BPEL activities are mapped to a section. For example, we ignore the <assign> activity since it is unrelated to the execution path modeling. In our research, the only changeable units in an execution path are invocations to partner Web services. Other activities are ignored during the topology modeling.

There are three types of sections: Partner Web service invocation, sequence, and flexPath. The section whose type is “partner Web service invocation” represents a <invoke> to a single partner Web service. The section whose type is “sequence” represents a <sequence> activity. For structured activities, since we only handle the sequential pattern of the composition, the only structured activity we need to handle in the topology interpreter is <sequence>. The section whose type is “flexPath” represents a <flexPath> activity.

A section can contain sub-sections. Therefore each BPEL activity that is mapped to a section may belong to other sections. If a section represents a basic BPEL activity such as
<invoke>, the section is a “leaf” which means it can not contain any sub-sections. The section that represents a <sequence> may contain sub-sections, each of which represents an activity in the <sequence>. The sub-sections of a <sequence> are called its sequential sub-sections. Figure 6.1 shows an example of modeling a <sequence> activity. When the topology interpreter models a <sequence>, a new sequential sub-section is created for each segment between two adjacent probes.

Figure 6.1: Modeling a <sequence> Activity

For modeling <flexPath>, we define another type of sub-section called parallel sub-section. Each parallel sub-section represents an execution path of the <flexPath>. Note that an execution path can be either a <invoke>, or a <sequence>, or a <flexPath>. Figure 6.2 shows an example of modeling a <flexPath> activity.
To answer the second question, we establish ownerships between a probe and its associated section. Also, the topology interpreter tracks the order of execution among sections. Therefore as long as the broker knows the ID of a probe, it knows the execution point of the BPEL process. Locating flexPath is handled in a similar way.

### 6.2 QoS Monitor

We monitor the QoS of a running process by using the QoS monitor in the broker. Each time a probe is invoked, it will notify the QoS monitor to calculate the current QoS. The scheme used by the calculation depends on the QoS parameters. In this thesis we study one dimensional QoS only and we pick response time as our QoS parameter. The QoS
monitor calculates $t_n - t_i$ as the response time at probe $n$, where $t_i$ is the time when the monitor gets the notification from probe $i$.

Note that the response time we measure at the broker is not the same as the response time the user experiences. This is the limitation when using a 3rd party monitor to measure QoS. However, we also need to know that setting up a monitor at the client side is generally unrealistic.

### 6.3 QoS Adaptor

The QoS Adaptor plays a key role in the broker by executing two main tasks: for each flexPath, it has to decide whether the adaptation needs to be triggered. If the adaptation is necessary, it must find a better execution path in order to improve the degraded QoS.

In order to decide if adaptation is required, the adapter needs to answer a key question: is the current QoS too low? If yes, the adaptation will then be triggered. Let us look at an example: at flexPath$_m$, the adapter retrieves the current response time $T_m$ from the monitor. If the QoS contract is $T_c$, then the condition to trigger the adaptation is $P(T_m + T_f > T_c) > x$, where $0 < x < 100\%$. Here $x$ is the probability threshold that is set by the broker administrator. $T_f$ is the future QoS which is predicted by the broker. This prediction is based on the historical QoS data of each partner Web service. If the broker has no QoS data record for a partner Web service, it will use its claimed QoS. Note that how to predict $T_f$ is another subject, which is out of the scope of this thesis.

After deciding the triggering of adaptation, the next step is to find the best alternate execution path. Let us continue with the aforementioned example. We need to divide $T_f$
into two parts: $T_{f\text{-}fPath}$ and $T_{f\text{-}rest}$, where $T_{f\text{-}fPath}$ is the predicted future response time of the current flexPath, and $T_{f\text{-}rest}$ is the predicted future response time of the rest of the process. Assume there are $N$ different execution paths in this flexPath, and the adapter measures their predicted response time to be $T_{f\text{-}fPath1}$, ..., $T_{f\text{-}fPathN}$. Let $P_n = P(T_m + T_{f\text{-}fPathn} + T_{f\text{-}rest} > T_c)$, where $n = 1 \ldots N$. Then path $k$ will be selected as the best path if $P_k \leq x$, and $P_k$ is the greatest among all $P_n$ which satisfies this condition. If there is more than one path with the same predicted response time, we randomly chose one. If no alternate path is able to meet the requirement, the path with the shortest predicted response time will be selected. The whole procedure is illustrated in Figure 6.3.

![Figure 6.3: Determine the Probability of Violation of Response Time](image)

Figure 6.3: Determine the Probability of Violation of Response Time
Again, we only consider Response time in our research. When multiple QoS parameters are involved, the best execution path should have the best overall QoS. A path with the best QoS in one dimension is not necessary the overall best. For example, a faster response time is normally associated with a higher price.

6.4 Summary

In this chapter, we studied the design of the QoS broker which has 4 major components: topology interpreter, QoS monitor, QoS adapter, and QoS database. We first explained how the topology interpreter extracts the schema of a BPEL process by modeling its BPEL definition as a tree data structure. We explained how the topology interpreter tracks the current execution point by using the tree data structure.

We then studied the QoS monitor and QoS adapter. In our research, they are designed to handle one QoS parameter only: response time. QoS monitor measures the date and time at every probe to calculate the latest response time. QoS adapter uses the current measured response time, the predicted future response time of the un-executed segment of the process, and the QoS contract to determine if the adaptation needs to be initiated. If so, it also determines which execution path is the best on the next flexPath.

We pointed out that the algorithm used in the QoS broker depends highly on the QoS parameters that need to be handled. On the next chapter, we will discuss the implementation of the prototype tool and use a case to study our architecture.
We implemented a prototype tool that includes a BPEL compiler and a QoS broker based on our architecture. We also built a few example BPEL processes and a number of dummy partner Web services to evaluate our proposed architecture. In this chapter we discuss the implementation of the prototype tool. We then use an example to do a case study, and analyze the result of the QoS adaptation.

7.1 Implementation of Prototype Tool

In our prototype tool, the BPEL compiler is written in Java. The broker and dummy Web services are designed and deployed through BEA WebLogic 9.2 [WebLogic]. The BPEL process is designed and deployed by using ActiveBPEL 3.1 [ActiveBPEL]. All the components run on a stand-alone computer which has Intel Pentium 4 3.0GHz CPU, 1GB RAM with Microsoft Windows XP SP2 as operating system.

When designing BPEL processes, we use <switch> activity to simulate flexPath given the similarity between the <switch> activity and the flexPath construct. The <switch> will choose the execution path based on the information retrieved from the corresponding pathSelector.
7.1.1 Implement the BPEL Compiler for Automatic Instrumentation

Three files are required by ActiveBPEL to deploy a BPEL process: a (.bpel) file, a (.wsdl) file, and a (.pdd) file which is a deployment descriptor. The BPEL compiler needs to instrument all these three files. During the instrumentation, we insert the probes, pathSelectors, and broker partnerLinks definition to the (.bpel) file. The partnerLinkType definition for the broker and the importing of the broker WSDL are instrumented in the (.wsdl) file. The endpoint reference for the broker partnerLink and the reference to the broker WSDL are instrumented in the (.pdd) file.

7.1.2 Implement the QoS Broker

In the broker, we implemented the three components and the database. The QoS broker is published as a Web service.

```xml
<s0:portType name="QoSBroker">
  <s0:operation name="handleRegularProbe" parameterOrder="parameters">
    <s0:input message="s1:regularProbeRequest"/>
    <s0:output message="s1:regularProbeResponse"/>
  </s0:operation>
  <s0:operation name="executionPathChoosing" parameterOrder="parameters">
    <s0:input message="s1:executionPathChoosingRequest"/>
    <s0:output message="s1:executionPathChoosingResponse"/>
  </s0:operation>
  <s0:operation name="handleLastProbe" parameterOrder="parameters">
    <s0:input message="s1:lastProbeRequest"/>
    <s0:output message="s1:lastProbeResponse"/>
  </s0:operation>
  <s0:operation name="handleFirstProbe" parameterOrder="parameters">
    <s0:input message="s1:firstProbeRequest"/>
    <s0:output message="s1:firstProbeResponse"/>
  </s0:operation>
</s0:portType>
```

Figure 7.1: Part of WSDL of the QoS Broker
The portType of the QoS broker Web service is defined as in Figure 7.1. In this prototype tool we define 4 operations for the QoS broker:

1. **handleFirstProbe**: this operation handles the invocation from the first probe of a BPEL process.
   a) Input message:
      i. bpelDefinition (type = xs:string)
      ii. probeID (type = xs:int)
   b) Output message:
      i. none
   c) Description: The QoS broker does a few things in this operation. It asks the topology interpreter to model the schema of the process by analyze the BPEL definition which is included in the input message. It also initiates the QoS monitor and adapter to start managing the running instance.

2. **handleRegularProbe**: this operation handles the invocation from a probe which is neither the first nor the last one of a BPEL process.
   a) Input message:
      i. probeID (type = xs:int)
   b) Output message:
      i. currentResponseTimeInSec (type = xs:float)
      ii. adaptationFlag (type = xs:boolean)
   c) Description: In this operation, the QoS monitor measures the current QoS (response time) and send it back through the output message. The QoS adapter asks the topology interpreter for the current execution point by passing the probe
ID from the input message. After knowing which part of the process has been executed and which has not, the adapter determines if the current QoS becomes unacceptable by using the measured QoS from the monitor and the QoS contract stored in the broker’s database. If the answer is yes, the adaptation flag in the output message will be set to TRUE. Otherwise it remains FALSE.

3. **handleLastProbe**: this operation handles the invocation from the last probe of a BPEL process.
   a) Input message:
      i.  probeID (type = xs:int)
   b) Output message:
      i.  finalResponseTimeInSec (type = xs:float)
   c) Description: Upon receiving the invocation from the last probe, the QoS monitor and adapter are notified to stop managing the QoS for the running instance. The final measured QoS (response time) is retrieved from the QoS monitor and sent through the output message.

4. **executionPathChoosing**: this operation handles the invocation from a pathSelector of a BPEL process.
   a) Input message:
      i.  pathSelectorID (type = xs:int)
   b) Output message:
      i.  suggestedExecutionPath (type = xs:int)
   c) Description: In this operation, the QoS adapter first uses the pathSelectorID to determine the current execution point through topology interpreter. It then
predicts the future QoS for each execution path in this flexPath and determines which one is the best to suite the QoS requirement. The result is sent back through the output message.

After describing the operations that is published by the QoS broker, let us discuss the internal implementation. We have explained how the topology interpreter models a BPEL process by using a tree data structure in Chapter 6. The basic unit of this model is called a section which represents a basic BPEL activity that forms the execution path. Figure 7.2 shows the definition of sections in our prototype tool.

```java
public class Section {
    public enum Property { PUREWS, FLEXPATH, OTHER, UNKNOWN }; 
    public Property property;
    public int sectionld;
    public int depth;
    public float historicalExeTime;

    // sequentialParent is only valid when containing more than 1 sequential children
    public Section sequentialParentSection;
    public int noOfSequentialSubSections;
    public Section sequentialPreviousSection;
    public Section sequentialNextSection;

    // The following are data for flexPath
    public Section parallelParentSection;
    public List<Section> parallelChildSections;
    // A flexPath is always structured as “probe + pathSelector + flexPath + ..”,
    // the probeld is the probe at the beginning of a section.
    public int probeld;
    public int flexPathld;
    public int parallelPathld;
}
```

Figure 7.2: Class Definition of Sections in Topology Interpreter

To simplify the QoS prediction in the adapter, we always use the historical QoS data as the future QoS for the partner Web services. Based on the analysis in the previous section,
we also simplify the condition for triggering the adaptation as: \( T_m + T_f \cdot \text{Path} + T_f \cdot \text{rest} > T_c \cdot f \), where \( f \) is a prediction factor with value from 0 to 100%. The reason of introducing this factor is to compensate the system overhead. We will show the impact of the factor in the next section. As for the QoS contract, we do not want to make it too tight or too loose which is rare in reality. Thus, we choose the QoS contract to be equal to the overall historical response time of the BPEL process.

7.2 A Case Study

In order to evaluate our prototype tool, we design a BPEL process which invokes a
number of dummy partner Web services. This process contains a flexPath which defines 3 different execution paths. One of the paths contains another flexPath. The default execution path is “invoking Web service 1 → invoking Web service 21”.

Before deploying the BPEL process, we pass its definition files to the BPEL compiler and the instrumented files are generated. Figure 7.3 shows the instrumented (.bpel) file. Since we are focusing on response time, the dummy Web services in this example are designed to consume a random period of time during execution. The length of the period follows a Gaussian distribution with a random mean.

In the QoS broker, the topology interpreter models the BPEL process as shown in Figure 7.4. This interpretation allows the QoS broker to understand the schema of the process and all the possible execution paths.

Figure 7.4: Modeling the Example BPEL Process in the Topology Interpreter
After deployed the BPEL process, we did a set of tests to evaluate the performance of QoS adaptation. A reasonable QoS contract was chosen for the whole test. Since the condition to determine the needs of adaptation is $T_m + T_{f_{\text{Path}}} + T_{f_{\text{rest}}} > T_c * f$, where $f$ is a prediction factor with value from 0 to 100%. In each round of testing, we chose a different value for $f$ ($f = 100\%, 90\%, 80\% \ldots$) and invoked the BPEL process for a number of times. At the end of each execution, the total response time is calculated by reading the measured value from the last probe. The value is compared with the QoS contract. If it is not greater than the contract, the QoS is well-maintained for this running instance. Otherwise, the QoS is considered as violated during the execution.

Figure 7.5 shows the result of testing the original BPEL process. We can see that without adaptation, the QoS violated the contract frequently.

Figure 7.5: QoS Statistics of the Original BPEL Process
We then instrument the process and test it again with the prediction factor in the broker set to 100%. The result is shown in Figure 7.6. The global QoS improved a bit compared to the original process. However, the contract violation still happens quite frequently.

Figure 7.6: QoS Statistics of the QoS-adaptable BPEL Process with f = 100%

When we set the prediction factor to 90%, the result is shown in Figure 7.7. The global QoS improved more, and so does the possibility of QoS violation. Still, there are about 30% of instances had un-acceptable QoS at the end.
Figure 7.7: QoS Statistics of the QoS-adaptable Process with $f = 90\%$

Figure 7.8: QoS Statistics of the QoS-adaptable Process with $f = 80\%$

Figure 7.8 is the result after we set the prediction factor to 80%. Finally, we can now hardly see QoS contract violations.
By comparing the results above, we can see that our proposed adaptation architecture works as expected when an appropriate prediction factor is chosen. If the factor is too high, the prediction result will be sometimes inaccurate due to the overhead of the instrumentation.

We can conclude from the test that it is critical to use an appropriate algorithm to determine the threshold for adaptation. The algorithm should accurately predict the QoS for non-executed part of the BPEL process. Also it needs to reflect the correct amount of overhead that the QoS broker introduced.

The test also revealed some limitations of our architecture. The QoS is improved by changing the execution path, and the execution paths use different partner Web services and different composition logic to differentiate from each other. When deploying the process, if the partner Web services that can be found for a given task all have similar QoS performance, it is possible that none of the alternate execution paths can offer enough improvement on QoS. On the other hand, the same result might be seen even if the most optimized composition logic is used in alternate execution paths.

7.3 Summary

In this chapter, we looked into a specific case study to evaluate our architecture. We build a test bed that contains a QoS broker, a BPEL compiler, and a BPEL process which invokes a number of dummy partner Web services. We presented the implementation of the QoS broker and the BPEL compiler. We choose response time as a QoS parameter to be handled.
The test has been performed in different configurations of QoS broker. We modified the condition for deciding the adaptation threshold in each configuration. The result shows that the relationship between the adaptation algorithms used in the broker and the performance of the adaptation. We can achieve a very satisfactory result by tuning the configuration of the QoS broker.
Chapter 8
Conclusion

This chapter gives a summary of the research contributions reported in this thesis. Potential future work is also pointed out.

8.1 Summary of Contributions

In this paper we proposed an architecture for enabling dynamic QoS adaptation for composite Web services. Our architecture uses a broker-based scheme where a QoS broker manages the QoS monitoring and adaptation for BPEL processes. Our main contributions are:

1. We introduced a method of generating adaptation-enabled BPEL processes through instrumentation. The instrumentation is done using a BPEL compiler. When the user provides the BPEL definition files to the BPEL compiler, it analyzes the XML schema of these files, and instruments the files. The new contents allow for the BPEL process to communicate with the QoS broker at run-time. The instrumented contents include: partnerLinkType and partnerLink of the broker, probes, and pathSelectors. We implemented a prototype of the BPEL compiler which is able to automatically instrument the BPEL files designed by ActiveBPEL.

2. We proposed a new construct called flexPath for BPEL. This allows the designer to define multiple alternate execution paths in a BPEL process.
3. We built QoS broker's functionalities that are lacking in the related work. The broker in our architecture supports QoS monitoring and adaptation for BPEL process. Our broker consists of three main components:
   a) Topology Interpreter that is responsible for analyzing the schema of the process;
   b) QoS Monitor that monitors the runtime QoS;
   c) QoS Adapter that initiates the adaptation according to the QoS status. The QoS adaptation is achieved by changing the execution path of the BPEL process. The adapter is able to figure out the best execution path for a given portion of the process. Another functionality of the adapter is to determine the current QoS status. It predicts the QoS for the portion of the process that has not been executed yet. The predicted QoS is then used to decide if the possibility of the QoS violation is high enough to trigger the adaptation.

4. We also studied the factors that might impact adaptation performance. In order to evaluate the architecture, we implemented the prototypes of the BPEL compiler and the QoS broker. An example of BPEL process has been used to test the prototypes.

8.2 Future Work

As future work, a few possible directions can be taken to extend our architecture to achieve more comprehensive functionalities and better performance:

1. We can extend the architecture to accommodate multiple QoS parameters handling. This might require mostly the changes on the mechanisms for QoS monitoring, algorithms to measure the QoS, algorithms to predict the QoS, and algorithms to calculate potential QoS violations.
2. A thorough and complete evaluation and analysis of the architecture can be undertaken.

3. We can also consider instrumenting the alternate execution paths on-the-fly by selecting partner Web services dynamically. One of the limitations of our architecture is that the alternate execution paths are defined statically at the design phase. The invocation of the partner Web services which form these paths are therefore defined statically as well. Dynamically binding to partner Web services and using them to form new execution path may be an approach to increase the flexibility of the adaptation.
References


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